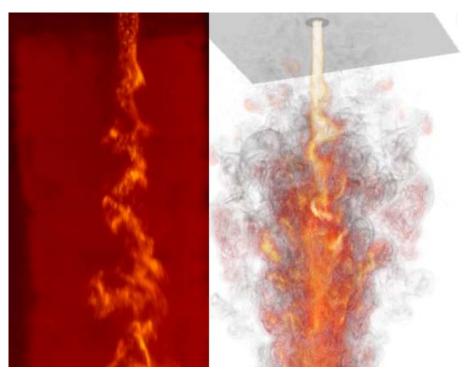


# Simulation of Coal Gasification Using Large Eddy Simulation & Direct Quadrature Method of Moments



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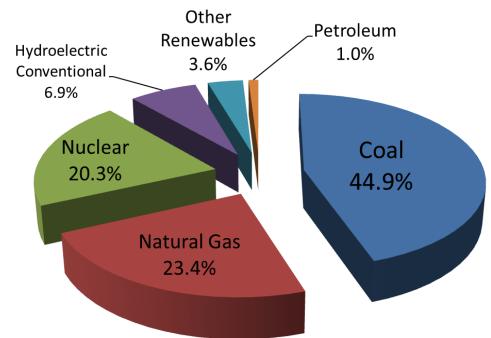
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### Motivation

#### 2009 U.S. Electricity Generation by Source





### Motivation

• U.S. has biggest coal reserves in the world

• 28% of the world's coal!

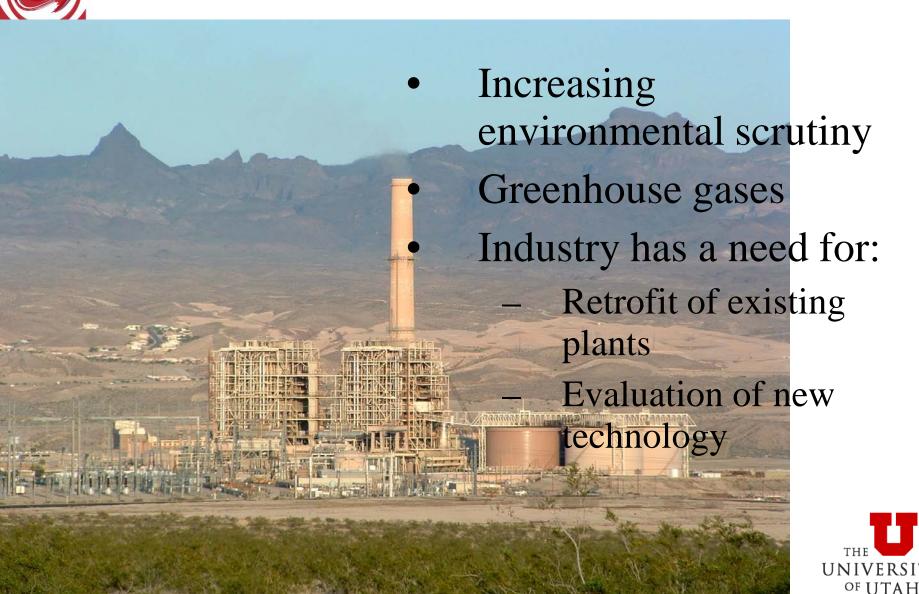
Energy has big implications

- Environmental
- Economic
- Geopolitical
- Social & Health





### Motivation

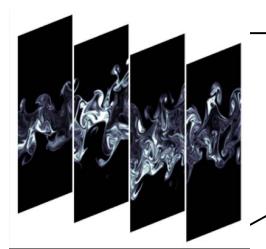




### Simulation

 Simulation - has potential to join experiments and theory as a research methodology

Large-scale simulation tools can tackle difficult multi-physics problems with wide range of length and time scales





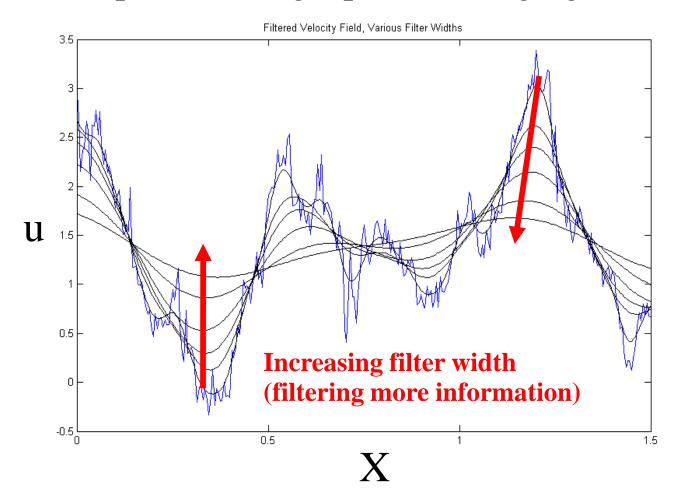
### Outline/Overview

- Large eddy simulation (LES)
- Solid-Phase Models
  - Direct quadrature method of moments (DQMOM)
- Application to coal gasification
- Results & Discussion
- Conclusions



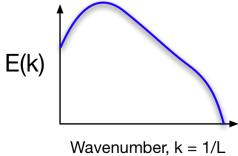


Low-pass filtering: spatial averaging

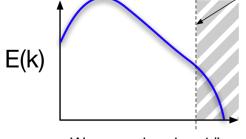




#### (a) **Direct Numerical Simulation (DNS)**

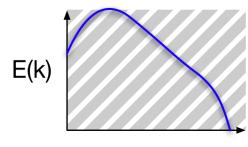


Large Eddy Simulation (LES) (b) Nyquist Limit



Wavenumber, k = 1/L

#### **Reynolds-Averaged Navier Stokes (RANS)** (c)



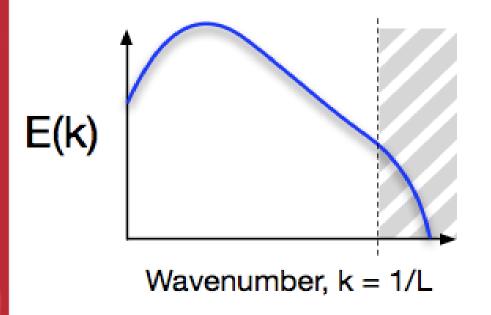
Wavenumber, k = 1/L







#### Scalar/Particle Energy Spectrum



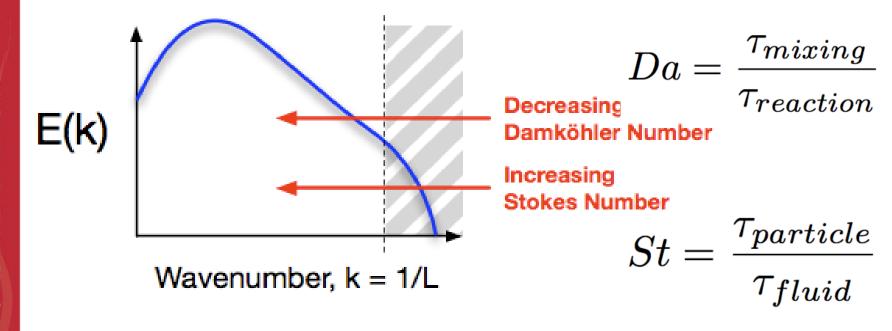
$$Da = \frac{\tau_{mixing}}{\tau_{reaction}}$$

$$St = rac{ au_{particle}}{ au_{fluid}}$$





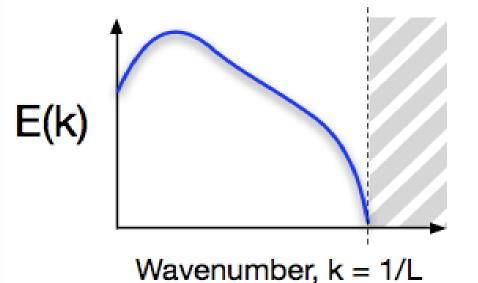
### Scalar/Particle Energy Spectrum







### Scalar/Particle Energy Spectrum



Damköhler Nyquist Limit:

$$\Delta \lesssim Da^{-\frac{1}{2}}Sc^{-\frac{3}{4}}\eta$$

Stokes Nyquist Limit:

$$\begin{cases} \text{if } \tau_{\text{eddy crossover}} < \tau_{\text{eddy lifetime}} \end{cases}$$

$$\Delta \lesssim \left(\frac{\tau_p \nu}{St}\right)^{1/2}$$

$$\Delta \lesssim rac{ au_p^2 g}{St}$$

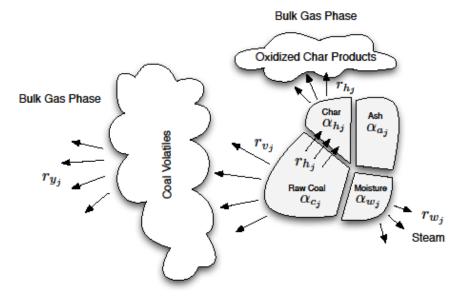


### Solid Phase Models

- Characterization of particles:
- Internal coordinates = particle independent variables

(Denoted  $\xi$ )

- Lagrangian models
- Eulerian models





### Solid Phase Models

• Lagrangian: ODEs

$$\frac{d\mathbf{x}}{dt} = S_{\mathbf{x}} \qquad \frac{d\mathbf{\xi}}{dt} = S_{\mathbf{\xi}}$$

Eulerian: NDF transport equation

$$\frac{\partial f\left(\boldsymbol{\xi};\boldsymbol{x},t\right)}{\partial t} + \frac{\partial}{\partial x_{i}}\left(\langle u_{i}|\boldsymbol{\xi}\rangle f\left(\boldsymbol{\xi};\boldsymbol{x},t\right)\right) + \sum_{j=1}^{N_{\boldsymbol{\xi}}} \frac{\partial}{\partial \xi_{j}}\left(\langle G_{j}|\boldsymbol{\xi}\rangle f\left(\boldsymbol{\xi};\boldsymbol{x},t\right)\right) = h\left(\boldsymbol{\xi};\boldsymbol{x},t\right)$$

$$u_i = \frac{ax_i}{dt}$$

$$G_j = \frac{d\xi_j}{dt}$$





### Solid Phase Models

Lagrangian: ODEs

$$\frac{d\boldsymbol{x}}{dt} = S_{\boldsymbol{x}} \qquad \frac{d\boldsymbol{\xi}}{dt} = S_{\boldsymbol{\xi}}$$

$$\frac{d\boldsymbol{\xi}}{dt} = S_{\boldsymbol{\xi}}$$

Eulerian: MDF transport equation

$$\frac{\partial f(\boldsymbol{\xi}; \boldsymbol{x}, t)}{\partial t} + \frac{\partial}{\partial x_i} \left( \langle u_i | \boldsymbol{\xi} \rangle f(\boldsymbol{\xi}; \boldsymbol{x}, t) \right) + \sum_{j=1}^{N_{\boldsymbol{\xi}}} \frac{\partial}{\partial \xi_j} \left( \langle G_j | \boldsymbol{\xi} \rangle f(\boldsymbol{\xi}; \boldsymbol{x}, t) \right) = h(\boldsymbol{\xi}; \boldsymbol{x}, t)$$

$$u_i = \frac{dx_i}{dt}$$

$$G_j = \frac{d\xi_j}{dt}$$





### Moment Methods

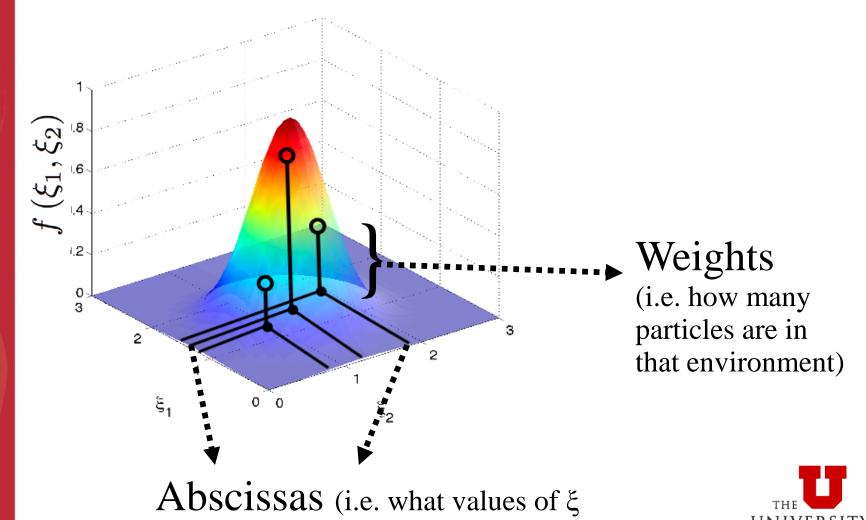
• Moment definition:  $m_k = \int_{-\infty}^{+\infty} \xi^k f(\xi) d\xi$ 

- Multi-fluid method
  - Solids = "fluid" phase
  - Zeroth, first moments
  - What about adding another "fluid" phase?
- Multi-environment models





# Direct Quadrature Method of Moments (DQMOM)



the particles have)

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# Direct Quadrature Method of Moments (DQMOM)

Weight/weighted abscissa transport equations

$$\frac{\partial w_{\alpha}}{\partial t} + \frac{\partial}{\partial x_{i}} \left( \langle u_{i} | \boldsymbol{\xi} \rangle w_{\alpha} \right) = a_{\alpha}$$

$$\frac{\partial s_{j,\alpha}}{\partial t} + \frac{\partial}{\partial x_{i}} \left( \langle u_{i} | \boldsymbol{\xi} \rangle s_{j,\alpha} \right) = b_{j,\alpha}$$

Source terms come from solution to linear system

$$Ax=B$$

 Linear system comes from moment transform of NDF transport equation



# **DQMOM** Implementation

- Numerical issues solving Ax=B
  - Abscissas overlapping
  - Linearly dependent moments
  - Small weights
- Large values of  $G_j = \frac{d\xi_j}{dt}$ For > 2 environments, A always ill-conditioned (condition number  $\sim 10^{16}$ )
- Contamination of one cell means contamination of all cells
- LU solvers, QR solvers, SVD solvers, Lapack solvers, Numerical Recipes solvers.....



# Optimized Moments Approach

- Professor Rodney Fox, "Optimal Moment Sets for Multivariate DQMOM", Ind. Chem. Eng. 2009.
- Replace abscissas in moment transform terms with optimal abscissas (star script)
- Because moment transform is linear,
   linear transform matrix (M\*) can be factored out
   on bot
   Ax = B

$$\mathbf{A} (\mathbf{A}^{\star})^{-1} \mathbf{A}^{\star} \mathbf{x} = \mathbf{B}$$

$$\mathbf{M}^{\star} \mathbf{A}^{\star} \mathbf{x} = \mathbf{M}^{\star} \mathbf{B}^{\star}$$

$$\mathbf{A}^{\star} \mathbf{x} = \mathbf{B}^{\star}.$$





# Implementation of DQMOM in Large Eddy Simulation





### Arches LES Code

- Finite volume
- 2nd Order Runge-Kutta, Strong Stability-Preserving
- Dynamic local similarity SGS model
- DOM Radiation calculation
- Object-Oriented C++

 Part of the Uintah Computationa Framework (UCF)





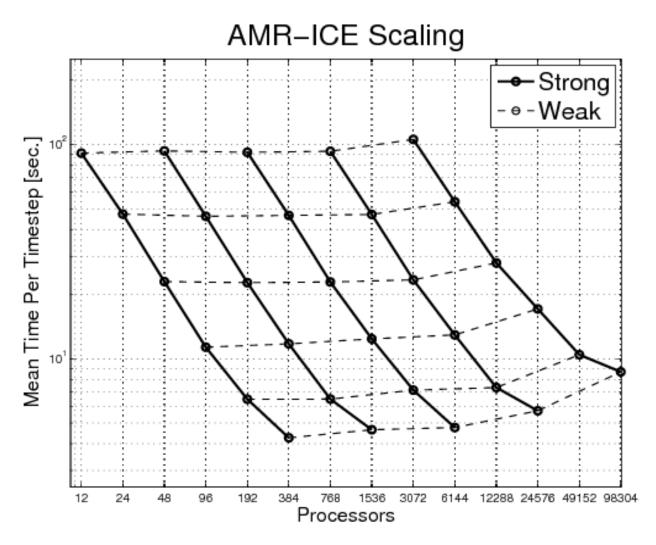
### Uintah Framework

- Component-based
- Structured grid
- Load balancing
- Taskgraph to schedule tasks and manage resources/data
- Provides parallelization to thousands of processors





### Uintah Framework







### Coal Models

- Equilibrium chemistry
- Kobayashi 2-step devolatilization

```
\begin{array}{ll} \text{(raw coal)} & \xrightarrow{k_1} & Y_1 \text{ (volatiles)} + (1 - Y_1) \text{ (char)} \\ \text{(raw coal)} & \xrightarrow{k_2} & Y_2 \text{ (volatiles)} + (1 - Y_2) \text{ (char)} \\ & A_1 &= 3.7 \times 10^5 \, s^{-1} \\ & A_2 &= 1.46 \times 10^{13} \, s^{-1} \\ & E_1 &= -17,600 \, \frac{kcal}{kmol} & \text{Ubhayakar (1976)} \\ & E_2 &= -60,000 \, \frac{kcal}{kmol} \end{array}
```

- Particle heat transfer: radiation, convection
  - DOM, 2 ordinates
  - Nusselt # convection model





### Coal Models

 Fast equilibrium Eulerian particle velocity model (Balachandar 2008)

$$\frac{(u_{particle} - u_{gas})}{u_k} \approx (1 - \beta) \left(\frac{\tau_{particle}}{\tau_k}\right)^{1/2}$$

$$eta = rac{3}{2
ho_p} + 1$$

 $\beta = 3$  Buoyant particles (bubbles)

$$\beta = 0$$
 Heavy particles



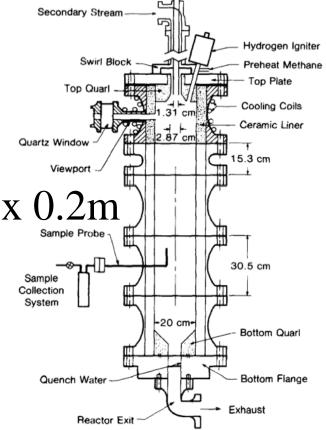


Soelburg et al. 1984, "Entrained Flow Gasification of Coal 1: Evaluation of Mixing and Reaction Processes"

Simulation: No walls

• Domain: 0.7m x 0.2m x 0.2m

• 350 x 100 x 100 (resolution of 2 mm)

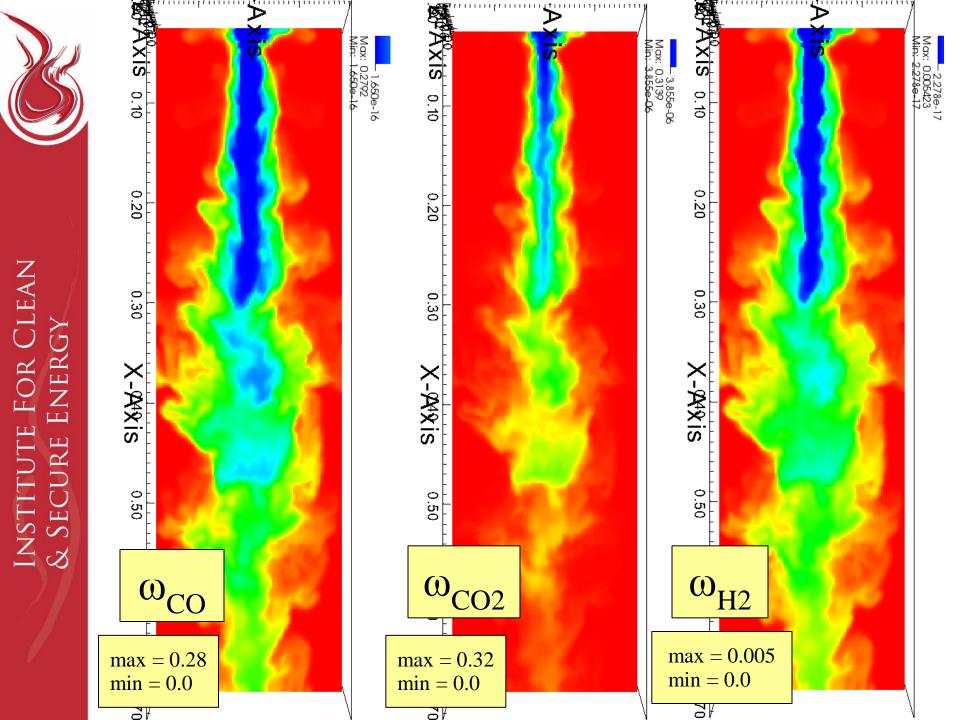




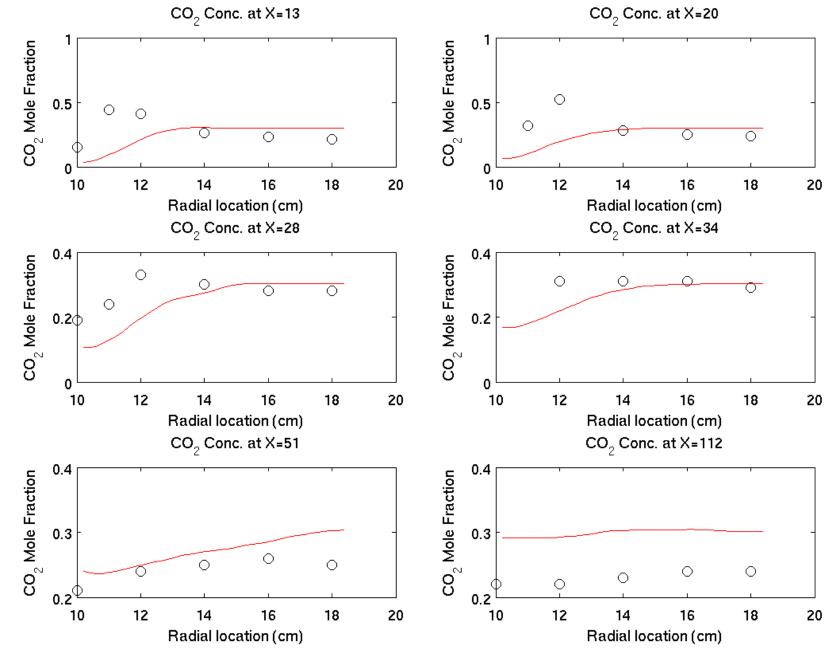


# DQMOM + LES Coal Gasification Results

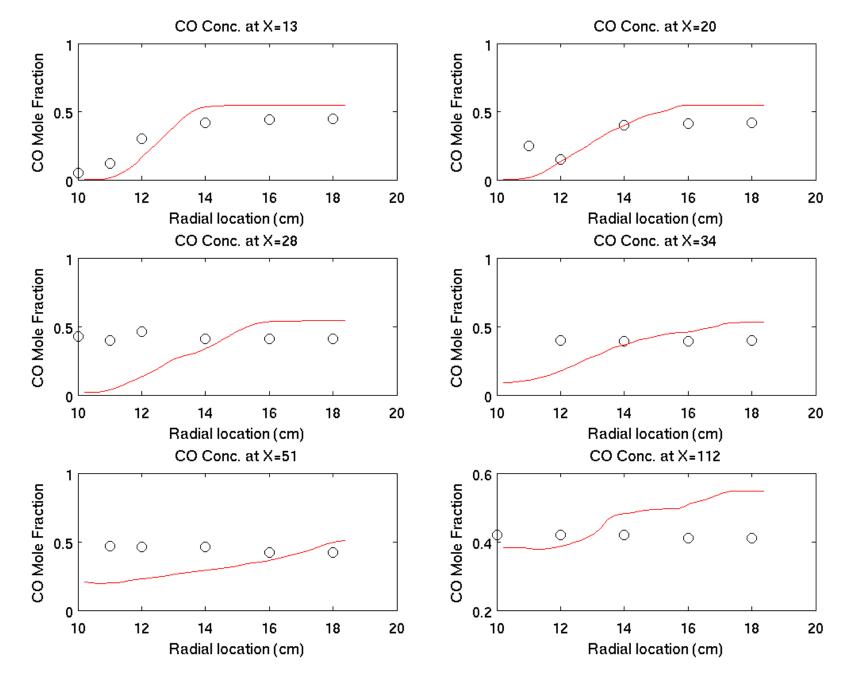




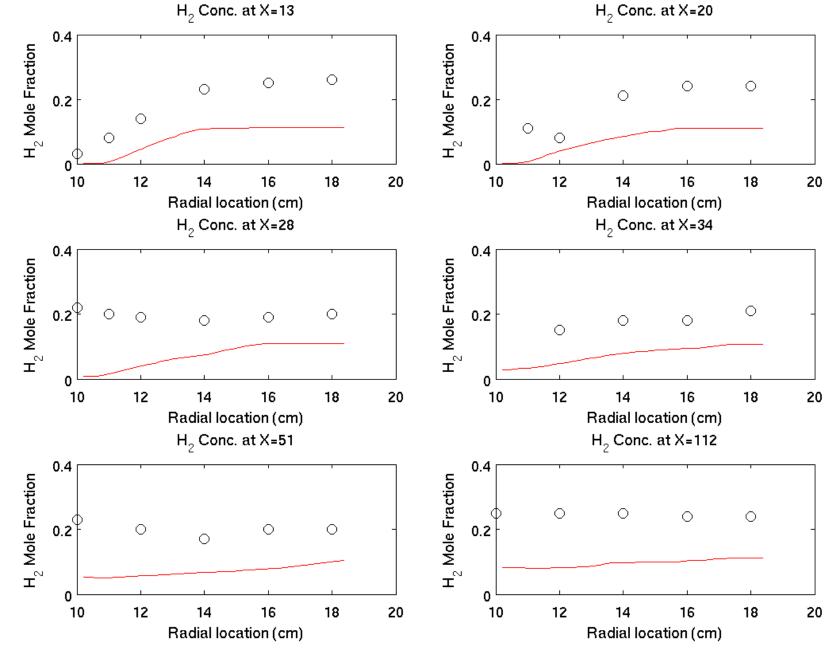


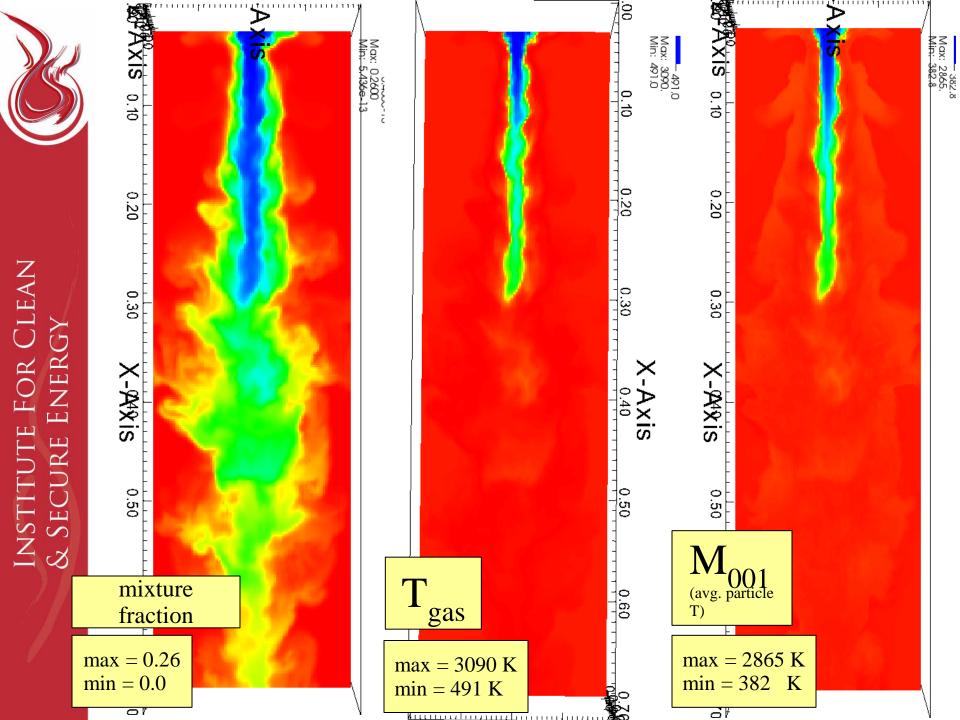


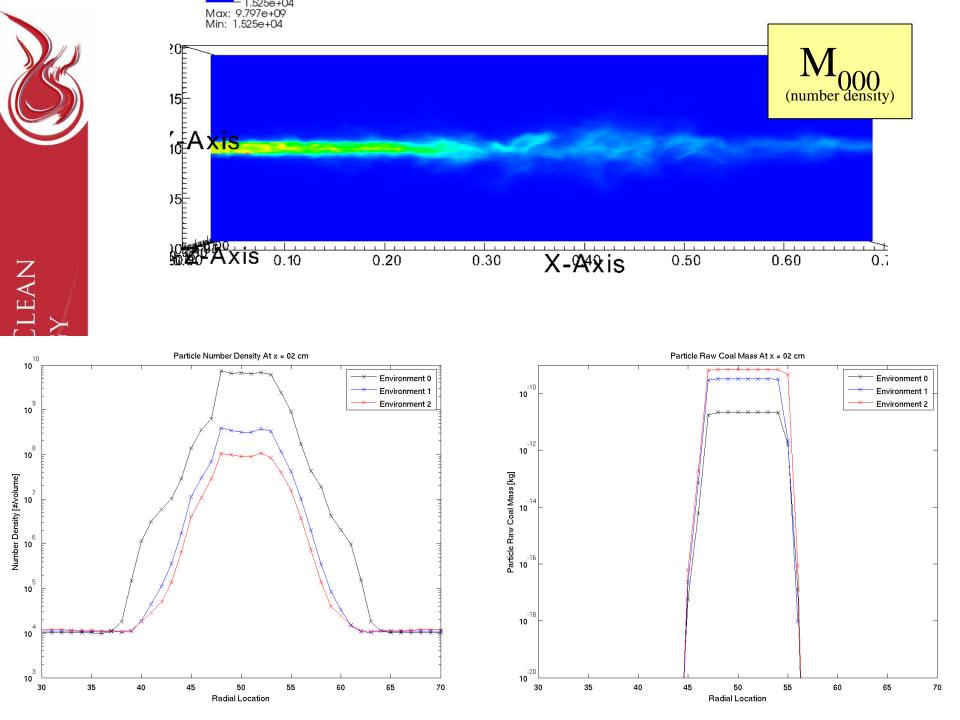


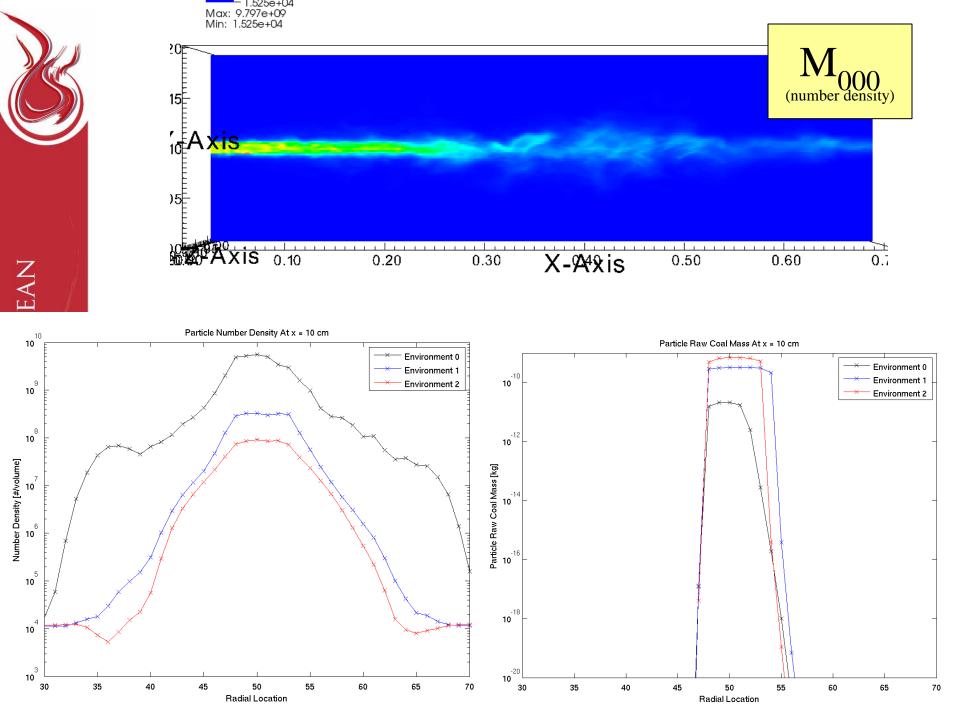


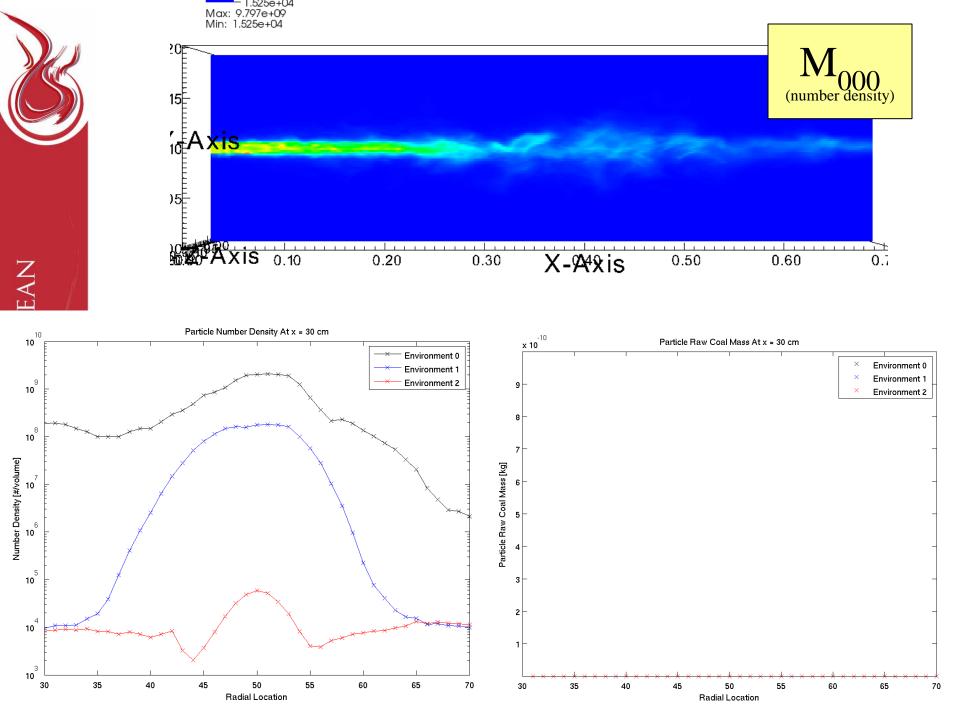










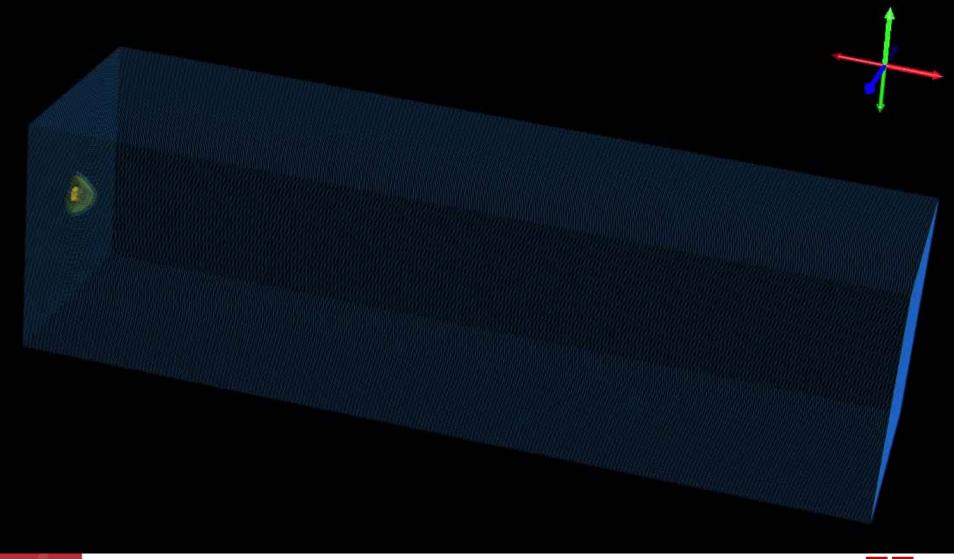


### Volume-Rendering: CO Concentration



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### Volume-Rendering: Mean Particle Size







## Summary of Results

- Not focusing on how well the simulation reproduced the data
- Demonstrating a procedure for implementation of DQMOM in a massively parallel large-eddy simulation code
- What we've implemented, and why we're excited about it
- Gasification physics lots of experience, existing numerical techniques
- 1DCOG, PCGC2/PCGC3, Glacier, Banff





### Where To Go From Here?

- Improving coal gasification physics
- Improving particle physics
- Increase number of internal coordinates
- Begin formal validation procedure





### Professor Philip Smith, University of Utah

Professor Jeremy Thornock, University of Utah

> Professor Rodney Fox, Iowa State University

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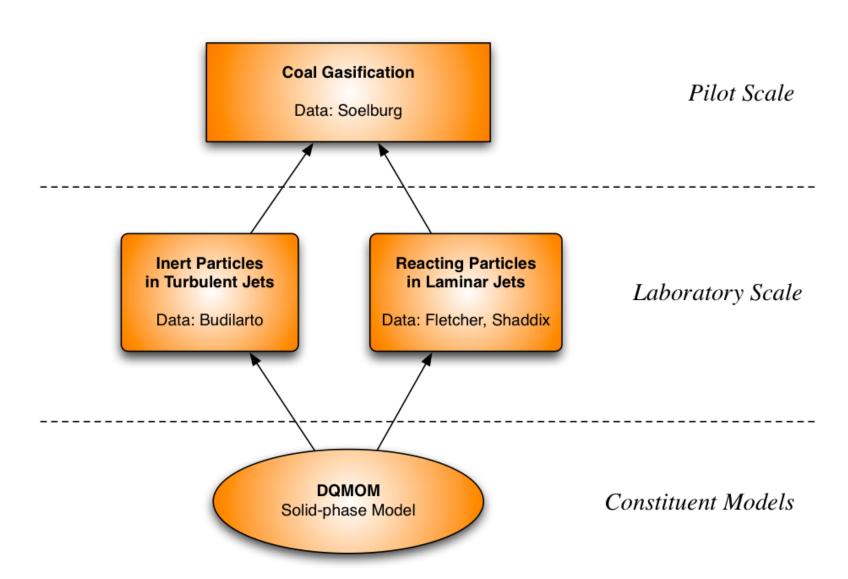
# Questions?







## Validation Roadmap:





### Matrix Expressions

$$\mathbf{A_1} = \left(1 - \sum_{m=1}^{N_\xi} k_m\right) \prod_{n=1}^{N_\xi} \langle \xi_n \rangle_{\alpha}^{k_n}$$

$$\mathbf{A_{j+1}} = (k_j) \left( \langle \xi_j \rangle_{\alpha}^{k_j - 1} \right) \left( \prod_{n \neq j, n = 1}^{N_{\xi}} \langle \xi_n \rangle_{\alpha}^{k_n} \right)$$

$$\mathbf{S} = -\sum_{n=1}^{N_{\xi}} \left[ \sum_{\alpha=1}^{N} w_{\alpha} \left( -k_{n} \langle \xi_{n} \rangle_{\alpha}^{k_{n}-1} \right) \left( \prod_{m \neq n, m=1}^{N_{\xi}} \langle \xi_{m} \rangle_{\alpha}^{k_{m}} \right) \left( G_{n} \left( \langle \xi_{n} \rangle_{\alpha} \right) \right) \right]$$





### Moment Definitions

$$m_k \approx \frac{\displaystyle\sum_{\alpha=1}^N w_\alpha \left\langle \xi \right\rangle_\alpha^k}{\displaystyle\sum_{\alpha=1}^N w_\alpha}$$

$$m_{\boldsymbol{k}} \bowtie \frac{\sum_{\alpha=1}^{N} \left\{ w_{\alpha} \left( \prod_{j=1}^{N_{\xi}} \left\langle \xi_{j} \right\rangle_{\alpha}^{k_{j}} \right) \right\}}{\sum_{\alpha=1}^{N} w_{\alpha}}$$

