

# Continuum and parcel-based approaches to dense granular rheology: model development and applications

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Princeton University



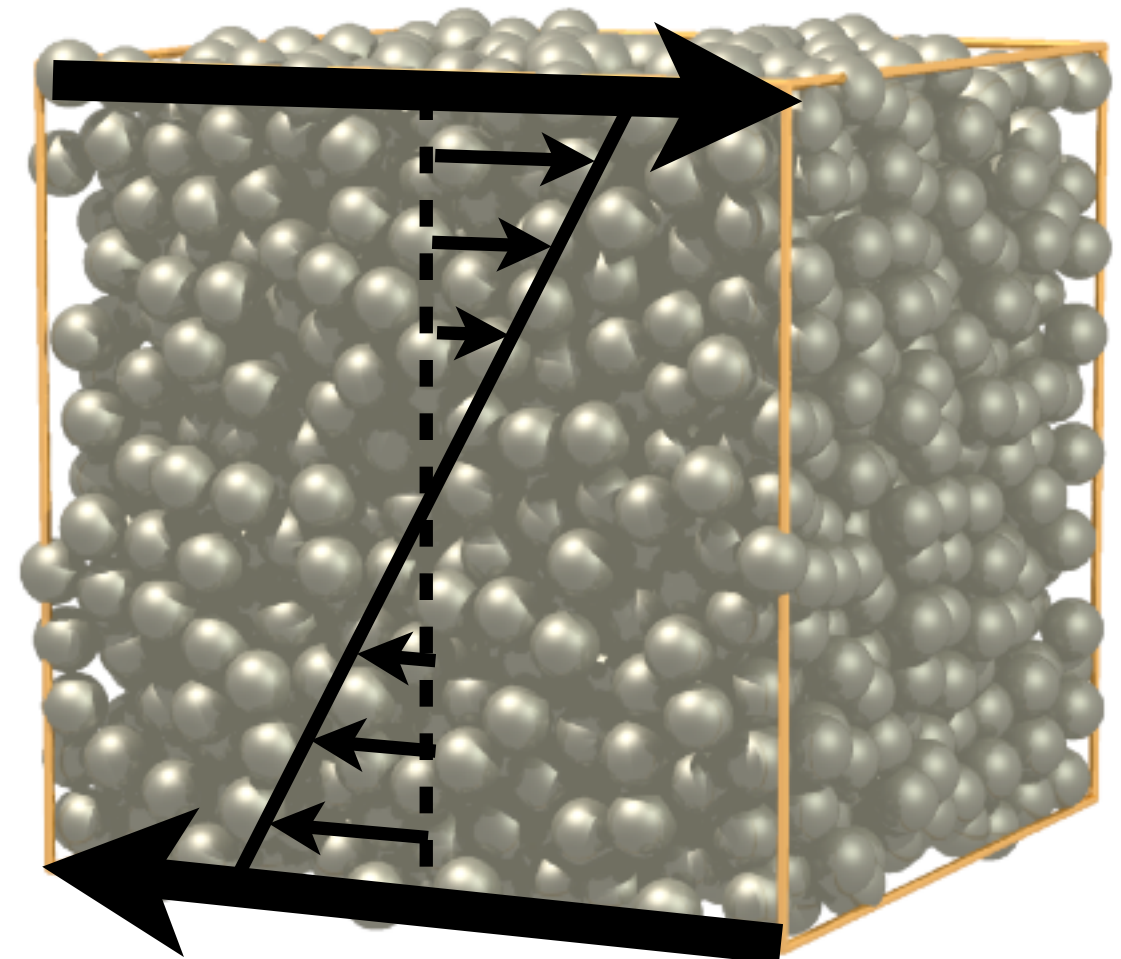
Tuesday, August 16, 2011



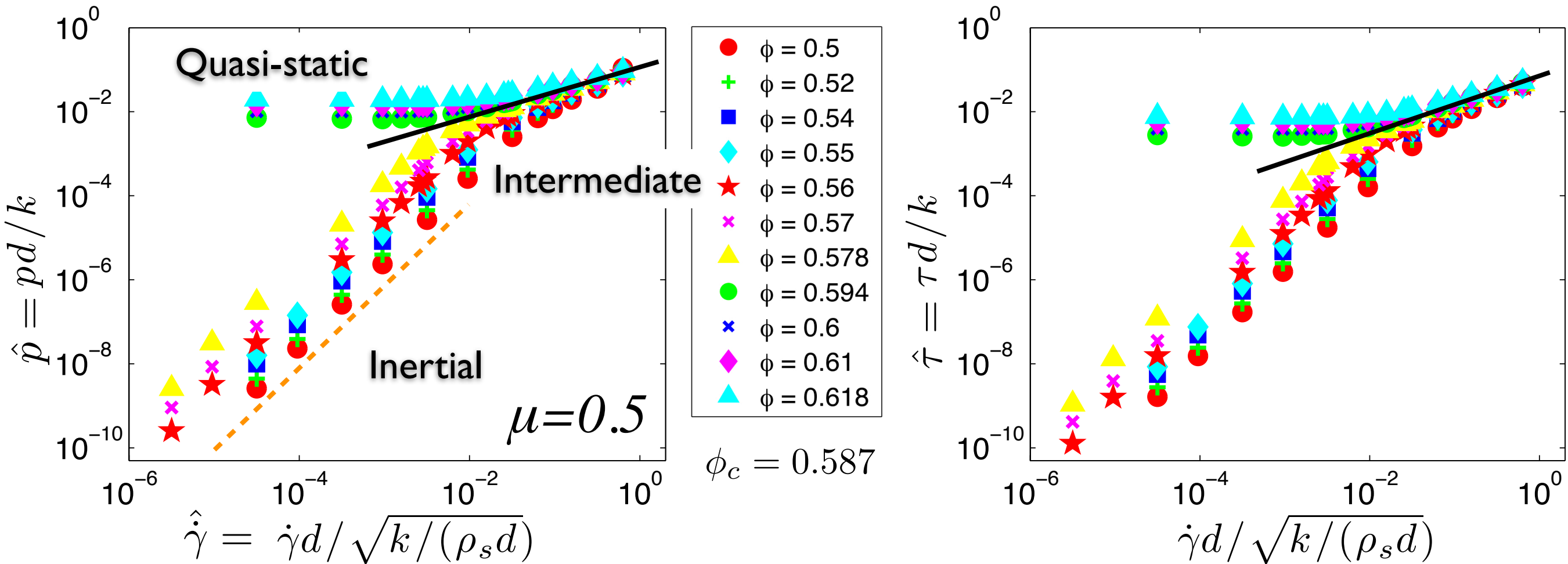
# Discrete element method



- Simulate particle dynamics of homogeneous assemblies under simple shear using discrete element method (DEM).
  - ▶ Linear spring-dashpot with frictional slider.
  - ▶ 3D periodic domain without gravity
  - ▶ Lees-Edwards boundary conditions
- Extract stress and structural information by averaging.



# Flow map

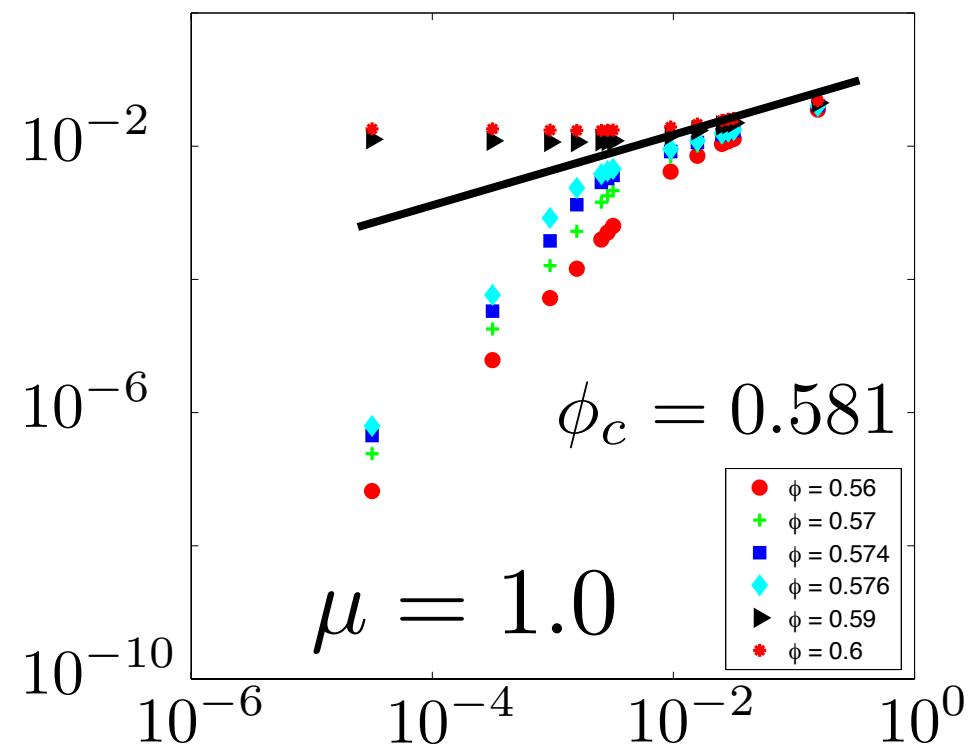
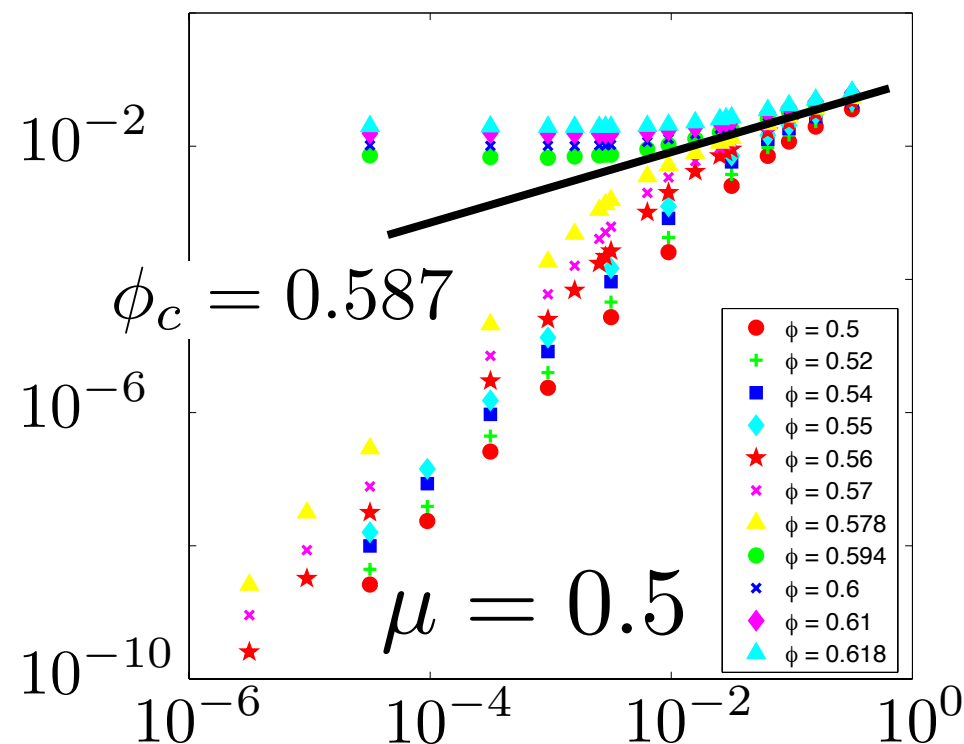
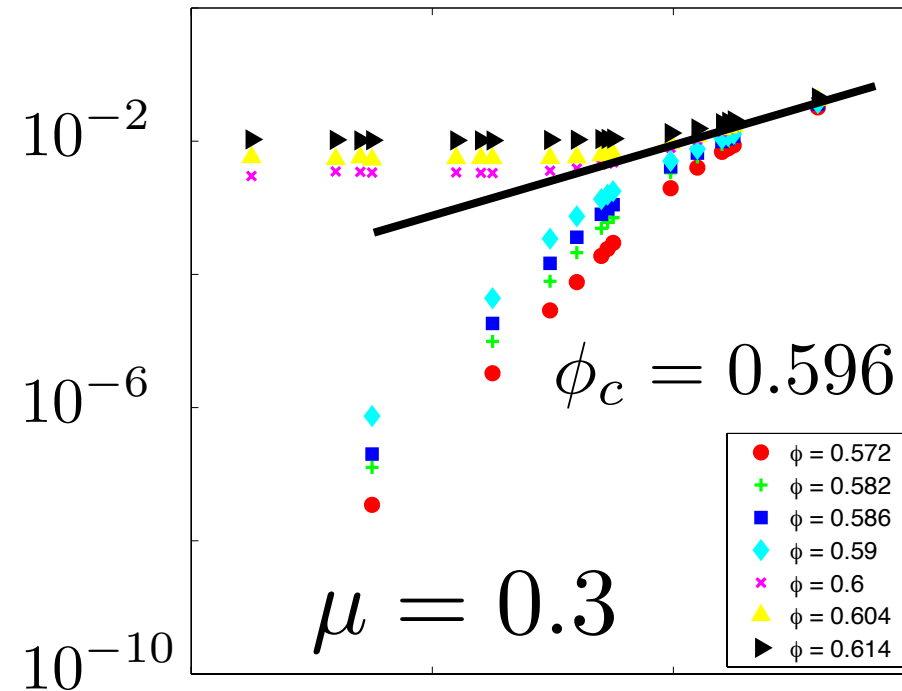
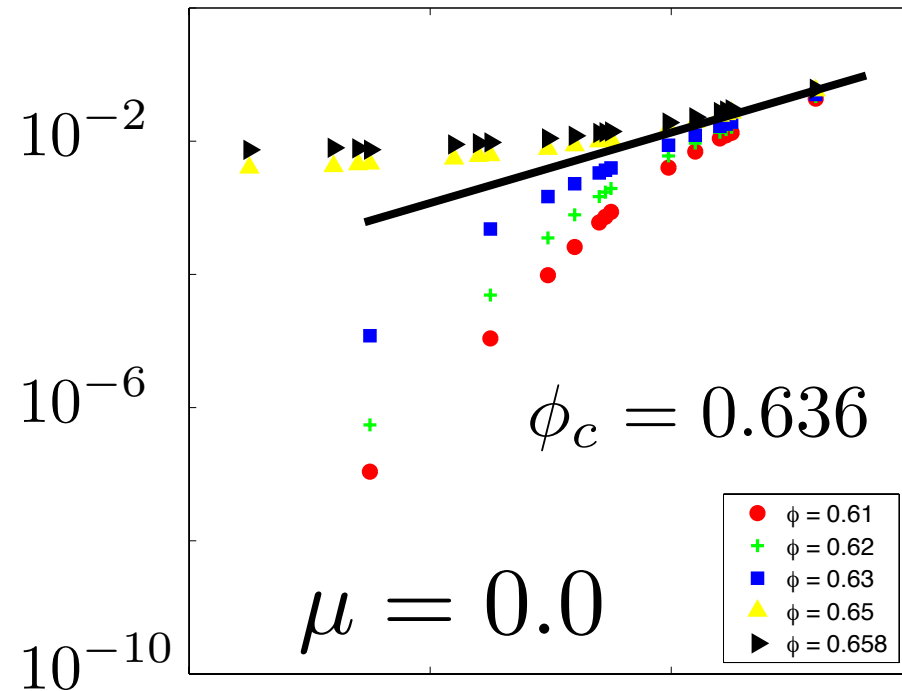


- Flow curve at a critical volume fraction  $\phi_c$ ,  $pd/k = \alpha \hat{\gamma}^m$  distinguishes flow regimes: quasi-static, inertial, and intermediate.
- Quasi-static and inertial bands merge smoothly towards the critical scaling at high shear rates.

# Effect of $\mu$ on rate dependence of pressure



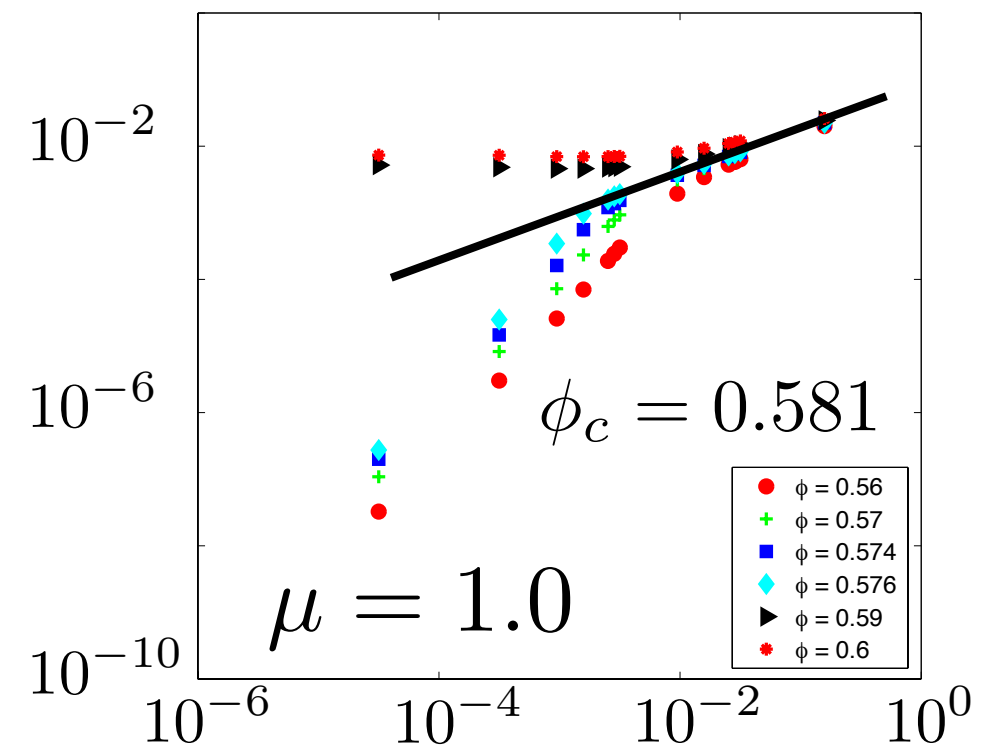
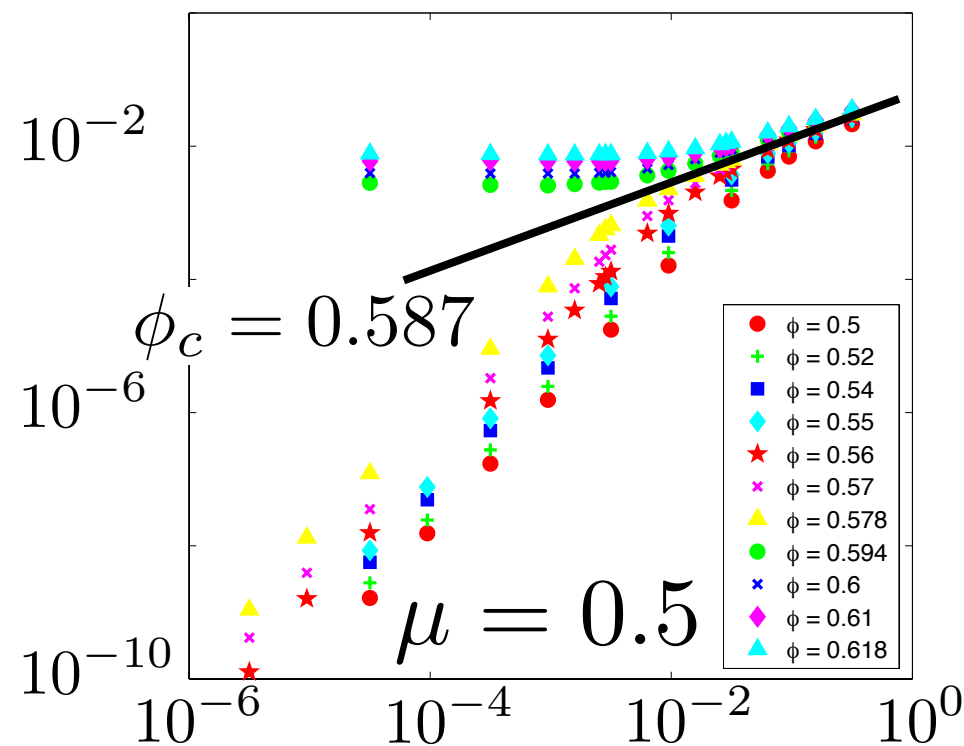
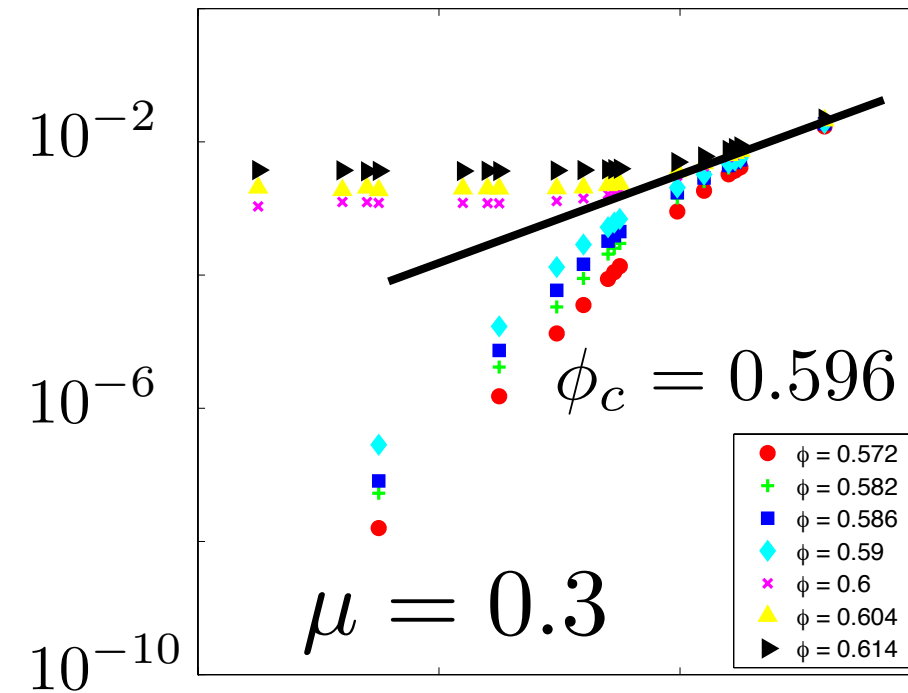
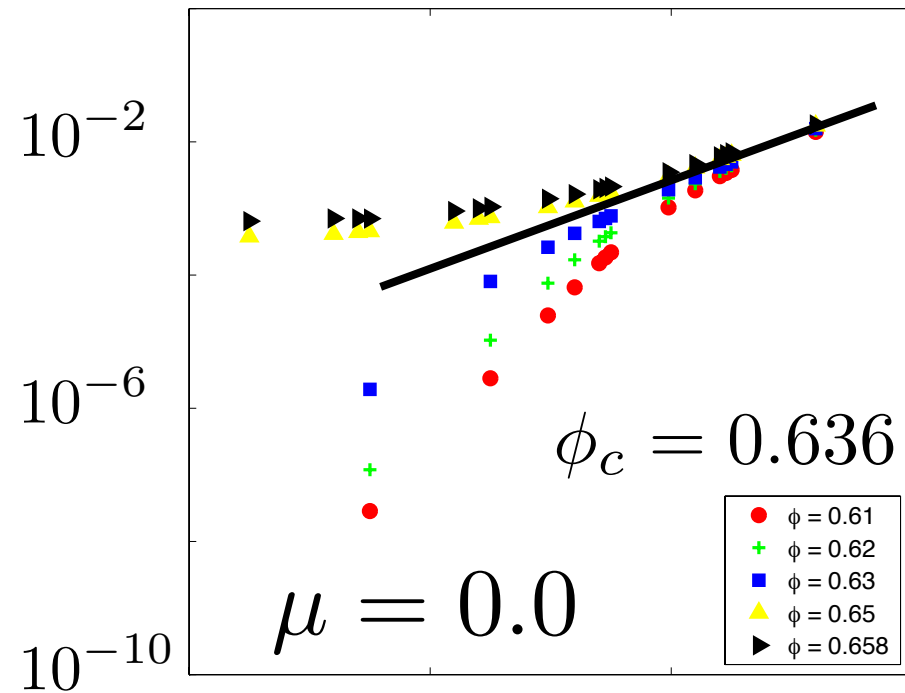
$\hat{p}$  vs.  $\hat{\gamma}$



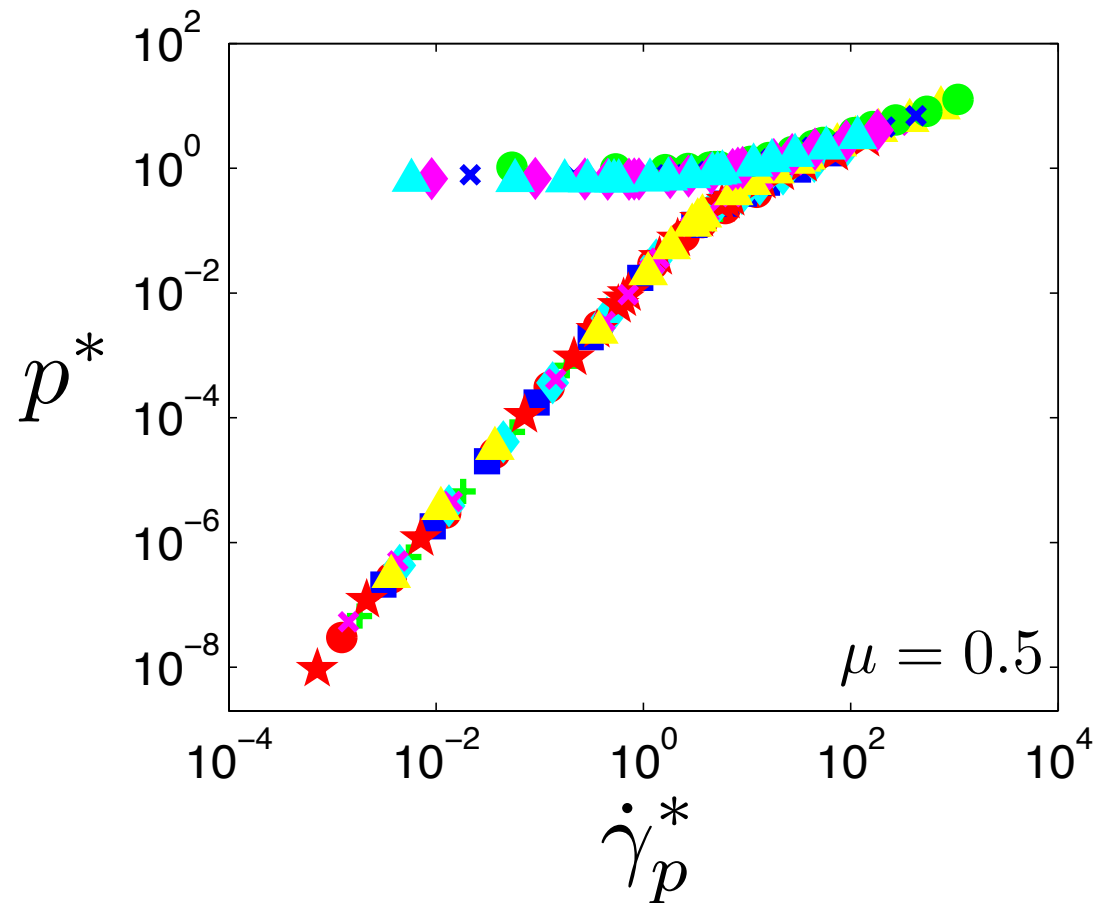
# Effect of $\mu$ on rate dependence of shear stress



$\hat{\tau}$  vs.  $\hat{\gamma}$

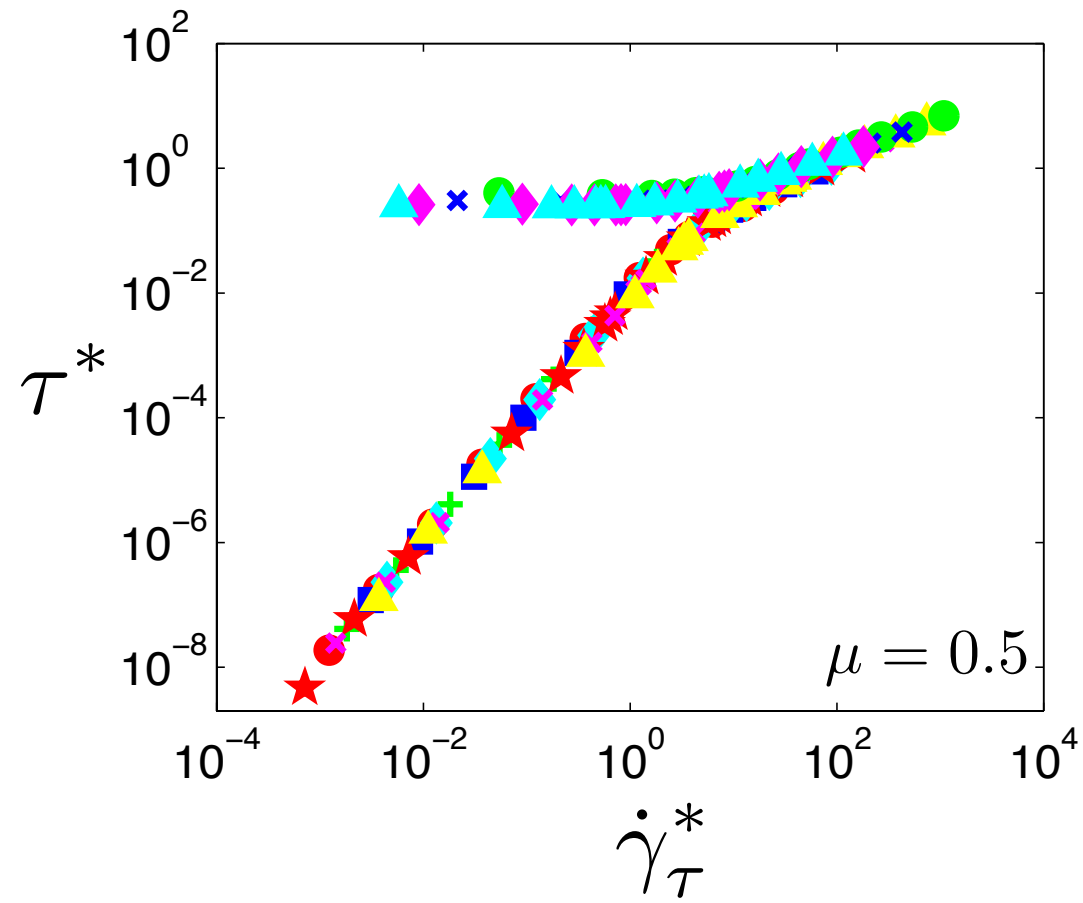


# Stress scalings for frictional particles



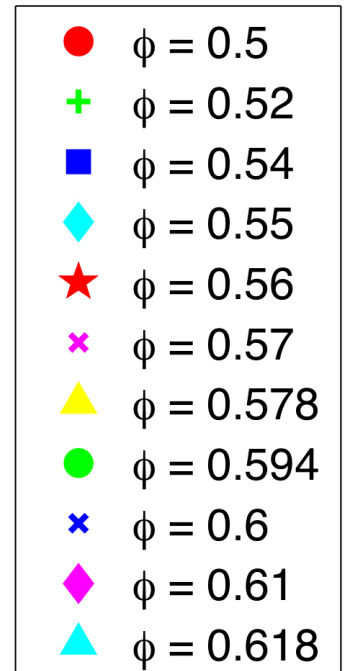
$$p^* = \hat{p}/|\phi - \phi_c|^{a_1}$$

$$\dot{\gamma}_p^* = \hat{\dot{\gamma}}/|\phi - \phi_c|^{b_1}$$



$$\tau^* = \hat{\tau}/|\phi - \phi_c|^{a_2}$$

$$\dot{\gamma}_\tau^* = \hat{\dot{\gamma}}/|\phi - \phi_c|^{b_2}$$



- Quasi-static regime data

$$\implies a_1 = a_2 = 1$$

- Inertial regime data

$$\implies \begin{aligned} b_1 &= 1.5 \\ b_2 &= 1.4 \end{aligned}$$

# Proposed model: regime asymptotes



- Stresses in each regime asymptote can be written as a power-law functions of shear rate:

$$\frac{p_i}{|\phi - \phi_c|} = \alpha_i \left( \frac{\dot{\gamma}}{|\phi - \phi_c|^{1.5}} \right)^m$$

$$\frac{\tau_i}{|\phi - \phi_c|} = \beta_i \left( \frac{\dot{\gamma}}{|\phi - \phi_c|^{1.4}} \right)^n$$

- Quasi-static:  $m = n = 0$
- Inertial:  $m = n = 2$
- Intermediate:  $m = 2/3$   
 $n = 5/7$

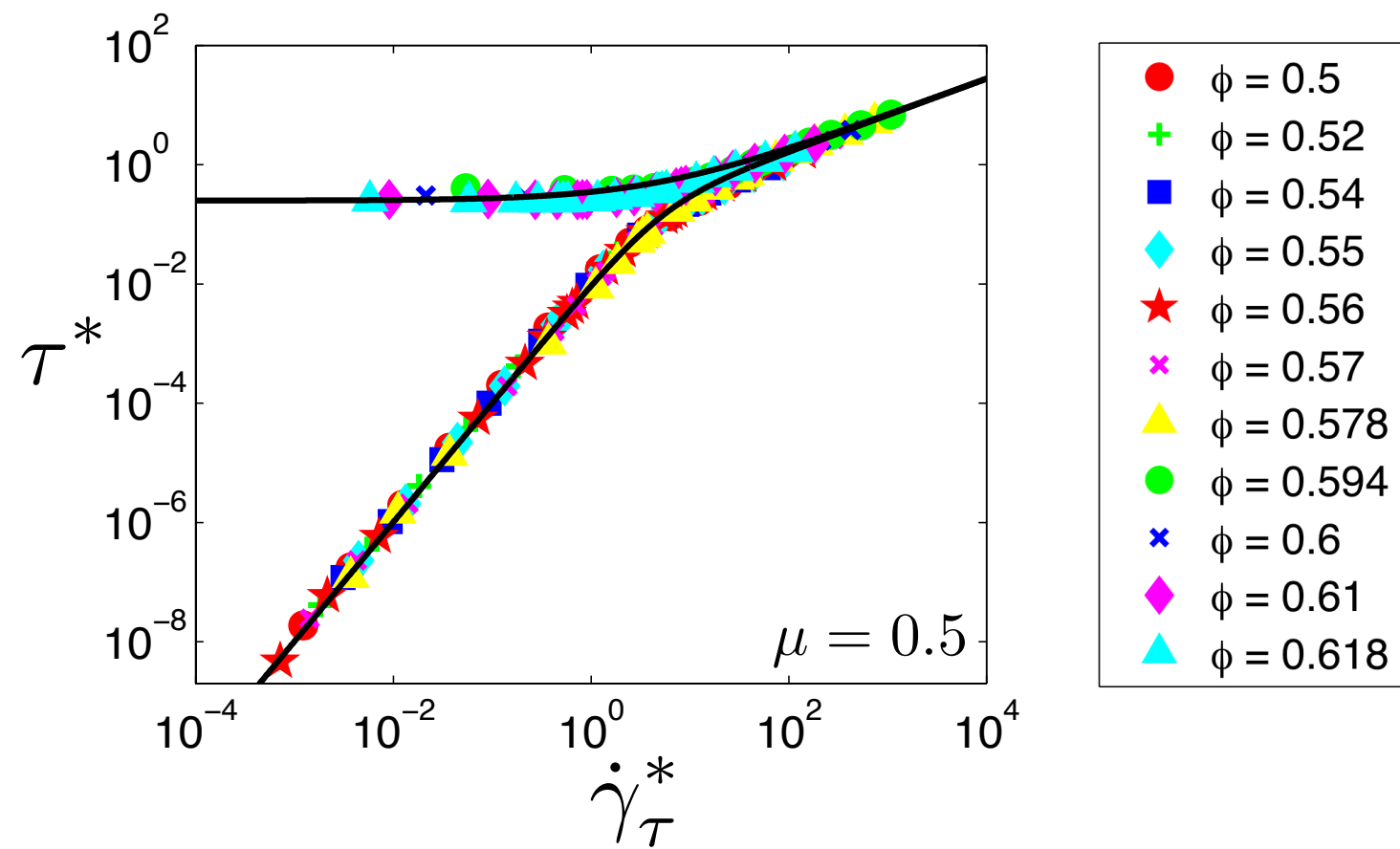
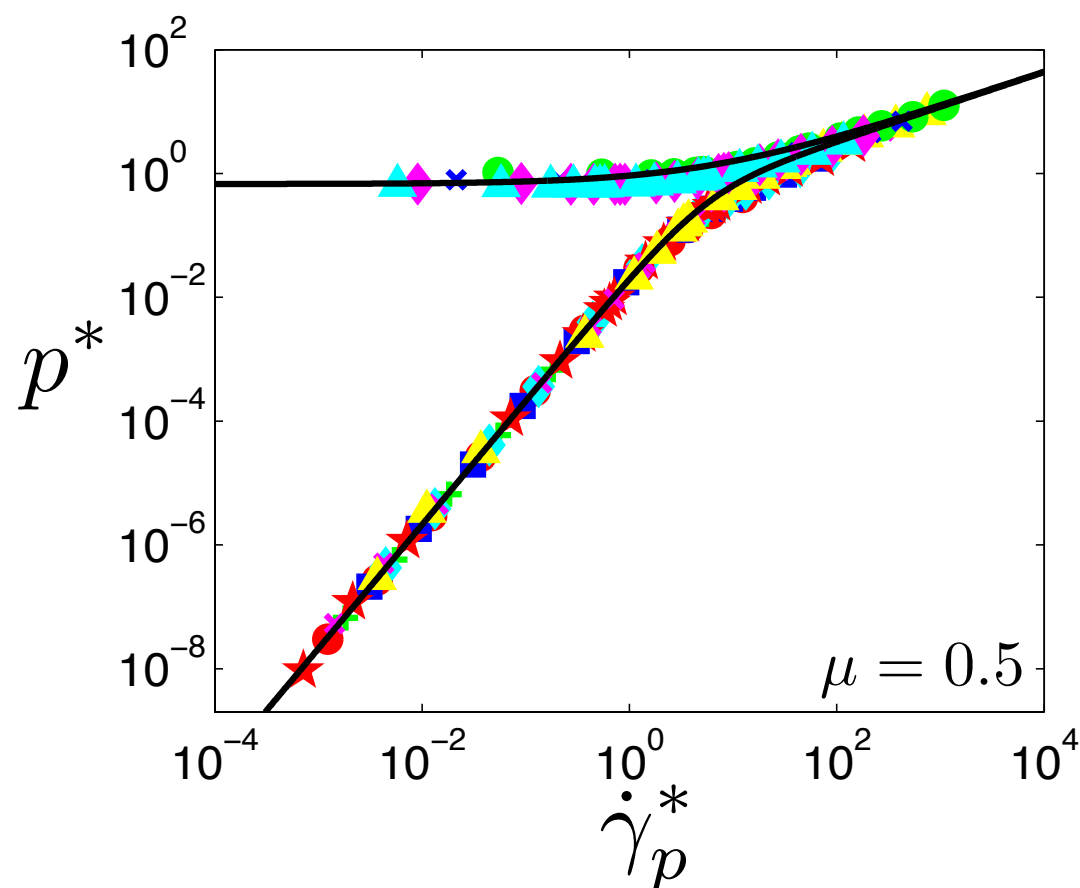
# Proposed model: blending



- Transitions between regimes can be captured using a blending function of the form:

$$B(y_1, y_2) = (y_1^w + y_2^w)^{1/w}$$

- $w = +1$  for top curve
- $w = -1$  for bottom curve



- Blended model provides fairly good agreement with DEM data.



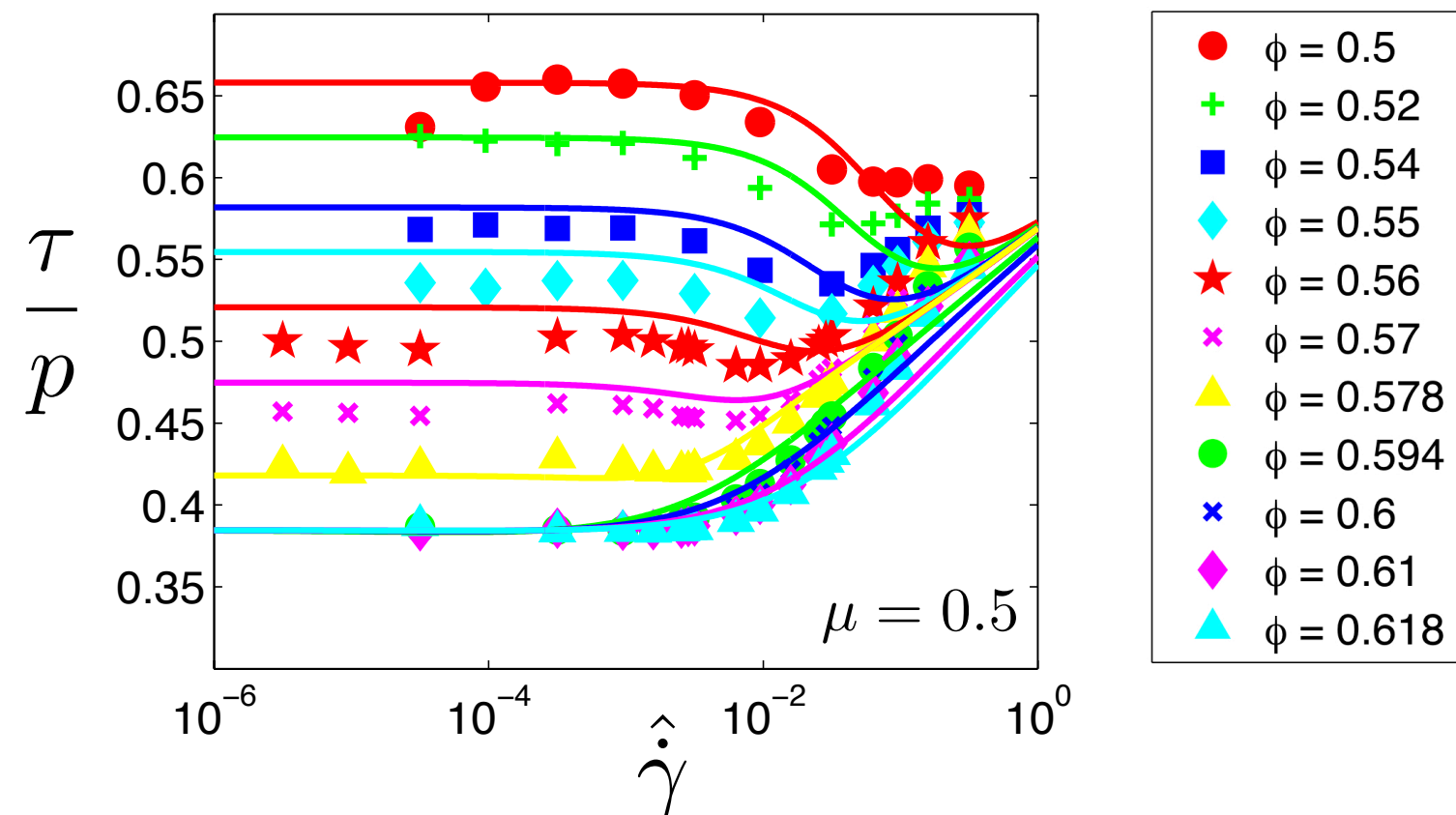
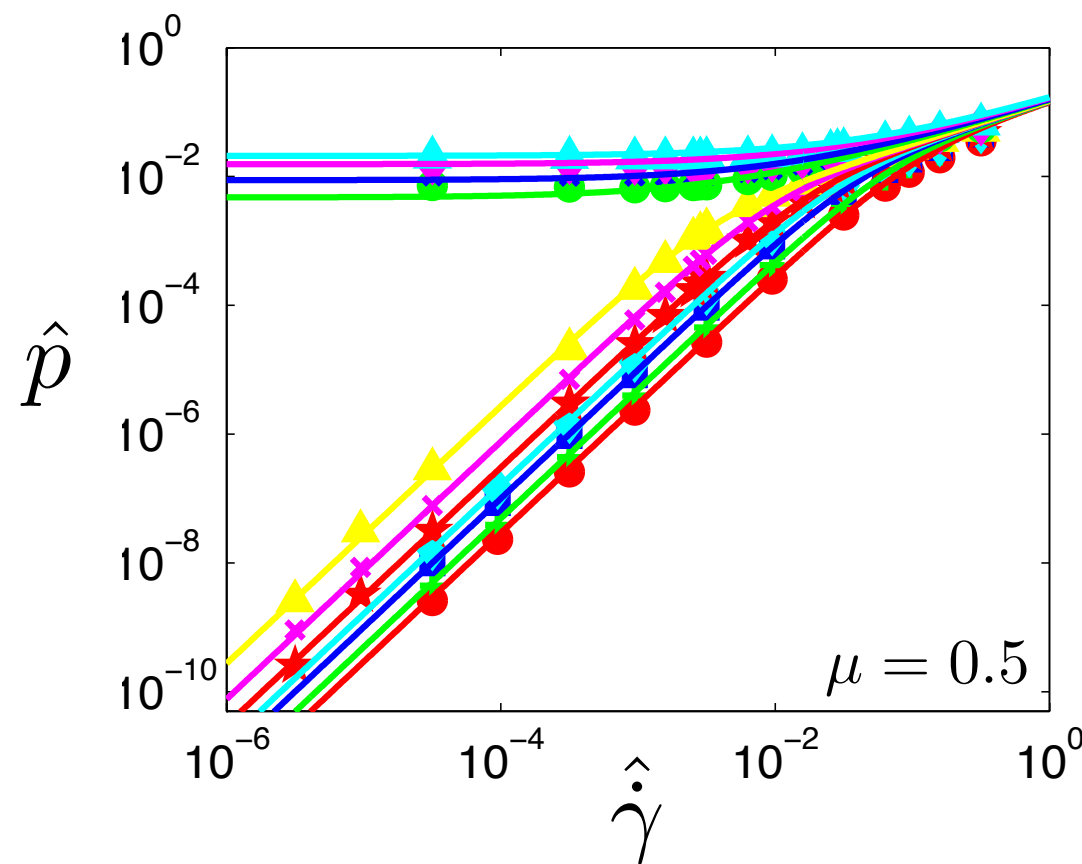
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- Blended model provides fairly good agreement with DEM data.

# Model summary

$$p = \begin{cases} p_{QS} + p_{Int} & \text{for } \phi \geq \phi_c \\ (p_{Inert}^{-1} + p_{Int}^{-1})^{-1} & \text{for } \phi < \phi_c \end{cases}$$

$$\tau = \begin{cases} \tau_{QS} + \tau_{Int} & \text{for } \phi \geq \phi_c \\ (\tau_{Inert}^{-1} + \tau_{Int}^{-1})^{-1} & \text{for } \phi < \phi_c \end{cases}$$

- **Model features:**

- ▶ Captures behavior in all three flow regimes and the transitions them.
- ▶ Continuous in shear rate – no arbitrary cutoffs.
- ▶ Piecewise in volume fraction
- ▶  $\alpha_{Inert}, \beta_{Inert} \sim (\phi/\phi_c)$  to ensure zero stresses in dilute limit.

$$p_{QS} = \alpha_{QS} |\phi - \phi_c|$$

$$\tau_{QS} = \beta_{QS} |\phi - \phi_c|$$

$$p_{Int} = \alpha_{Int} \dot{\gamma}^{2/3}$$

$$\tau_{Int} = \beta_{Int} \dot{\gamma}^{5/7}$$

$$p_{Inert} = \frac{\alpha_{Inert} \dot{\gamma}^2}{|\phi - \phi_c|^2}$$

$$\tau_{Inert} = \frac{\beta_{Inert} \dot{\gamma}^2}{|\phi - \phi_c|^{9/5}}$$

# Model summary

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- **Model features:**

- ▶  $\phi_c = \phi_c(\mu)$
- ▶  $\alpha_{QS}, \beta_{QS}$  depend on  $\mu$
- ▶  $\alpha_{Inert}, \beta_{Inert}$  depend on  $\mu$  via effective restitution coefficient
- ▶  $\alpha_{Int}, \beta_{Int}$  independent of  $\mu$

$$p_{QS} = \alpha_{QS} |\phi - \phi_c|$$

$$\tau_{QS} = \beta_{QS} |\phi - \phi_c|$$

$$p_{Int} = \alpha_{Int} \dot{\gamma}^{2/3}$$

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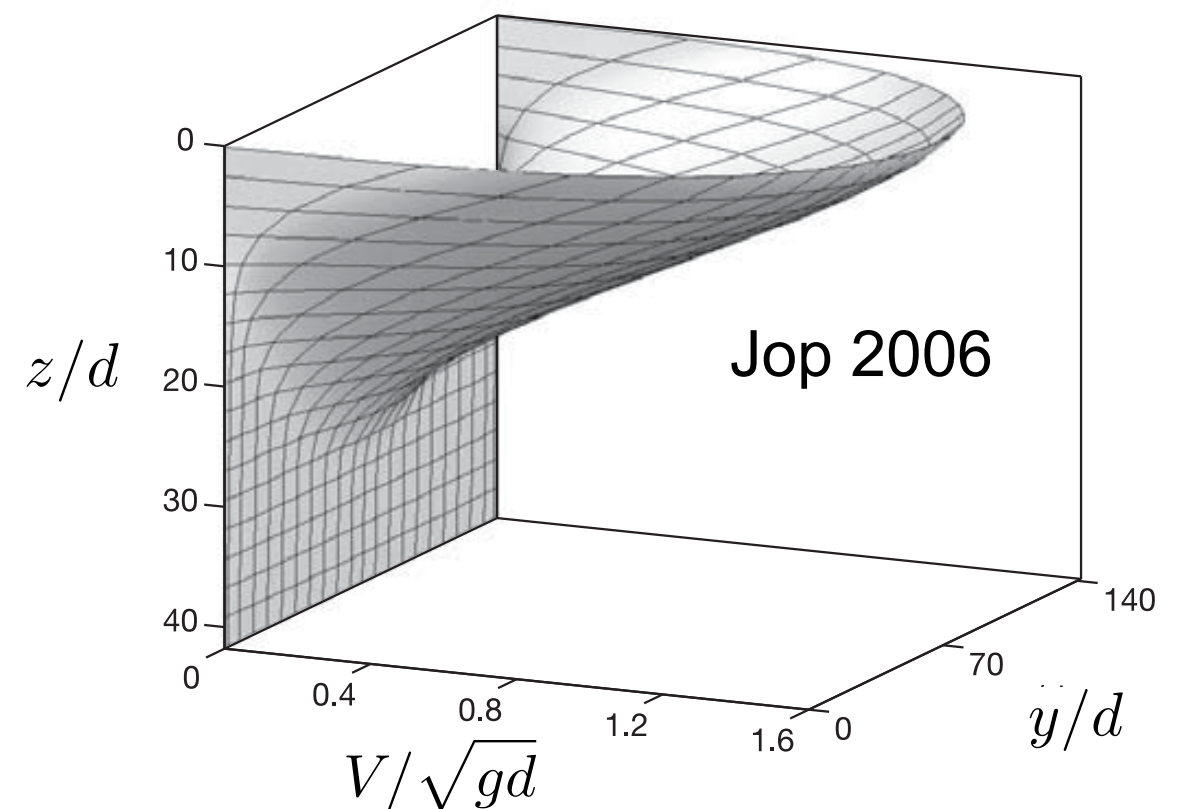
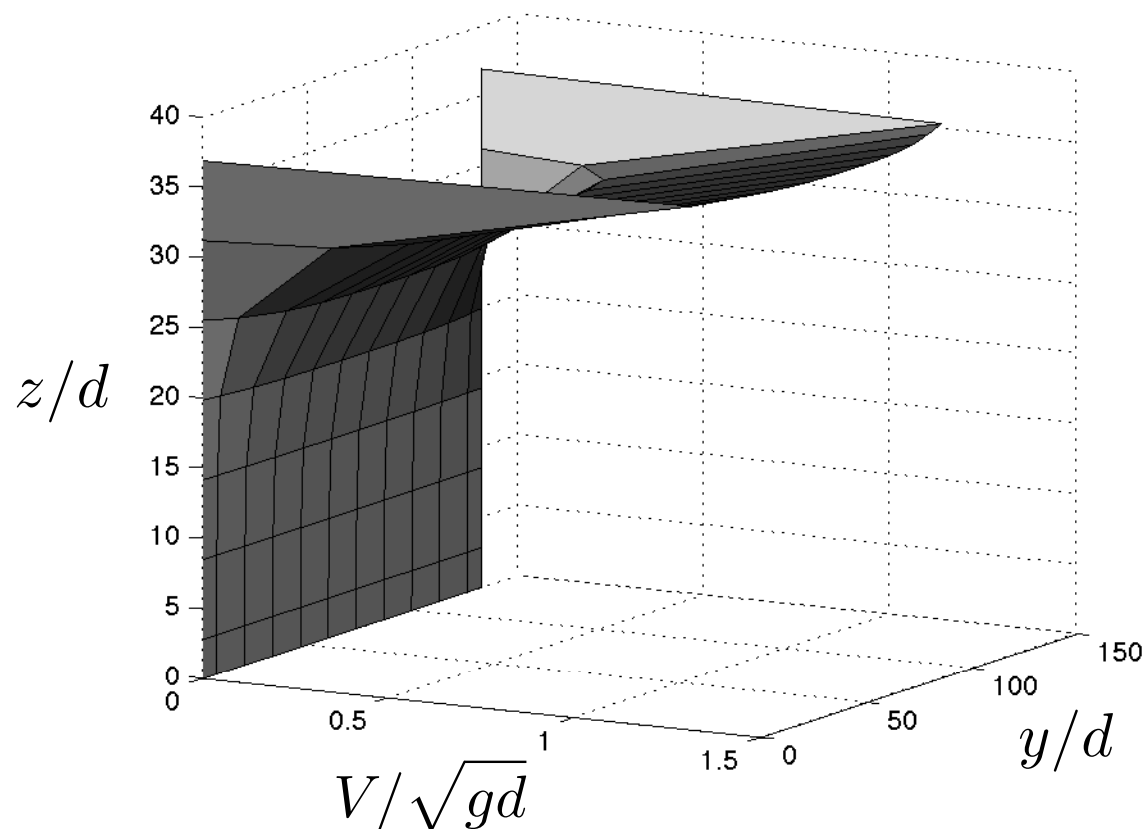
$$p_{Inert} = \frac{\alpha_{Inert} \dot{\gamma}^2}{|\phi - \phi_c|^2}$$

$$\tau_{Inert} = \frac{\beta_{Inert} \dot{\gamma}^2}{|\phi - \phi_c|^{9/5}}$$

# Continuum model application



- Stress model was implemented in MFLX
- Chute flow simulations were performed for comparison with existing experimental and computational data<sup>†</sup>.

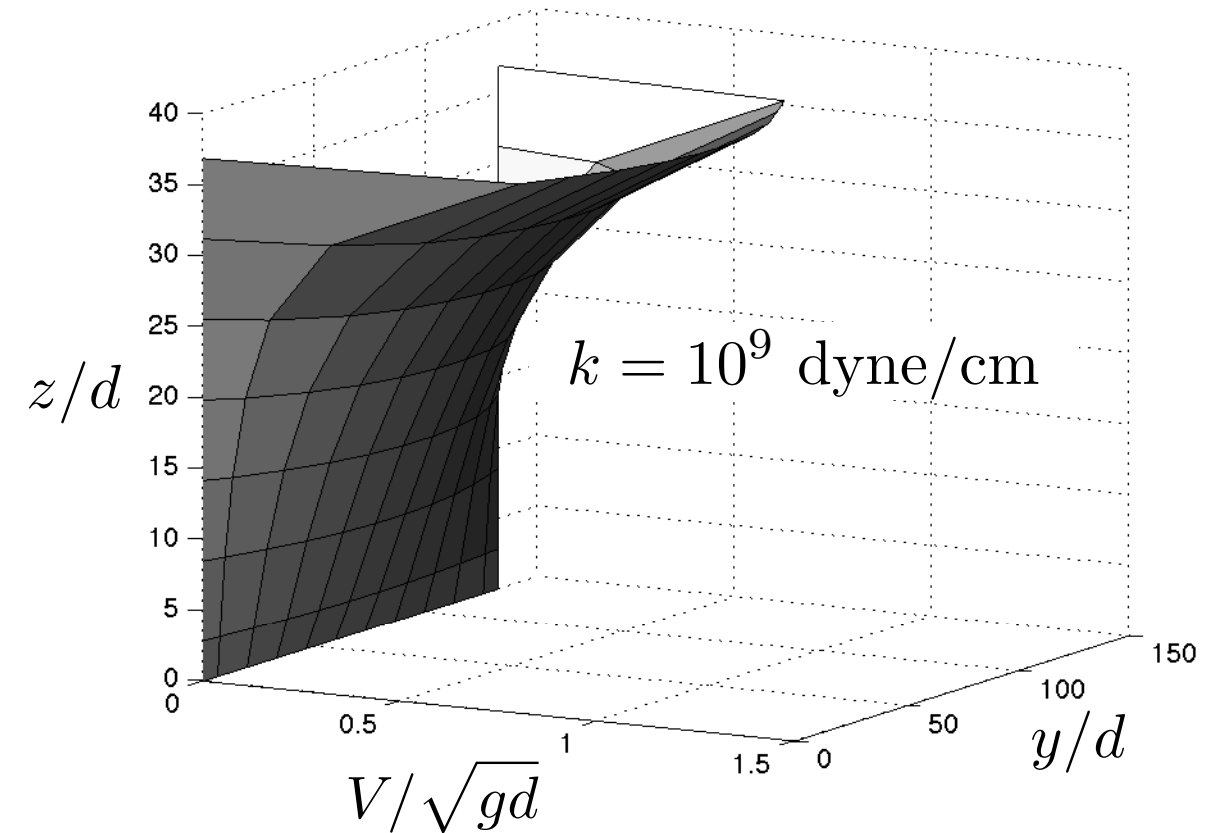
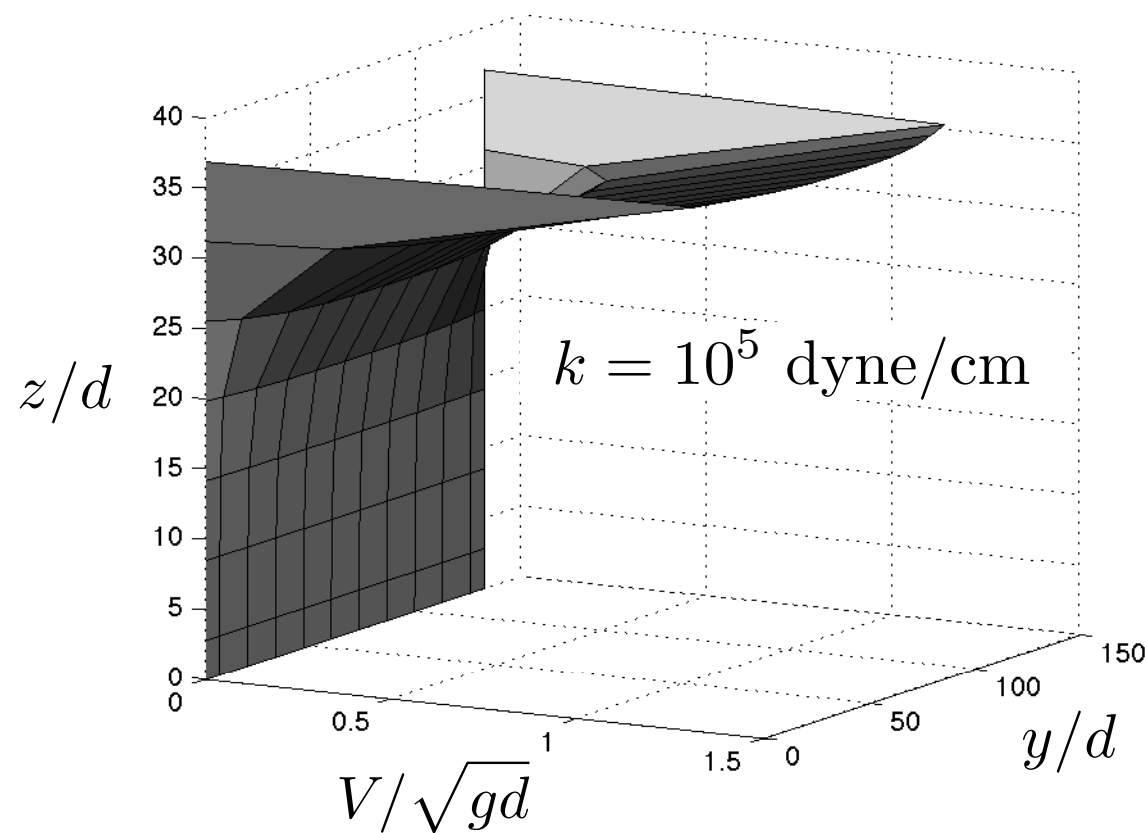


<sup>†</sup> P. Jop, Y. Forterre, and O. Pouliquen, Nature 441, 727 (2006).

# Continuum model application



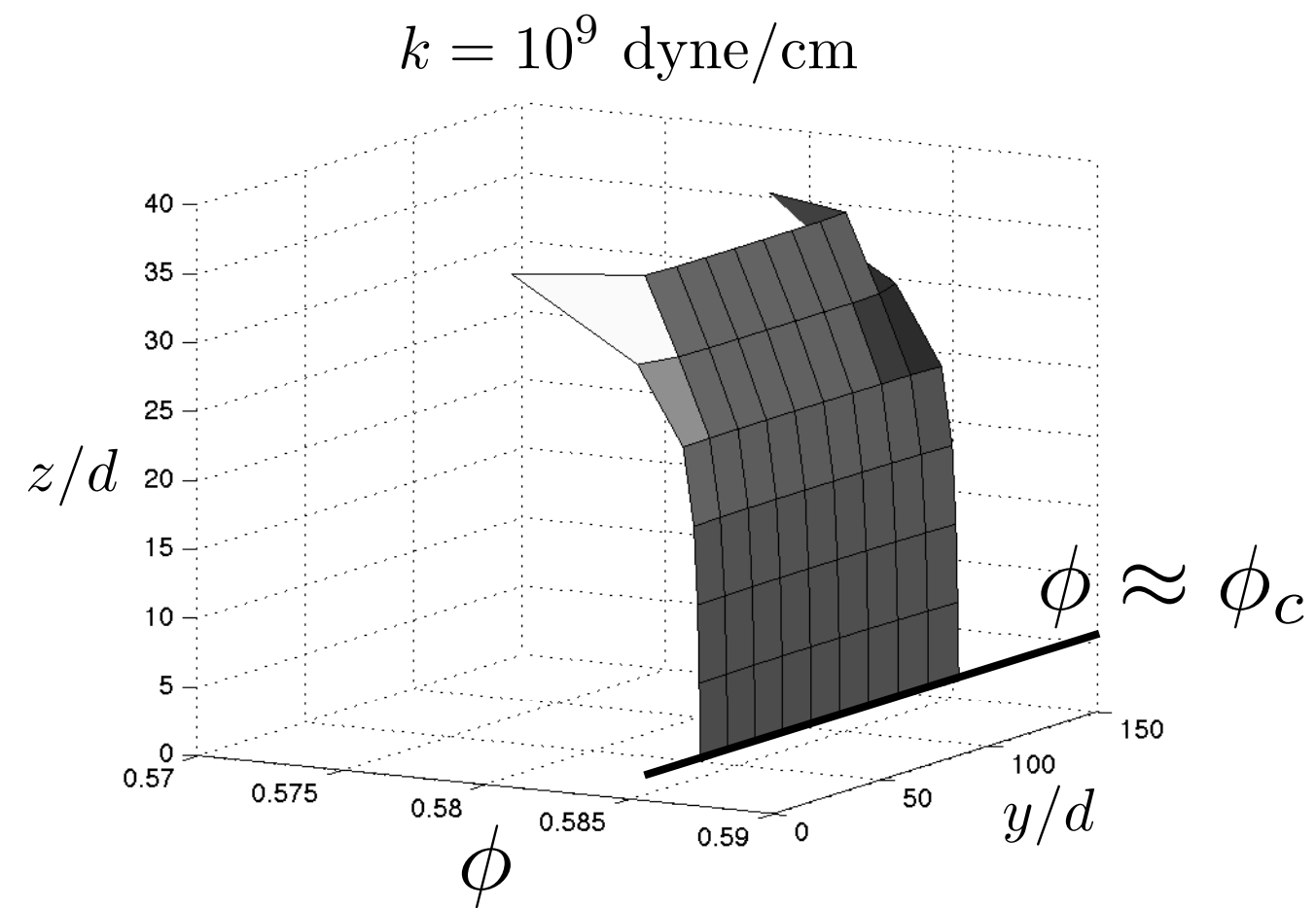
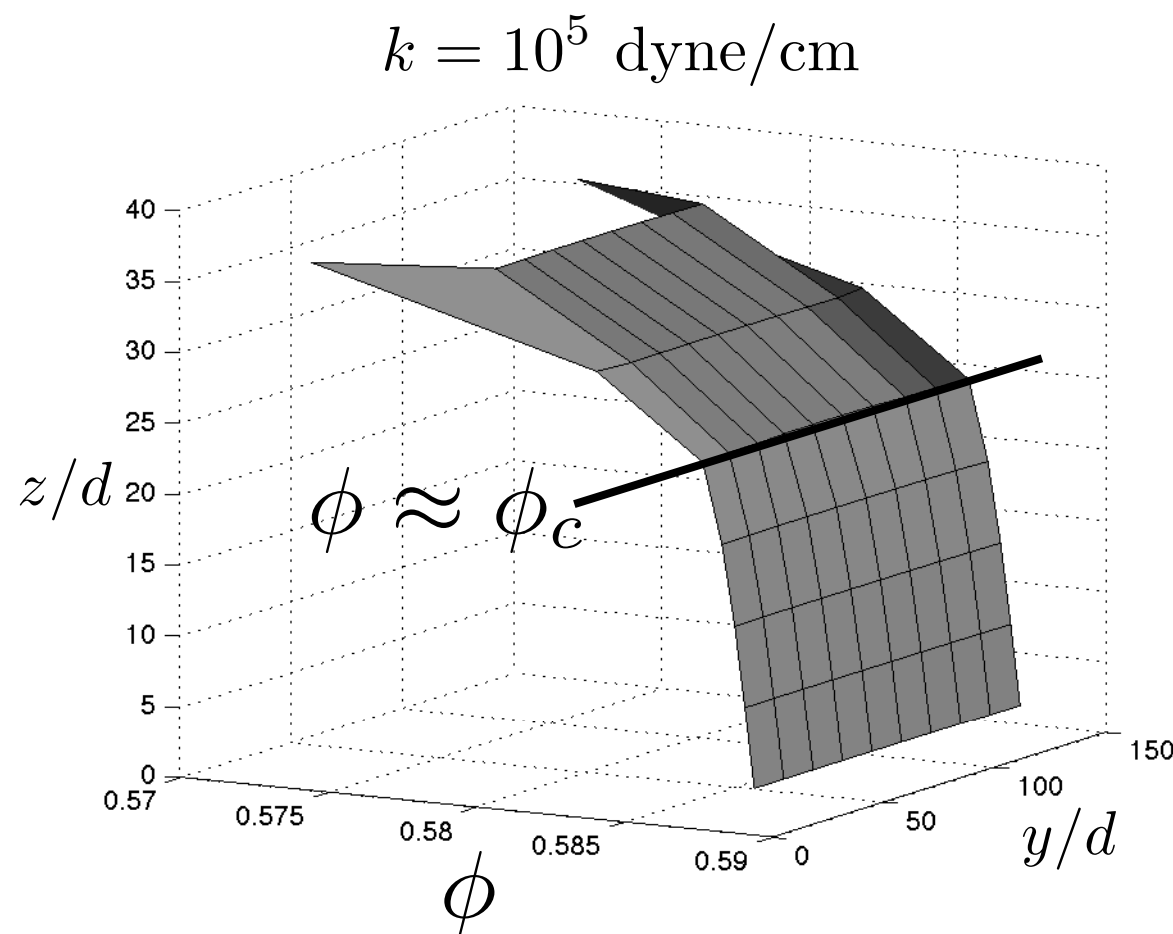
- Thickness of flowing and stagnant layers depends on particle stiffness  $k$



# Continuum model application



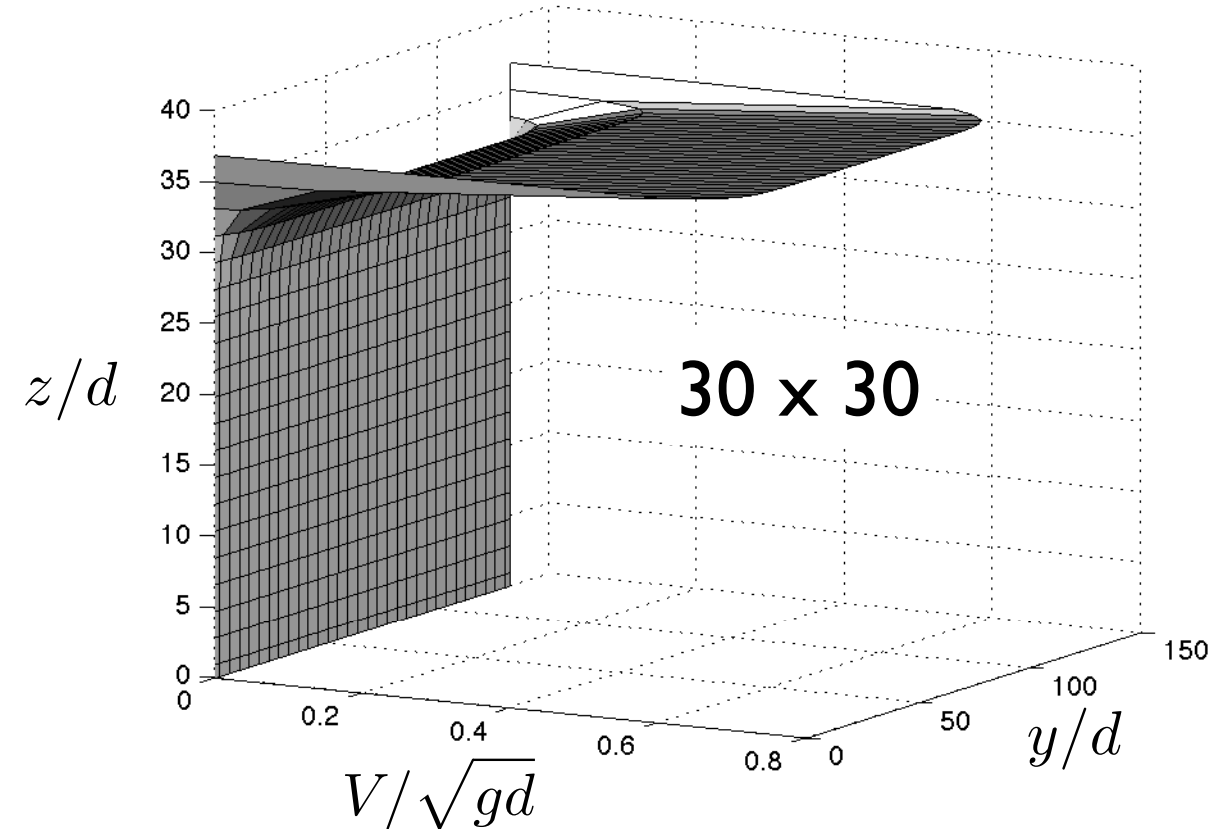
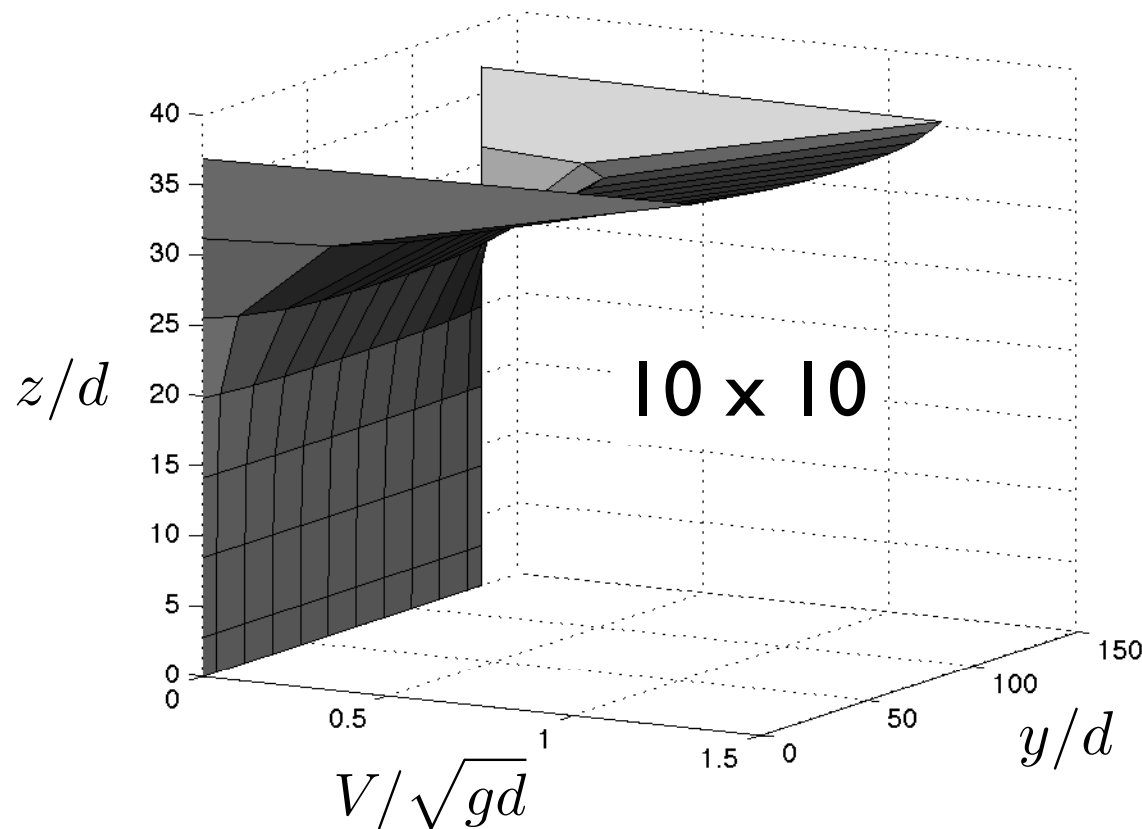
- Slight volume fraction variations around  $\phi_c$  dictate regime of flow



# Continuum model application



- Unresolved issues:
  - ▶ Flow profile depends on grid size
  - ▶ Flow profile is sensitive to initial volume fraction profile

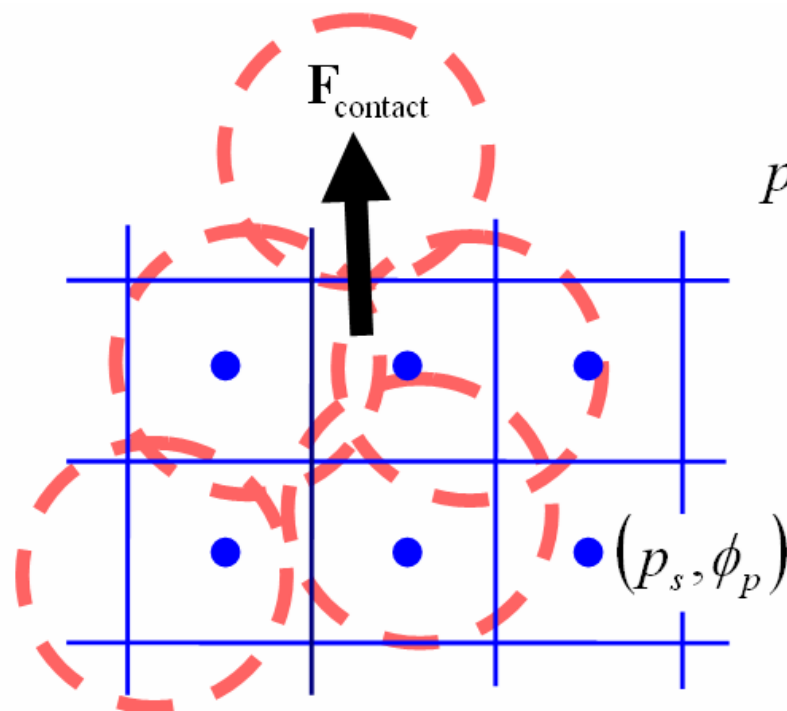


# Parcel Based Methods

- Groups of particles
- Requires virtual contact forces to prevent overpacking

## MP-PIC

Effective particle phase pressure  
(Snider<sup>1</sup>)

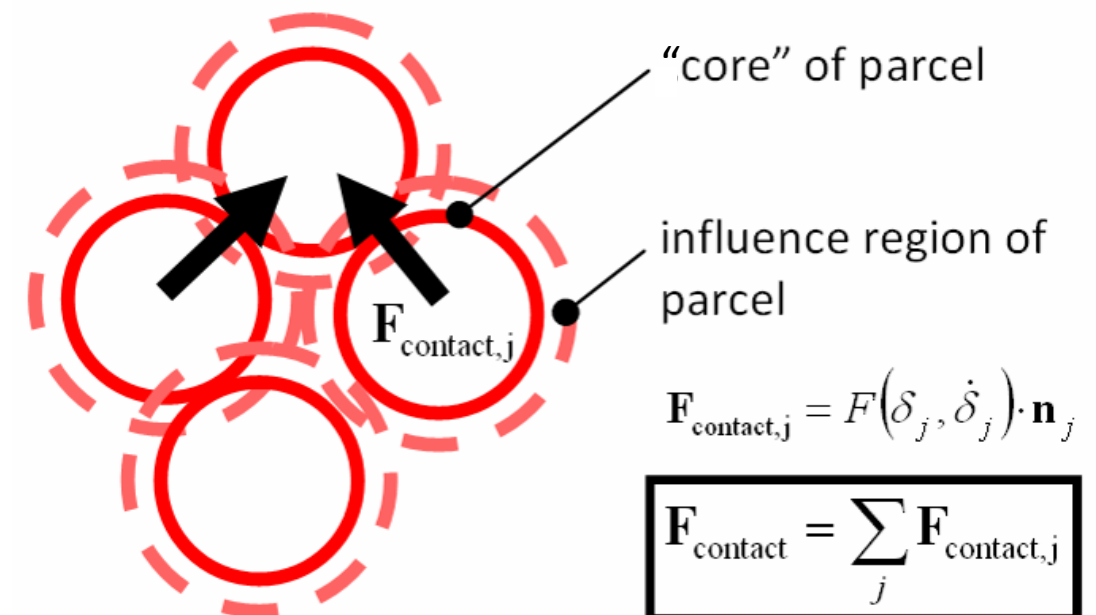


$$p_s = P_s \cdot \frac{\phi_p}{\phi_{CP} - \phi_p}$$

$$\mathbf{F}_{\text{contact}} = -\nabla p_s$$

## DPM

Parcel collisions  
(Patankar and Joseph<sup>2</sup>)



<sup>1</sup>Snider, *JCP* 170 (2001), 6014-6028. <sup>2</sup>Patankar and Joseph, *IJMF* 27 (2001), 1659-1684.



# Questions on DEM to DPM



## 1. Quasi-static flow regime

- ▶ How should the particle interaction parameters in DEM be scaled for the DPM?

## 2. Inertial flow regime

- ▶ Is the scaling identified in quasi-static flow sufficient?
- ▶ If not, what additional model is needed?

# Quasi-Static Regime Scaling



- Dimensional analysis of a linear spring-dashpot model requires:<sup>3</sup>

$$\left. \begin{aligned} \Pi_1 &= k_n / (R_i \cdot \rho_p \cdot v_0^2) \\ \Pi_2 &= c_n / (R_i^2 \cdot \rho_p \cdot v_0) \end{aligned} \right\} = \text{const}$$

$c_n$ ...damping coefficient

$k_n$ ...spring stiffness

$R_i$ ...radius of parcel  $i$

$v_0$ ...char. impact velocity

$\omega$ ...rotation rate

$\Pi$ ...dimensionless  
parameters

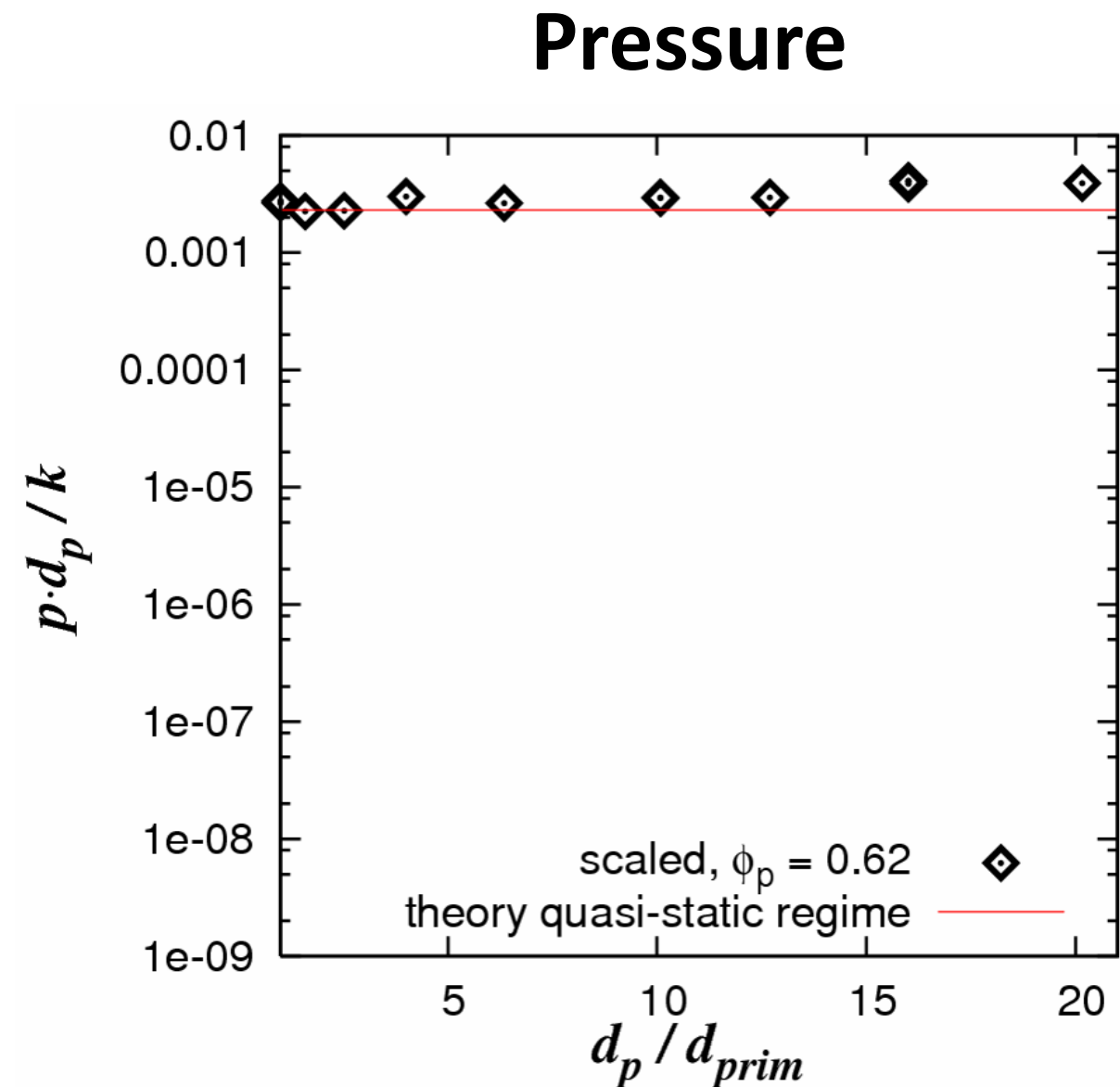
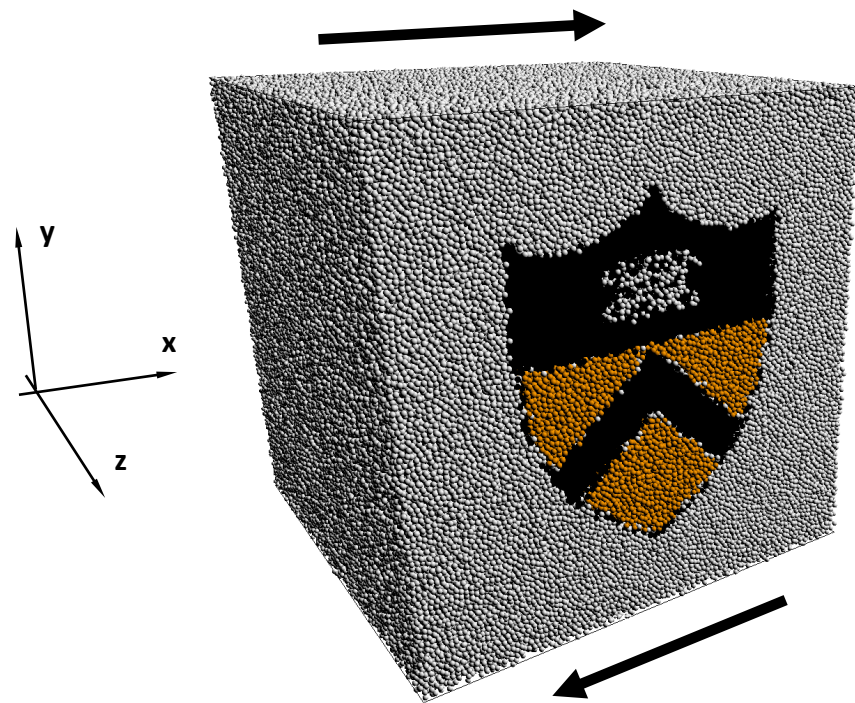
$\rho_p$ ...parcel density

<sup>3</sup>Bierwisch, *PhD Thesis* (2009), University of Freiburg.

# Simple shear in quasi-static regime



- Spring stiffness and damping coefficient are adjusted as stipulated by dimensional analysis.
- Stresses in the quasi-static regime ( $\Phi_p = 0.62$ ) are nearly constant.



# Inertial flow regime scaling



- Spring stiffness and damping coefficient are adjusted as stipulated by dimensional analysis
- Model unresolved collisions with BGK-like relaxation<sup>4</sup>
  - ▶ Try to achieve consistency with DEM by taking parcel-to-particle diameter ratio  $\alpha$  into account.

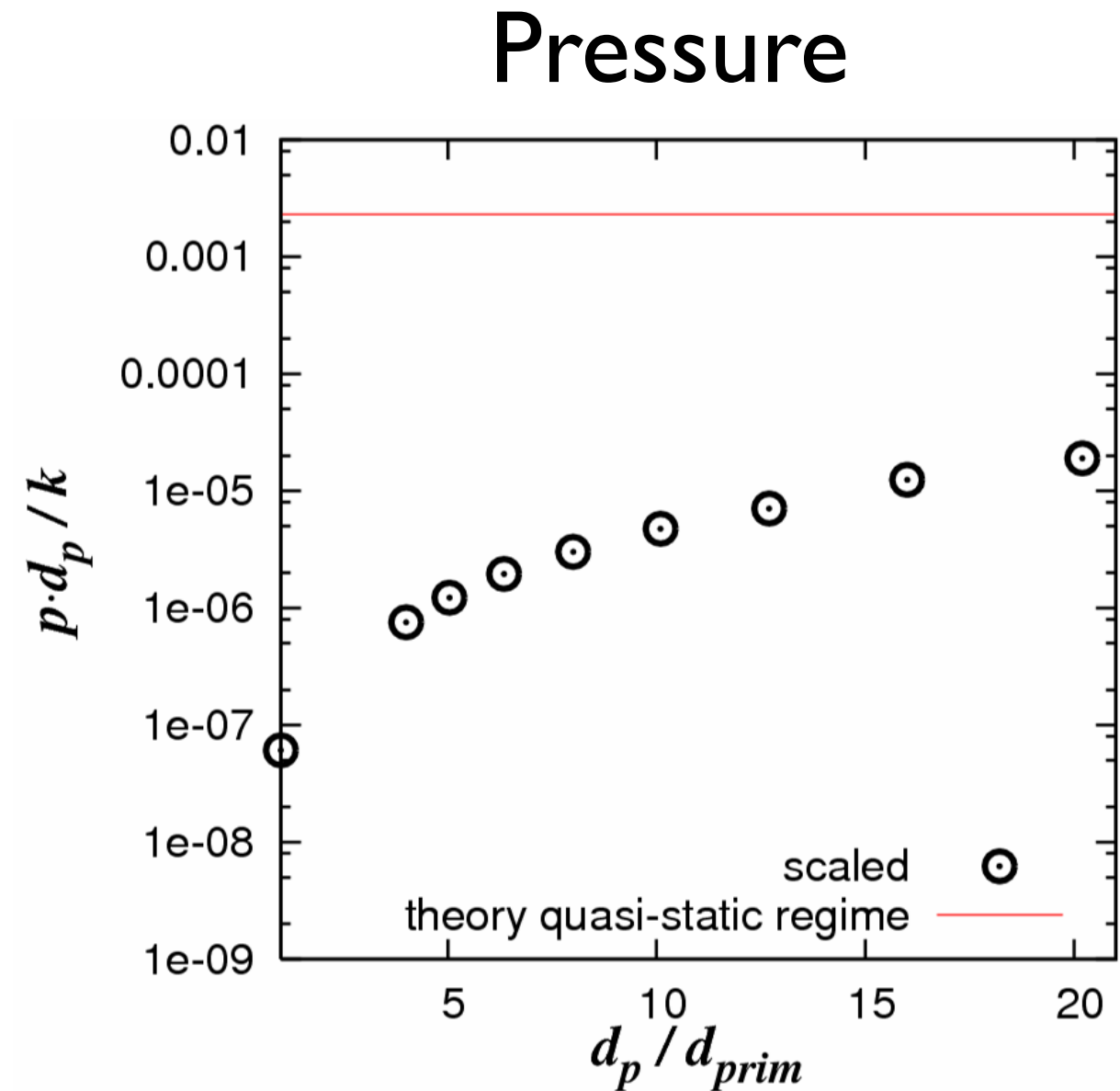
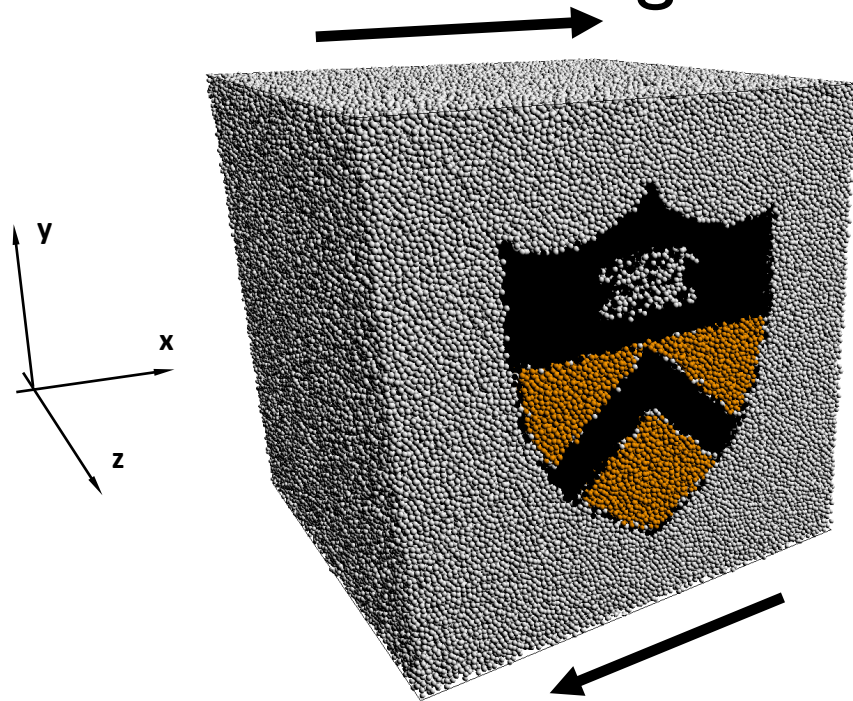
$$\frac{1}{\tau_{\text{relax}}} = \underbrace{\frac{1}{\tau_{\text{coll}}}}_{\substack{\text{collision time} \\ \text{from kinetic theory}}} \underbrace{\left(1 - \frac{1}{\alpha}\right)}_{\substack{\text{factor to guarantee} \\ \text{consistency with} \\ \text{DEM}}}$$

$\alpha$ ...ratio of parcel and primary particle diameter  
 $\tau_{\text{coll}}$ ...collision time  
 $\tau_{\text{relax}}$ ...relaxation time

# Simple shear in inertial regime



- Massive increase in stress in the inertial regime ( $\Phi_p = 0.55$ ). Similar observations for  $T_{gran}$ .<sup>5</sup>



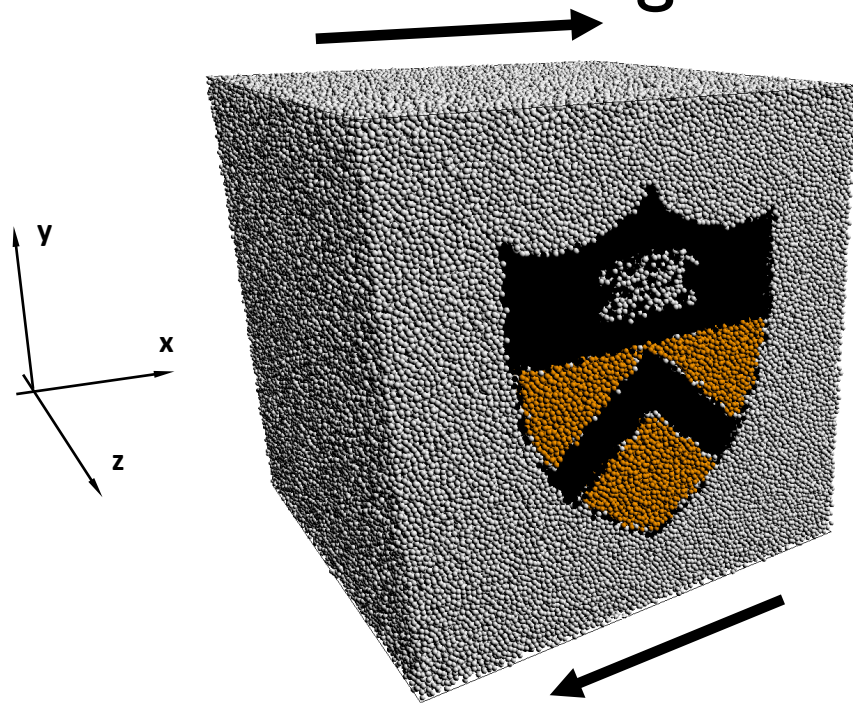
<sup>5</sup>Benyahia and Galvin, *Ind Eng Chem Res* 49 (2010), 10588-10605



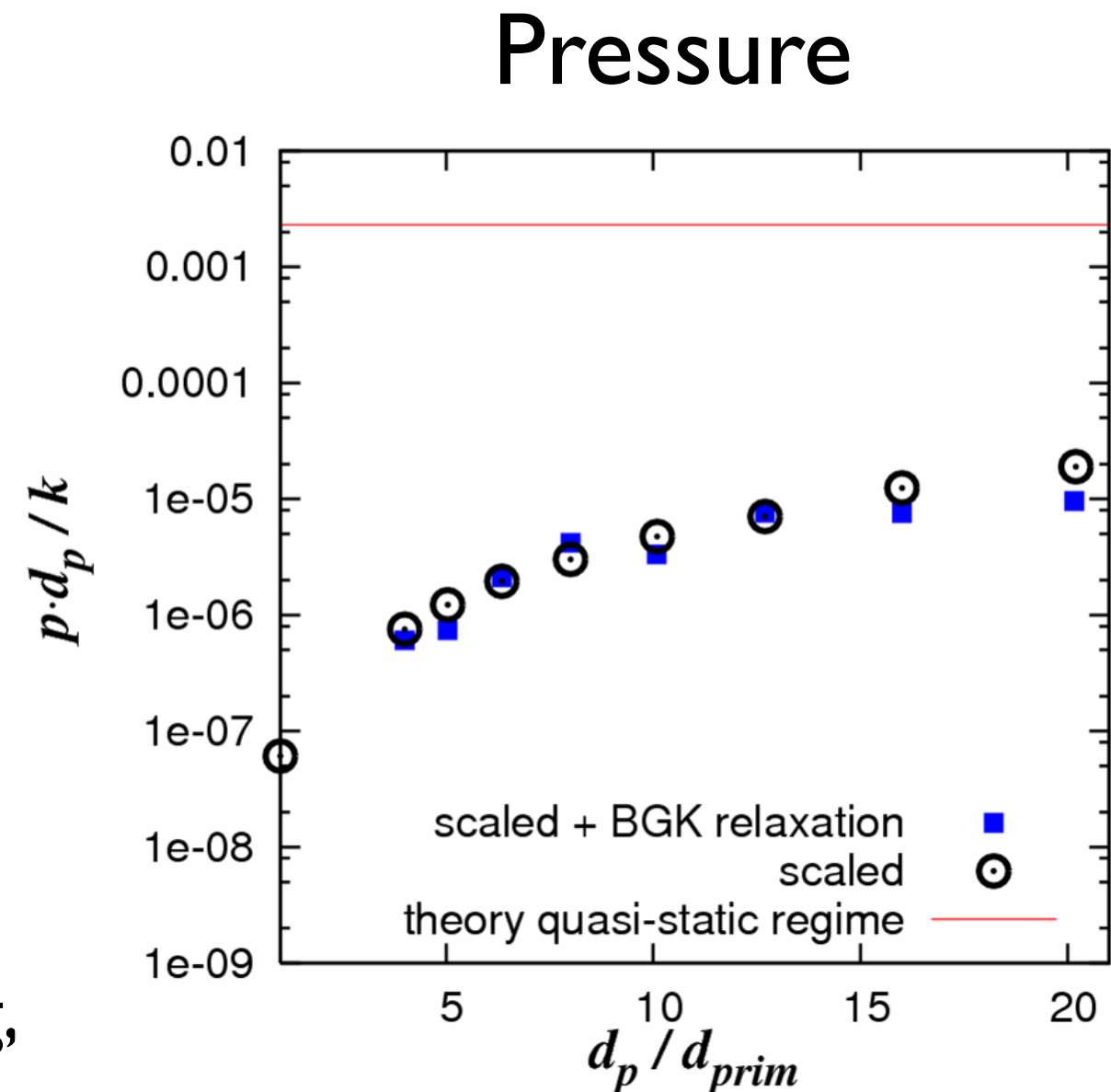
# Simple shear in inertial regime



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- In DPM with parcel collision tracking, gross overprediction of stresses cannot be avoided, even if we implement BGK-like damping.



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# Results

## Granular Jet

- Comparison of scattering pattern of particles with experiments.<sup>5</sup>

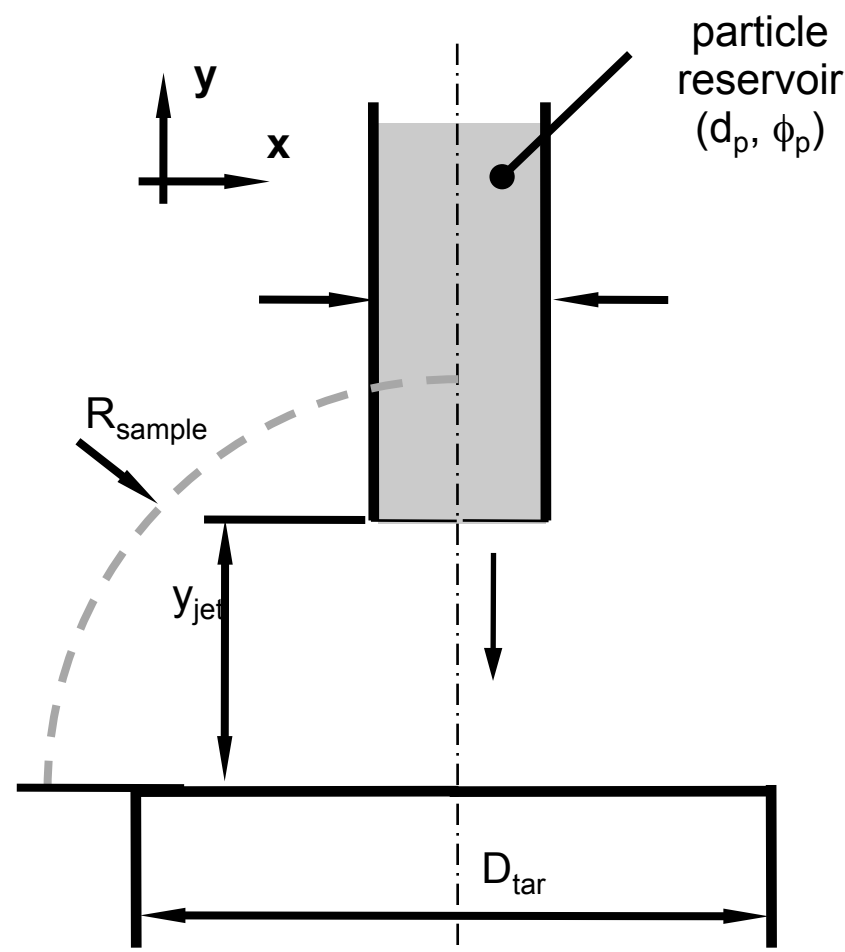


Figure: Setup used for the granular jet computations.

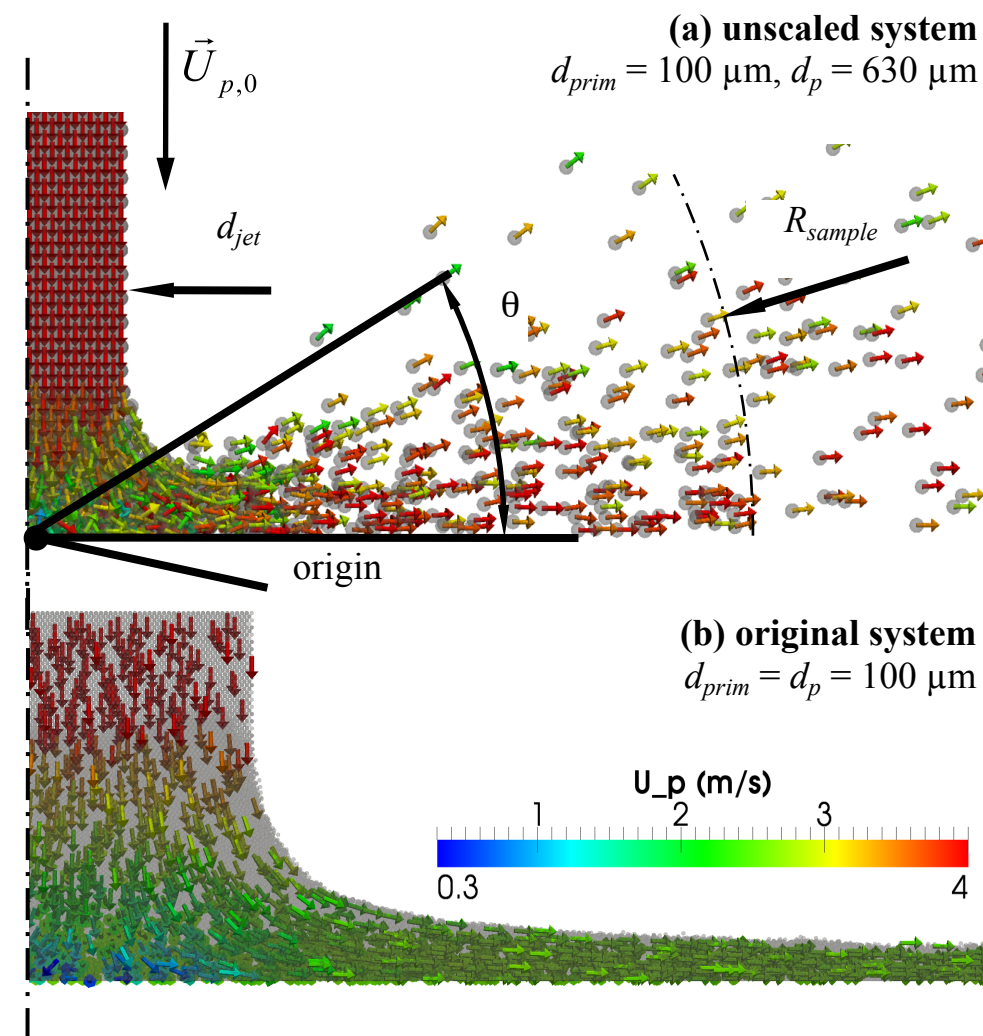


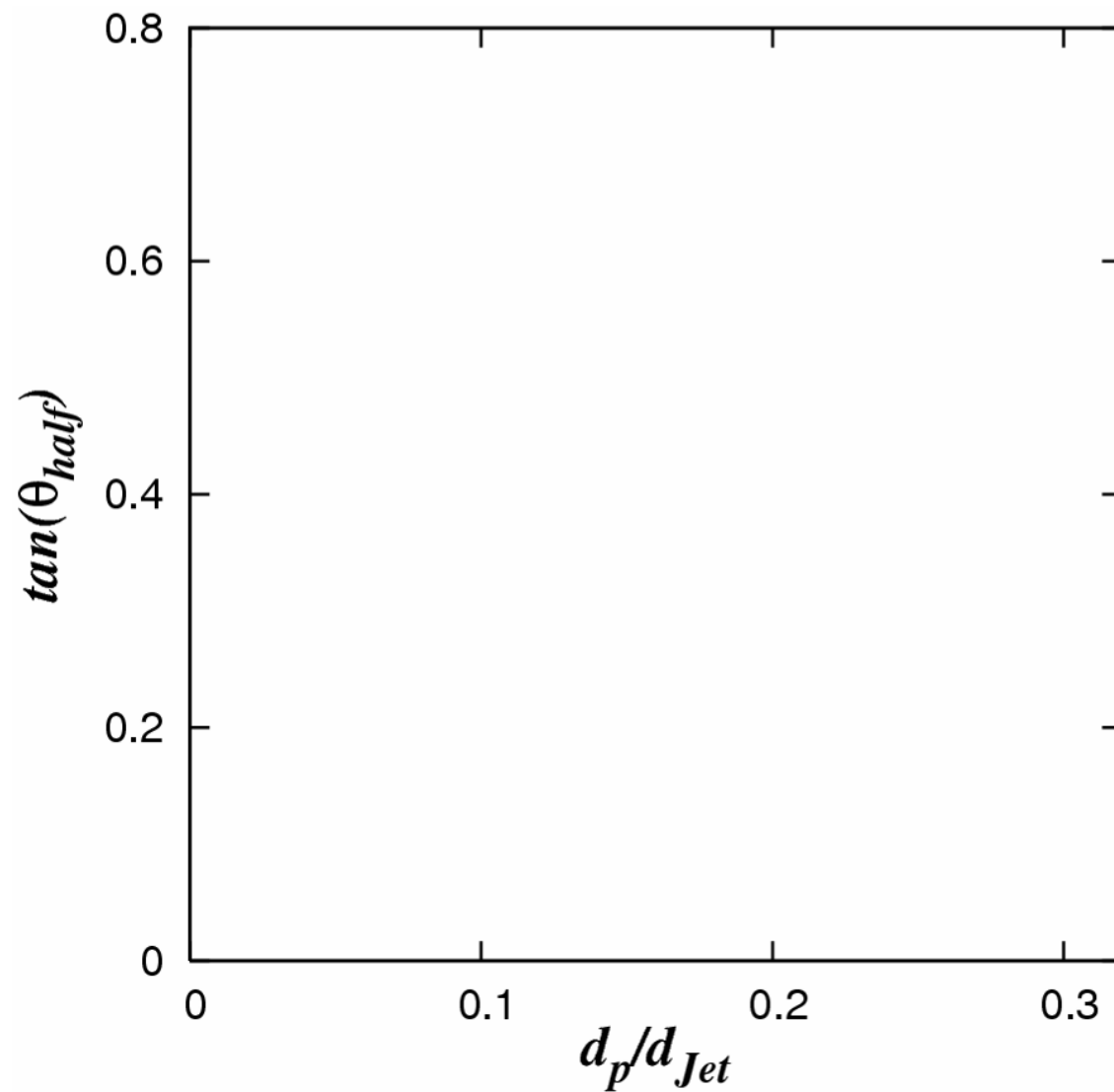
Figure: Particle velocities near the impact region of a granular jet.

<sup>5</sup>Cheng et al., *PRL* 99 (2007), 188001-188004.

# Granular Jet



Scattering half angle  $\theta_{half}$   $\int_0^{\theta_{half}} P(\theta) d\theta = 0.5$



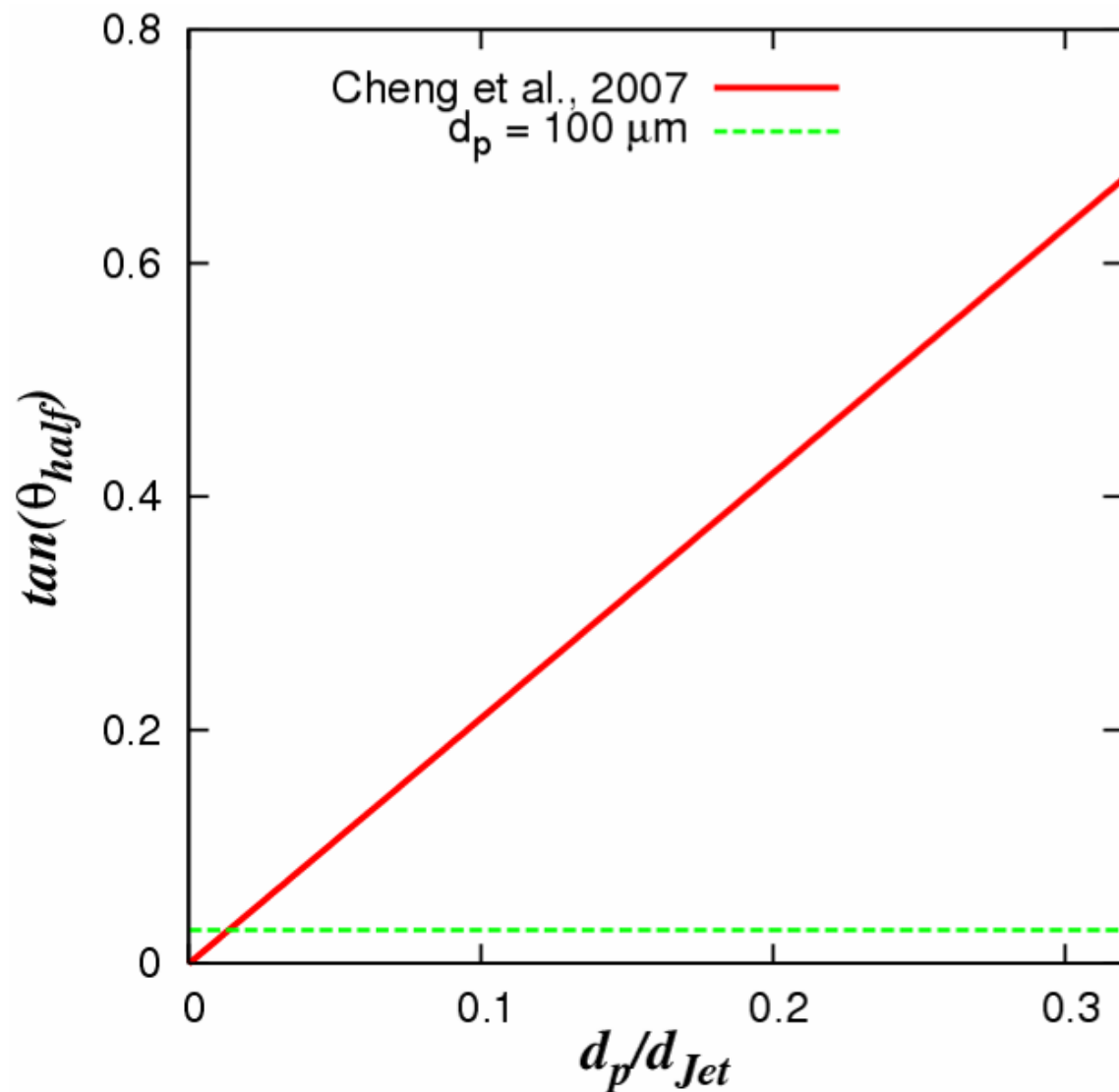


# Granular Jet



Scattering half angle  $\theta_{half}$

$$\int_0^{\theta_{half}} P(\theta) d\theta = 0.5$$



- **Cheng's prediction:**

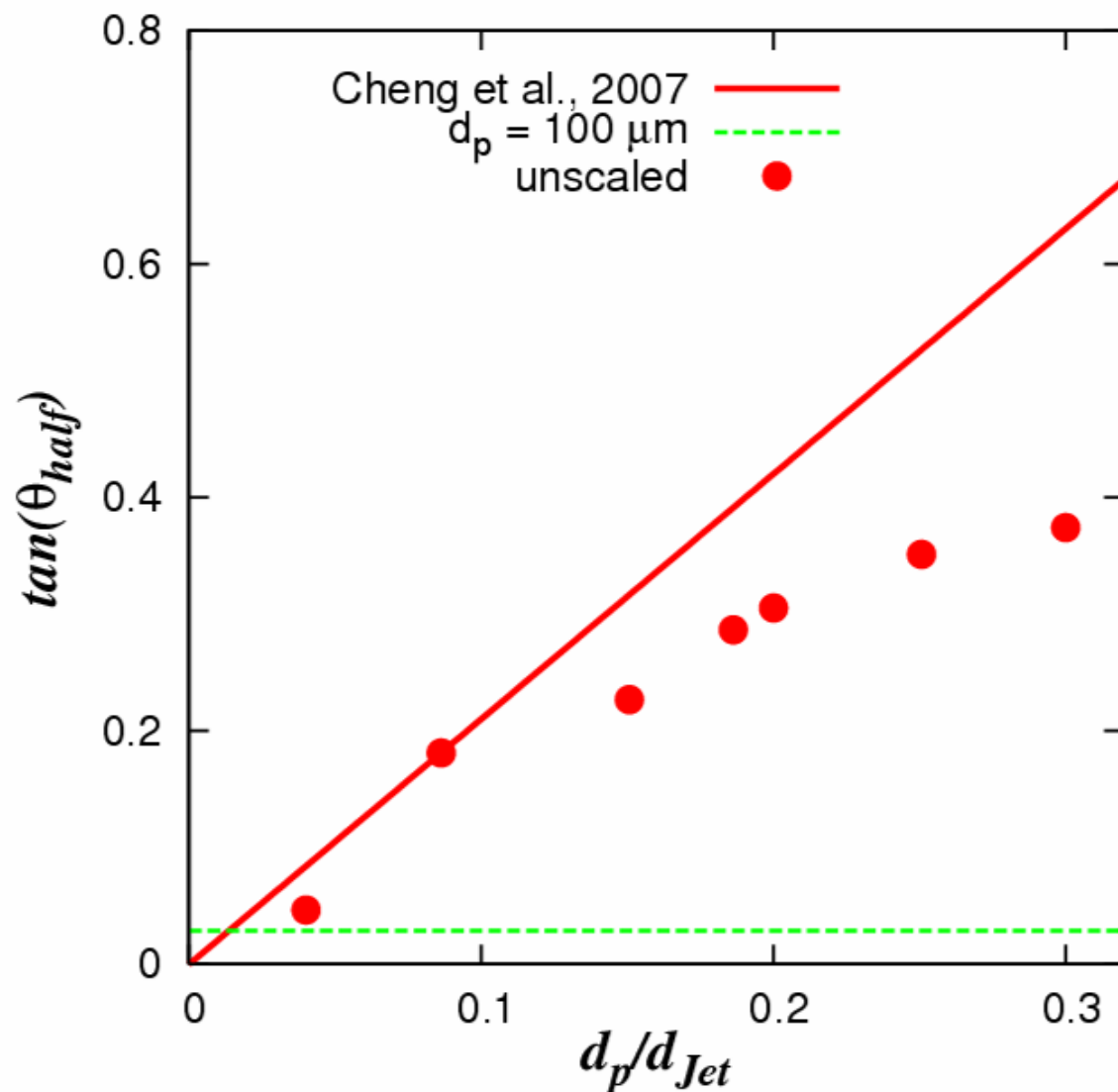
$$\tan(\theta_{half}) = 2.1 \times d_p / d_{jet}$$

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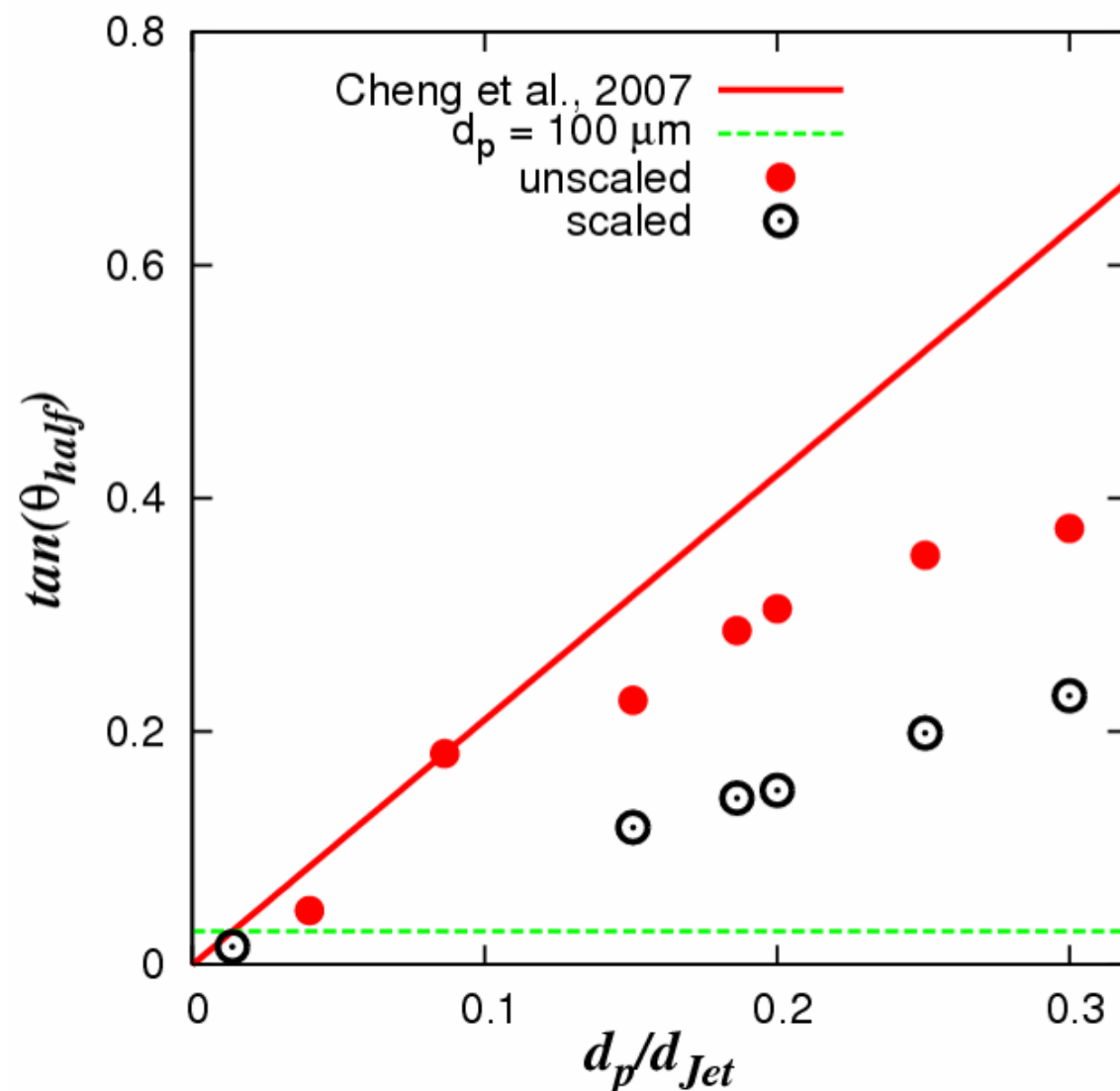
- **Unscaled system** behaves like a system with **larger primary particles**.

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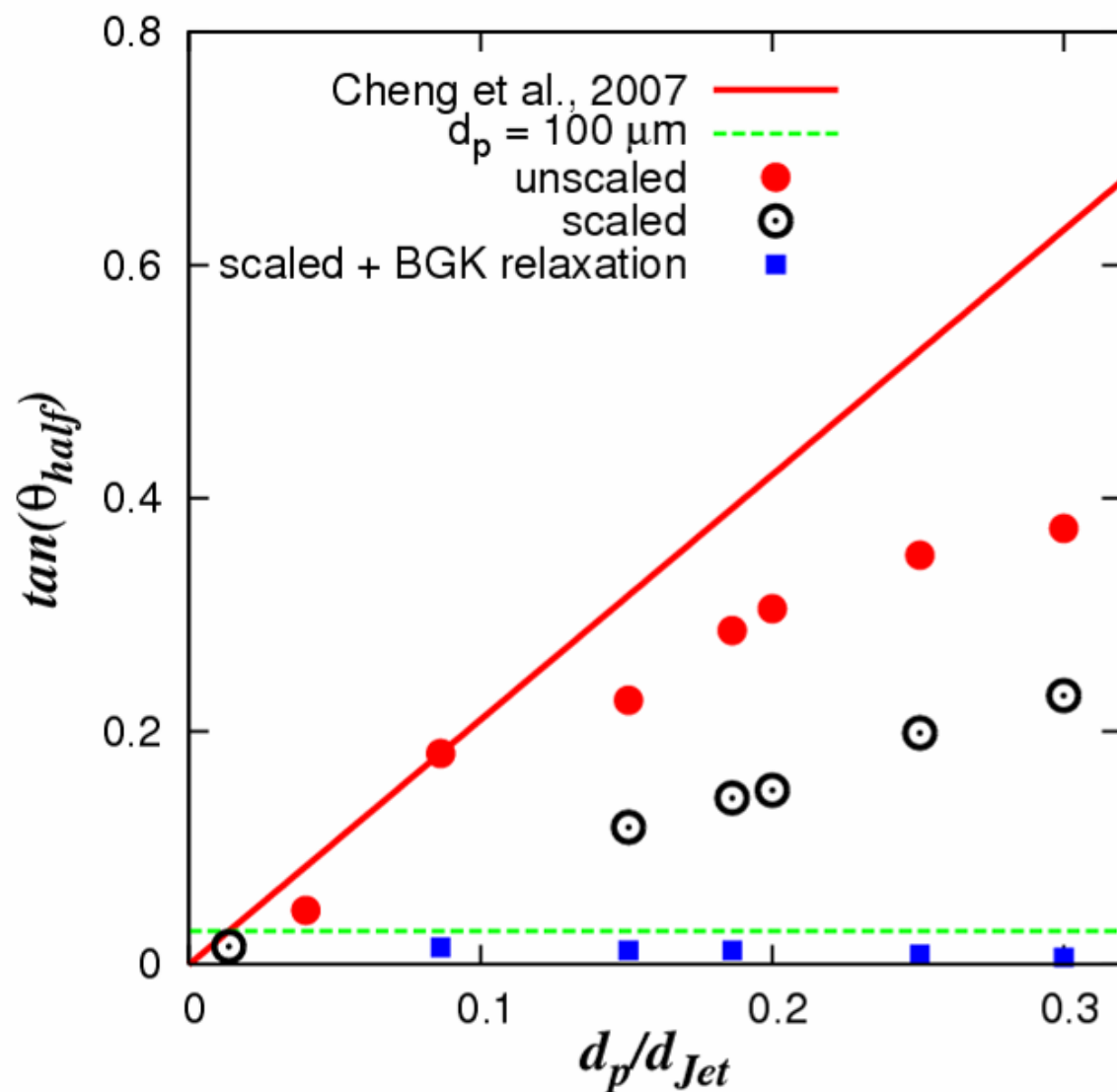
- **Unscaled system** behaves like a system with **larger primary particles**.
- **Scaled system** also **overpredicts scattering angle**.

# Granular Jet



Scattering half angle  $\theta_{half}$

$$\int_0^{\theta_{half}} P(\theta) d\theta = 0.5$$



- **Cheng's prediction:**

$$\tan(\theta_{half}) = 2.1 \times d_p / d_{jet}$$

- **Unscaled system** behaves like a system with **larger primary particles**.
- **Scaled system** also **overpredicts scattering angle**.
- **Improved agreement** when **BGK-like relaxation** is employed.

# Summary

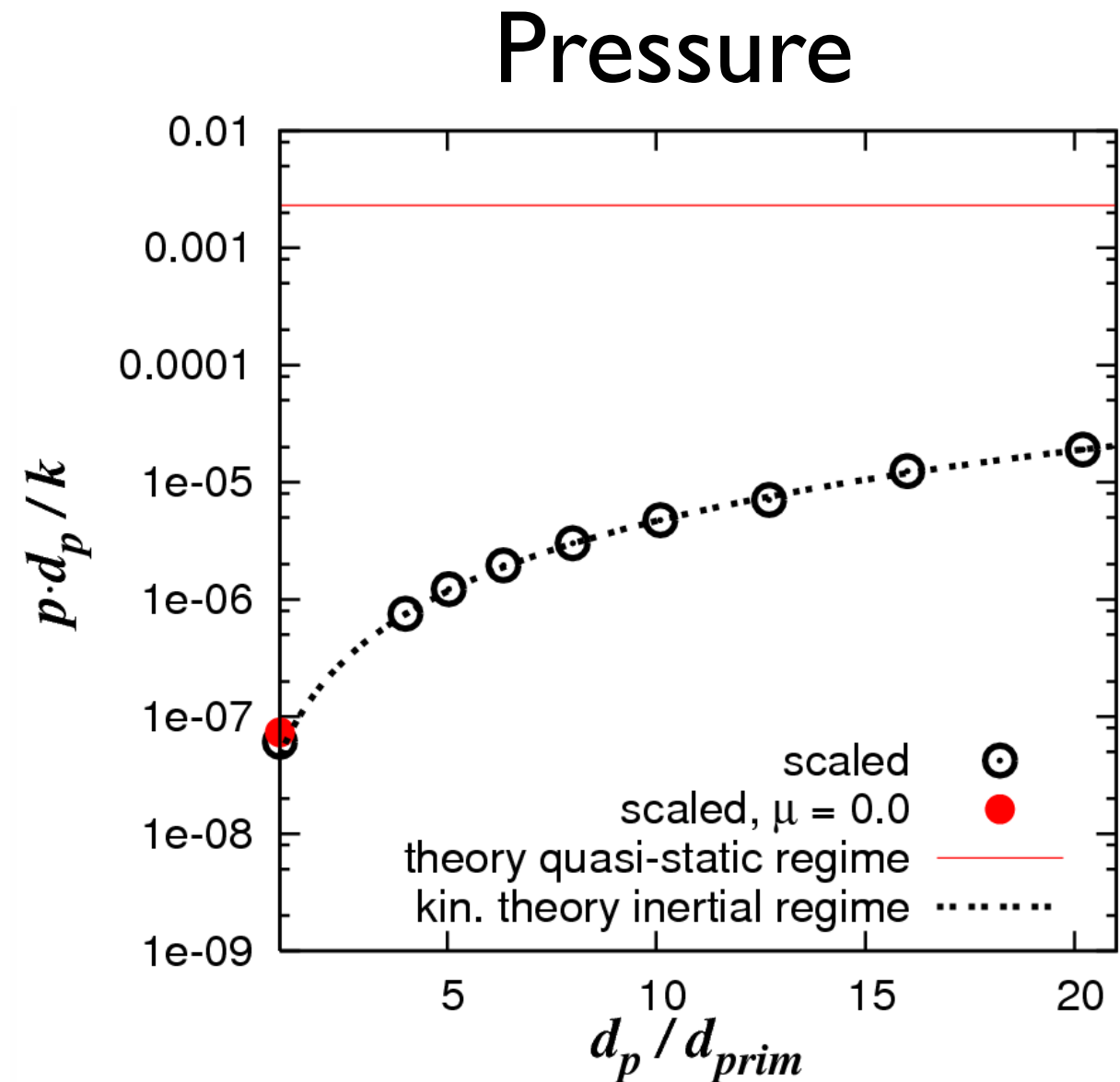
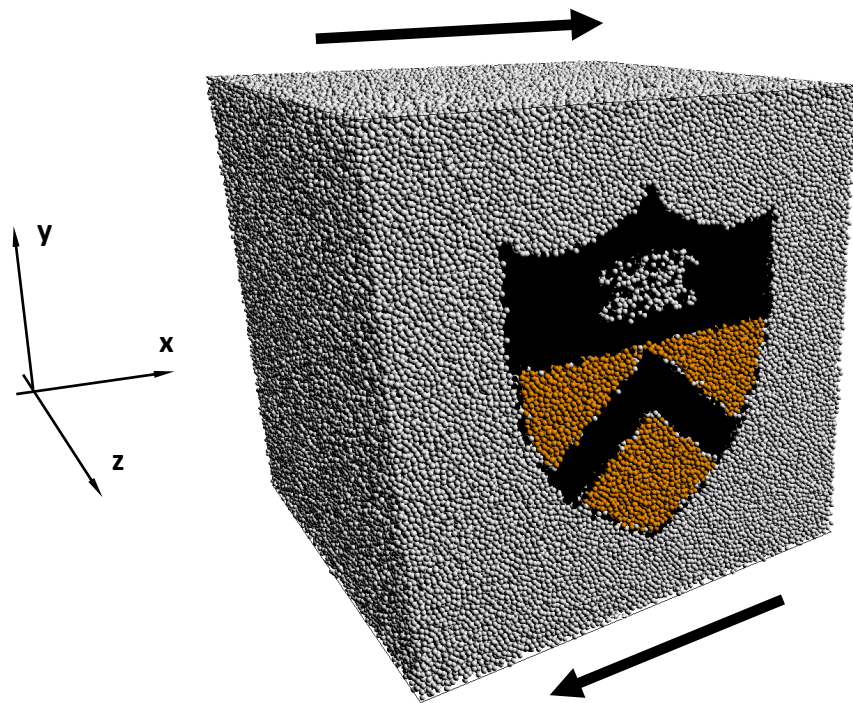


- Continuum model
  - ▶ We have formulated a continuum rheological model that spans all three regimes of flow and implemented in MFIX.
  - ▶ Preliminary results on chute flow have been obtained, but a systematic parametric study remains incomplete.
- Parcel-based simulation with collisions between parcels
  - ▶ Scaling DEM parameters for DPM in quasi-static flow regime readily follows from dimensional analysis.
  - ▶ Even with the addition of BGK-like relaxation, DPM cannot be made to yield the same stress as DEM in the inertial regime.
  - ▶ Particle jet data could be captured by DPM if BGK-like relaxation is included.

# Simple shear in inertial regime



- Massive increase in stress in the inertial regime ( $\Phi_p = 0.55$ ).

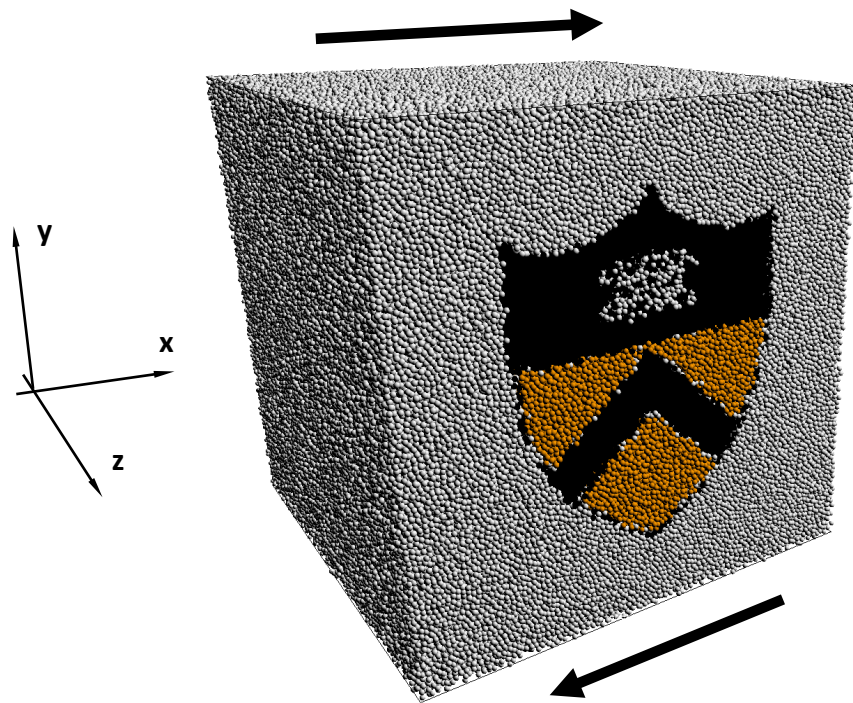




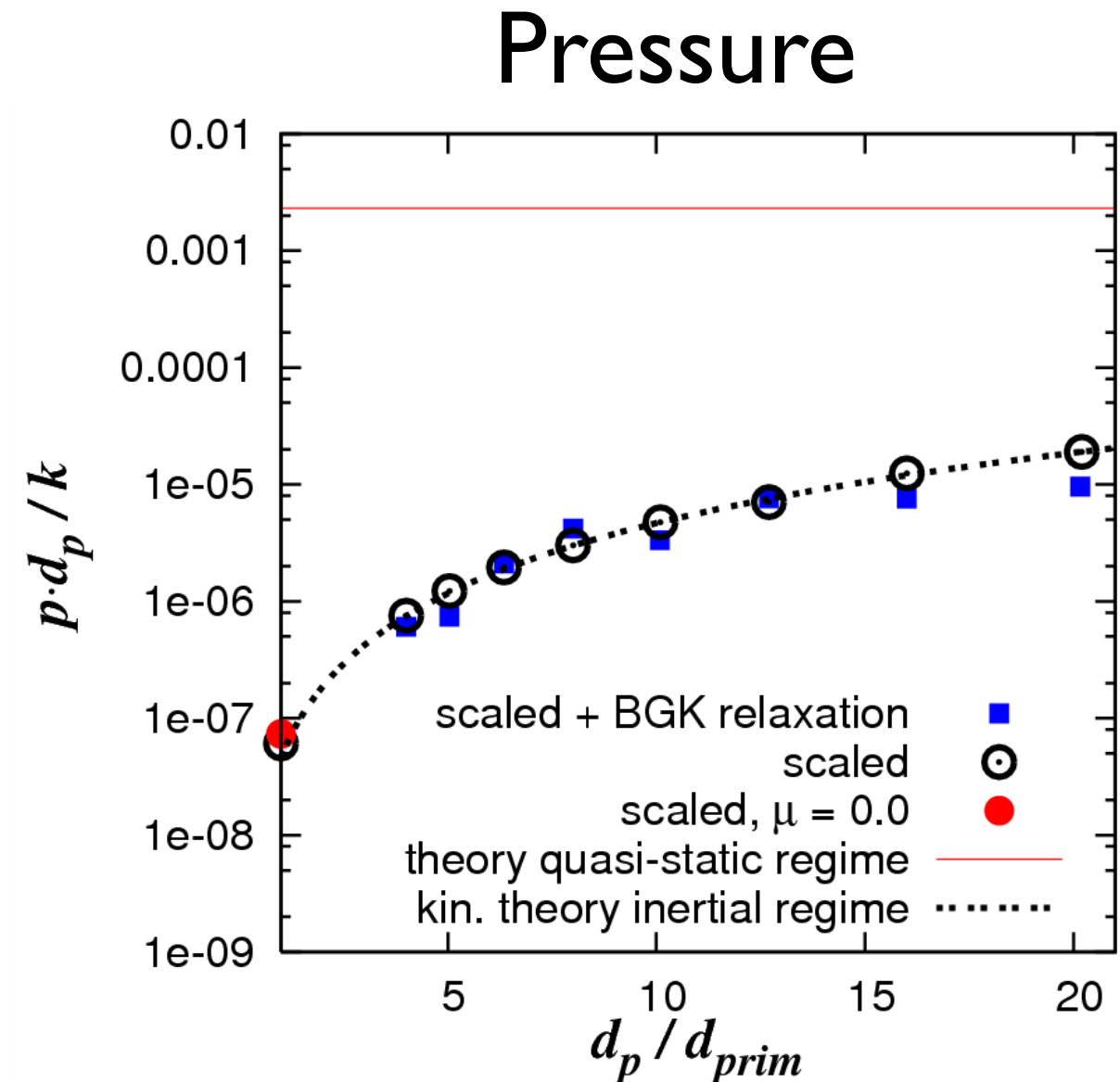
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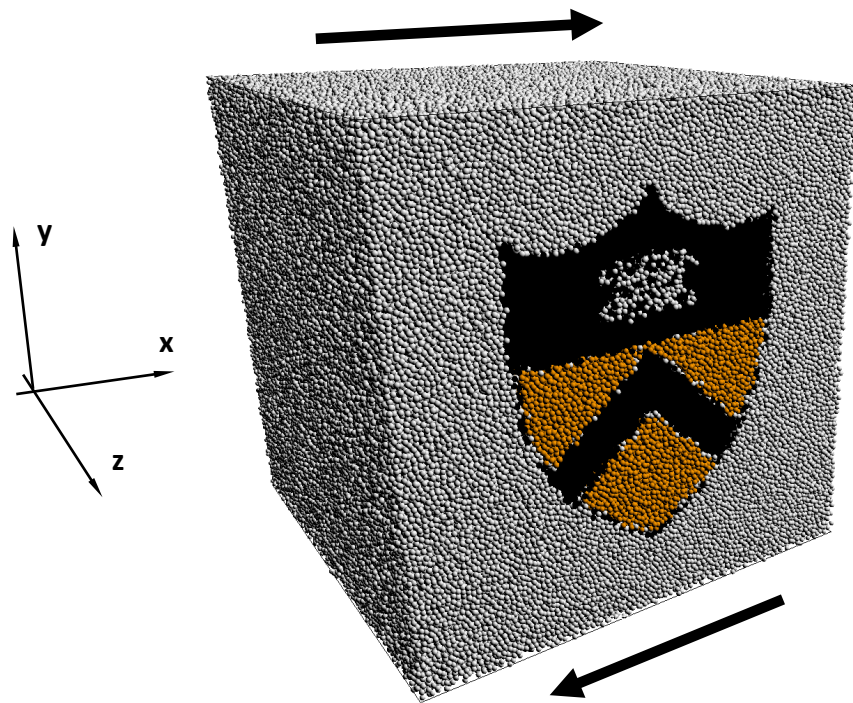
- In DPM with parcel collision tracking, gross overprediction of stresses cannot be avoided, even if we implement BGK-like damping.



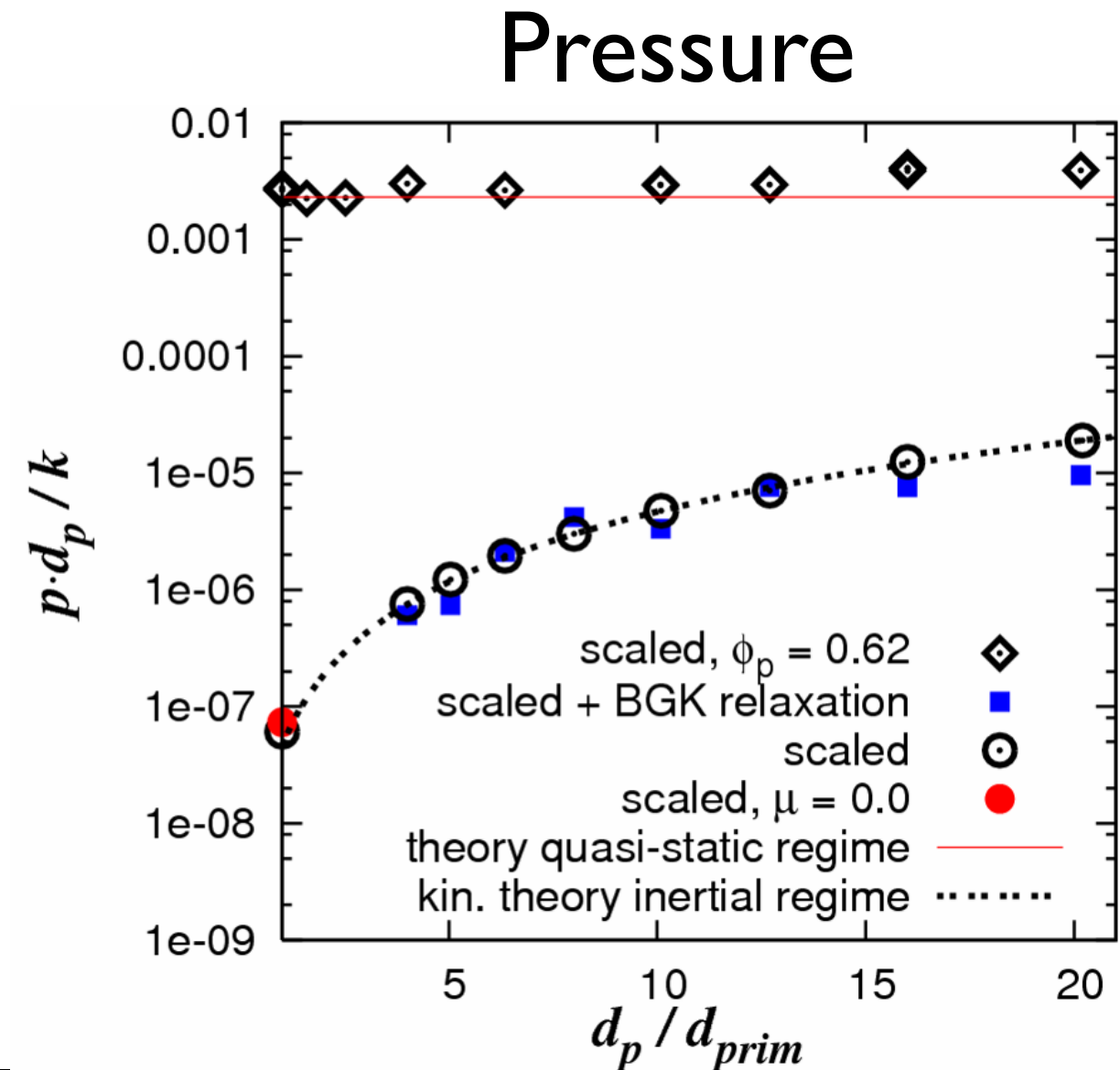
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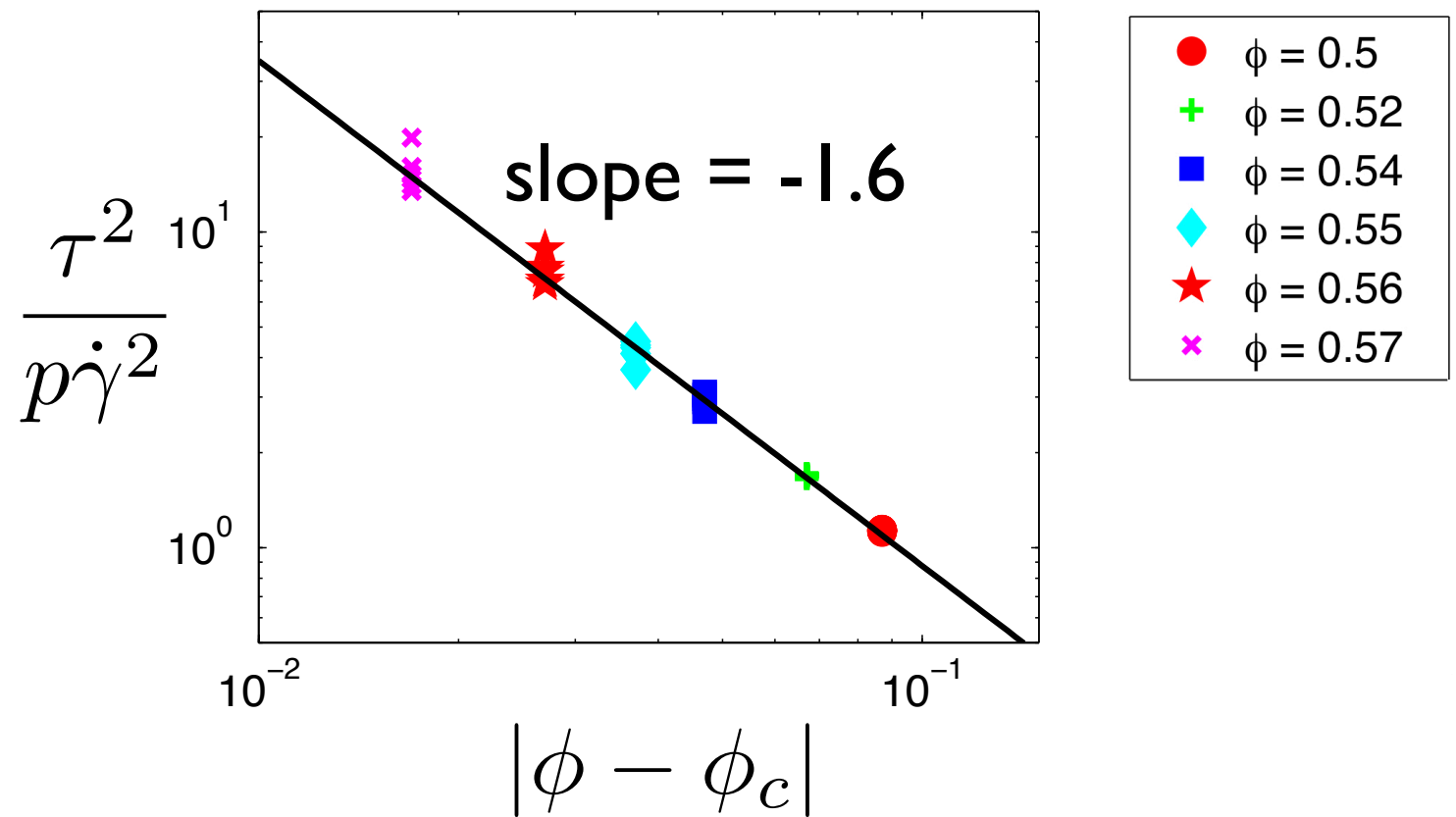
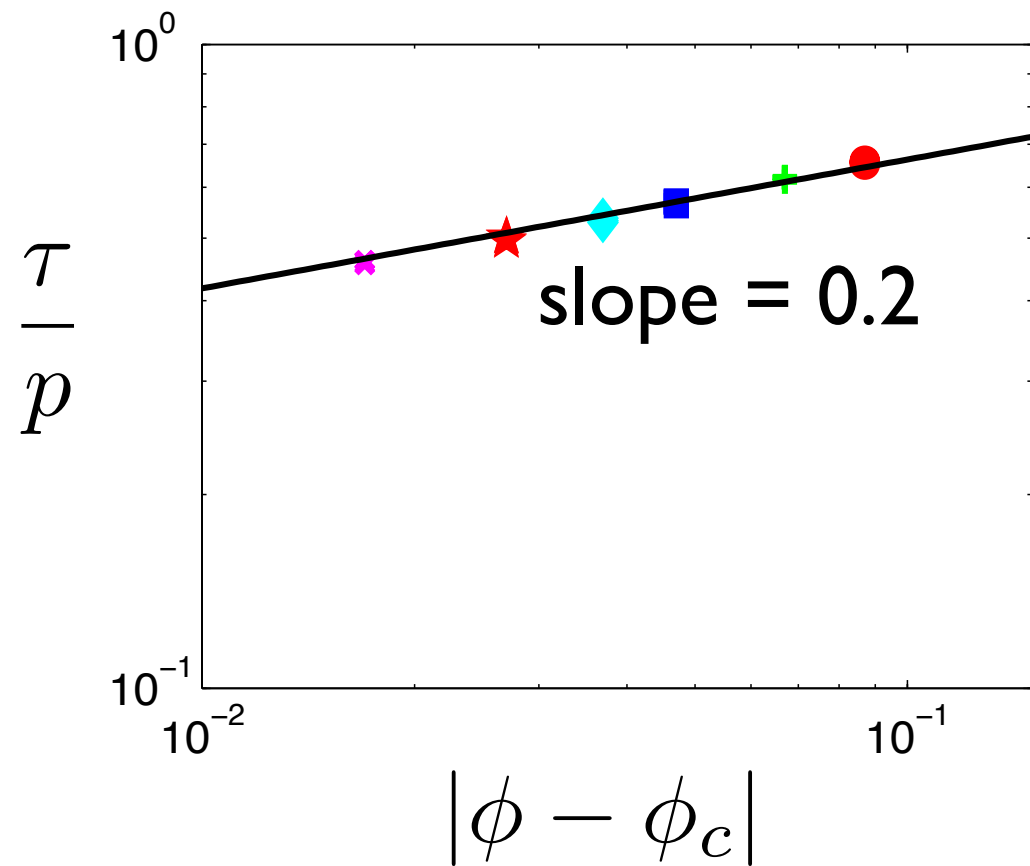


# Work in progress

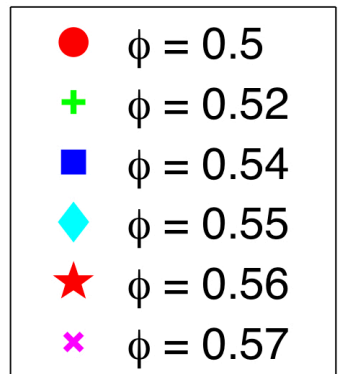
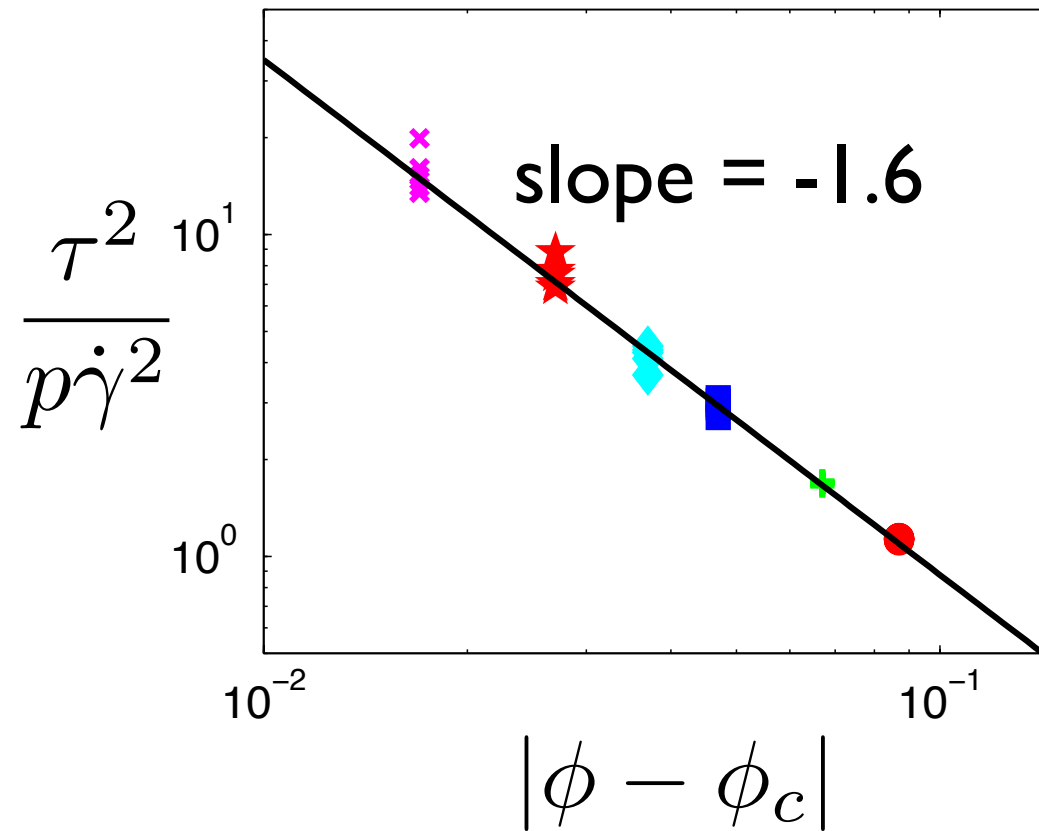
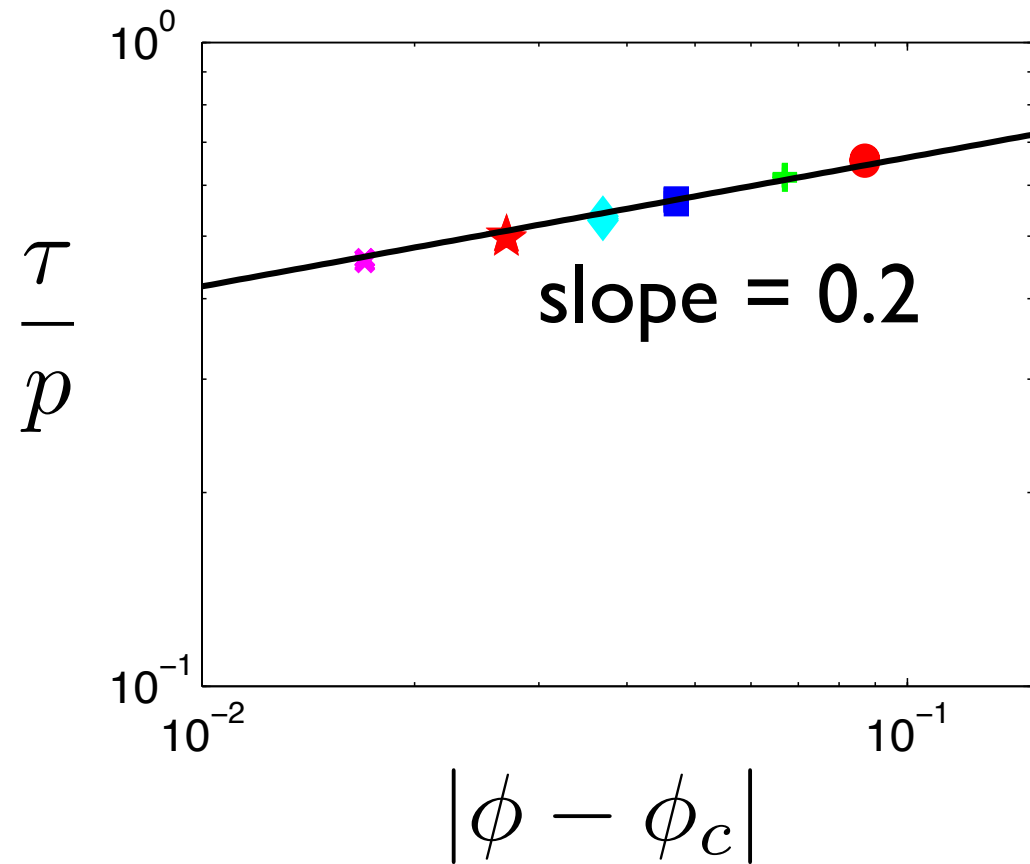


- Connect rheological behavior to changing microstructure.
- Refine the model for flows near bounding walls.
- Apply the model to
  - ▶ hopper and bin flows
  - ▶ shear bands

# Stress scalings for frictional particles



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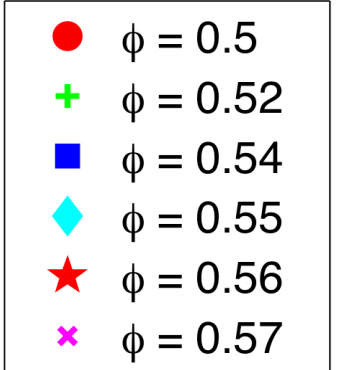
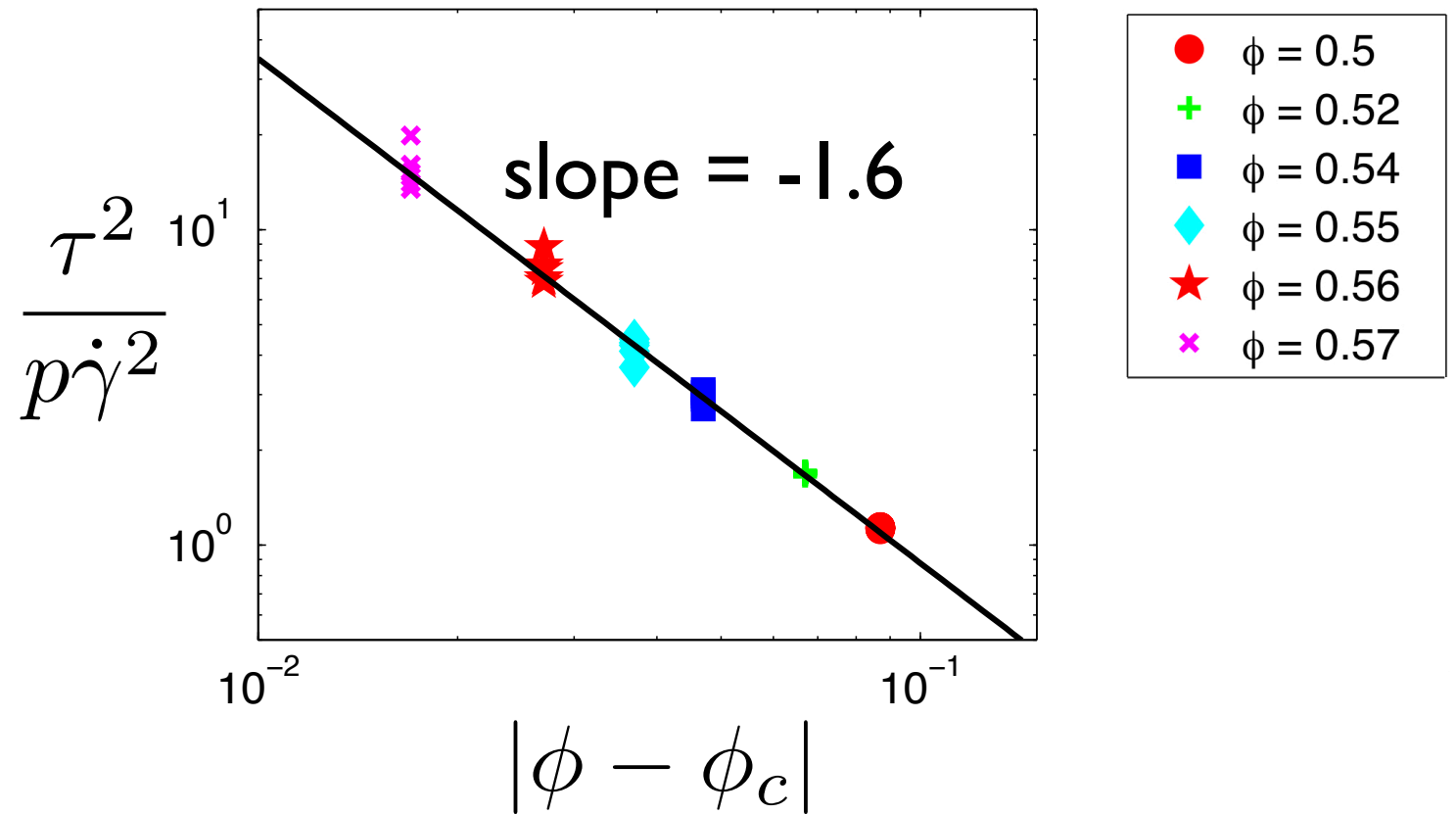
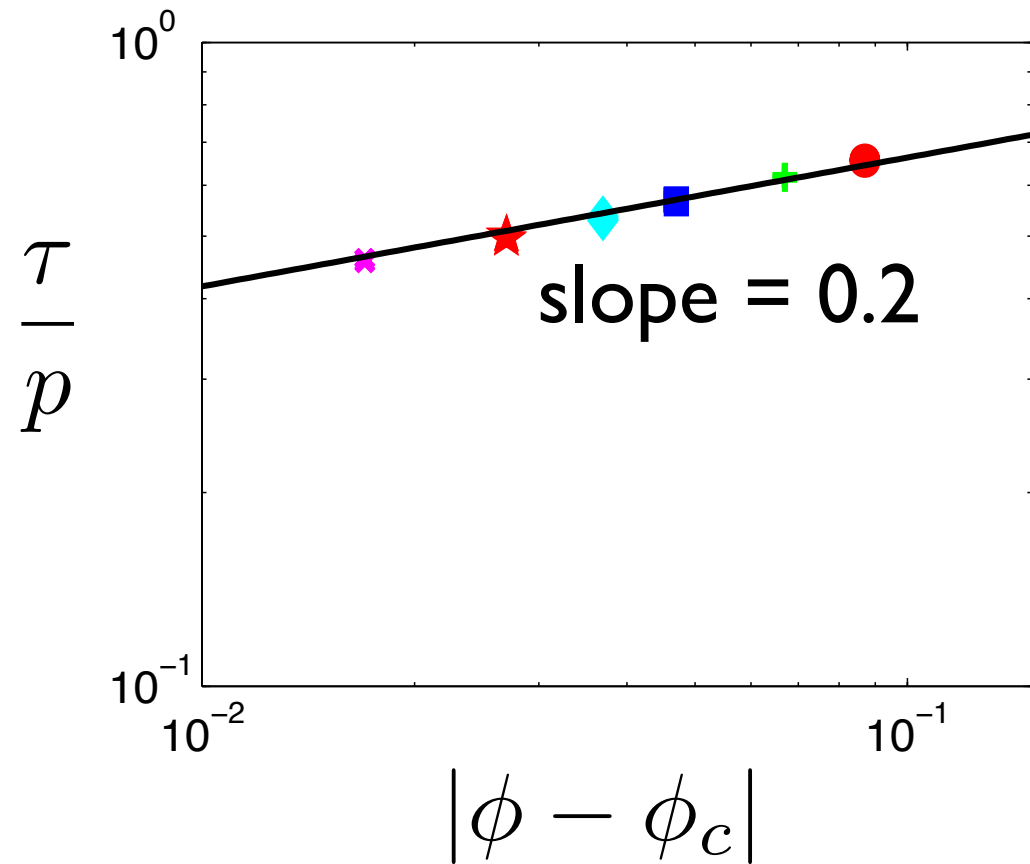


- From inertial regime data:

$$\frac{\tau}{p} \sim |\phi - \phi_c|^{0.2} \sim \frac{|\phi - \phi_c|^{a_2 - 2b_2}}{|\phi - \phi_c|^{a_1 - 2b_1}}$$

$$\frac{\tau^2}{p\dot{\gamma}^2} \sim |\phi - \phi_c|^{-1.6} \sim \frac{(|\phi - \phi_c|^{a_2 - 2b_2})^2}{|\phi - \phi_c|^{a_1 - 2b_1}}$$

# Stress scalings for frictional particles



- From inertial regime data:

$$\frac{\tau}{p} \sim |\phi - \phi_c|^{0.2} \sim \frac{|\phi - \phi_c|^{a_2 - 2b_2}}{|\phi - \phi_c|^{a_1 - 2b_1}}$$

$$\frac{\tau^2}{p\dot{\gamma}^2} \sim |\phi - \phi_c|^{-1.6} \sim \frac{(|\phi - \phi_c|^{a_2 - 2b_2})^2}{|\phi - \phi_c|^{a_1 - 2b_1}} \Rightarrow \begin{aligned} b_1 &= 1.5 \\ b_2 &= 1.4 \end{aligned}$$

# Discrete element method

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# Discrete element method

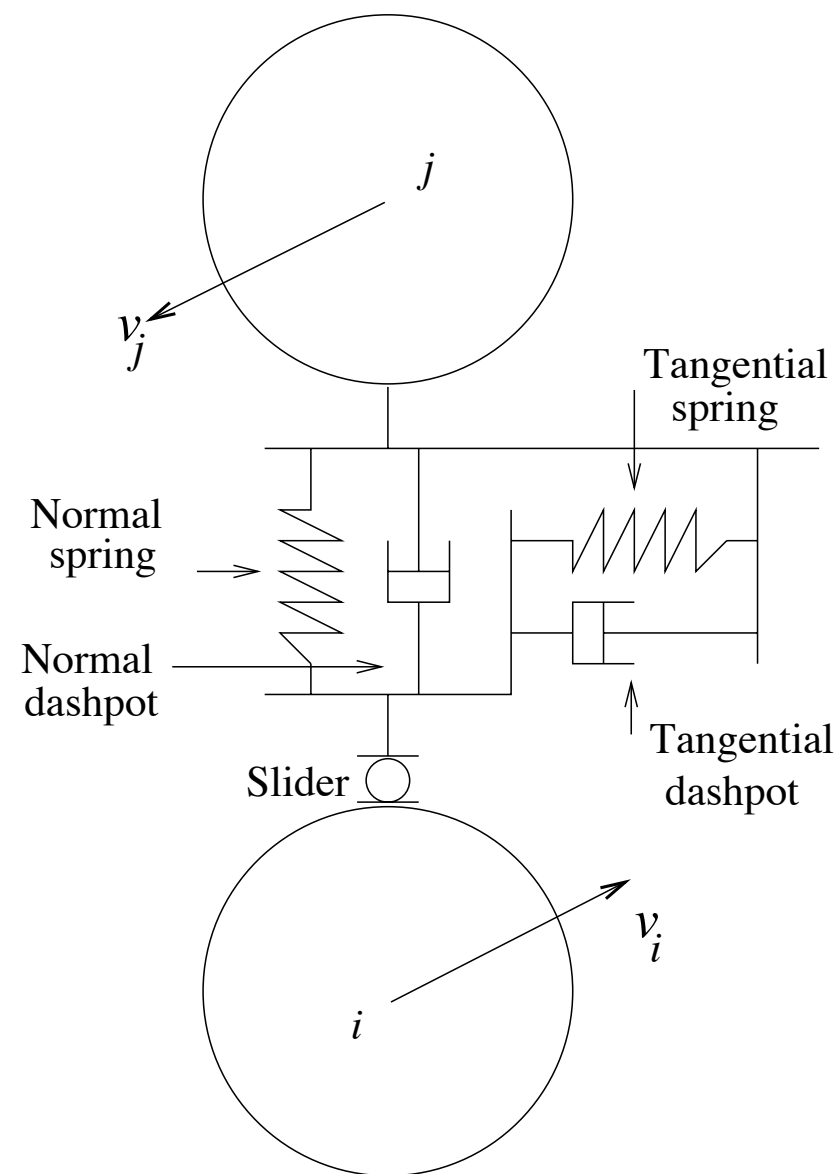


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# Discrete element method



- Numerically integrate equations of motion for every particle
- Short range ( $r_c=d$ ) repulsive force based on spring-dashpot model



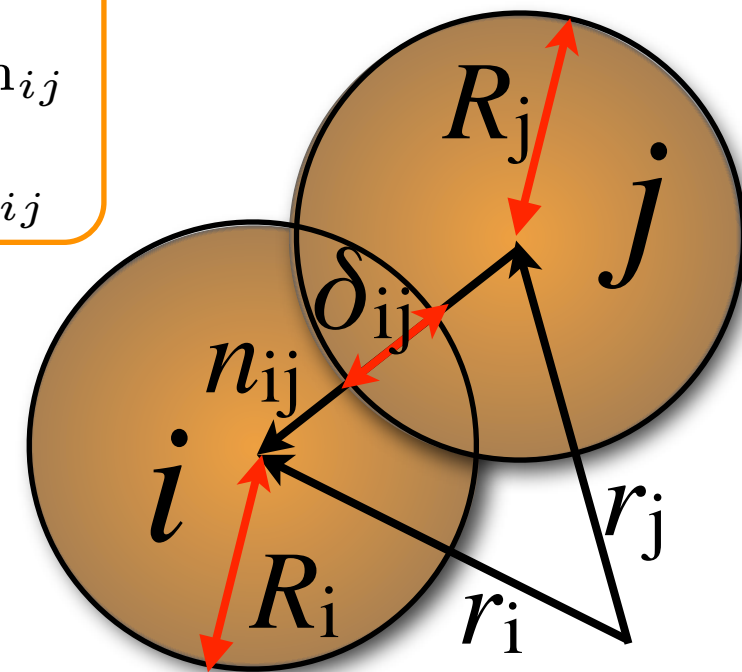
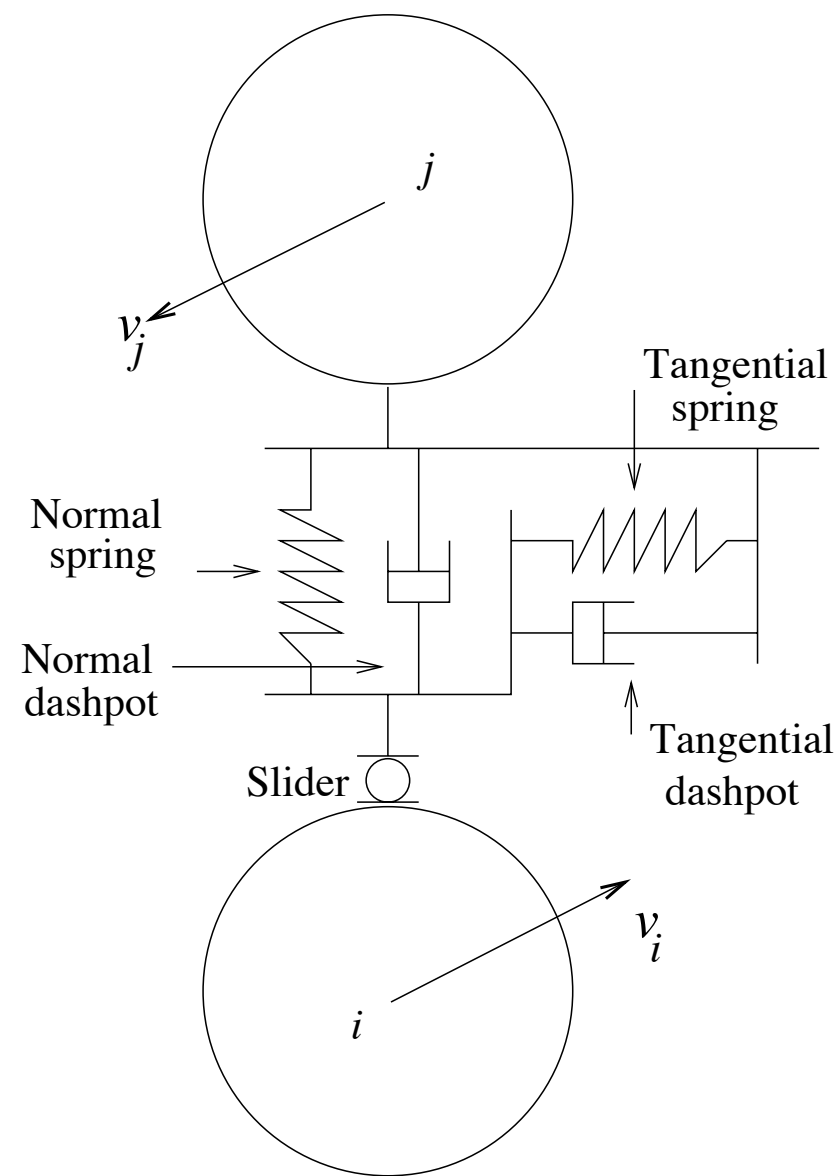
# Discrete element method

- Numerically integrate equations of motion for every particle
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Linear (Hookean) model:

$$\mathbf{F}_{n_{ij}} = k_n \delta_{ij} \mathbf{n}_{ij} - \gamma_n m^* \mathbf{v}_{n_{ij}}$$

$$\mathbf{F}_{t_{ij}} = -k_t \mathbf{u}_{t_{ij}} - \gamma_t m^* \mathbf{v}_{t_{ij}}$$





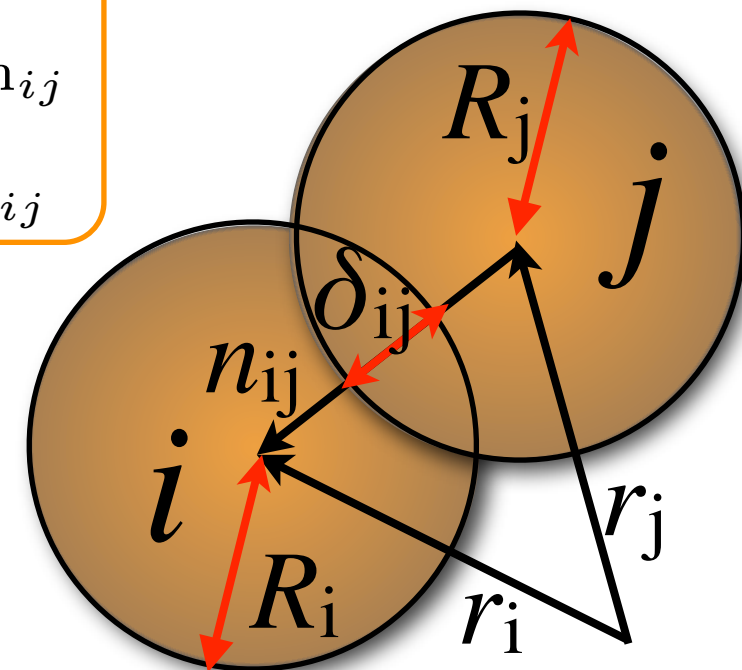
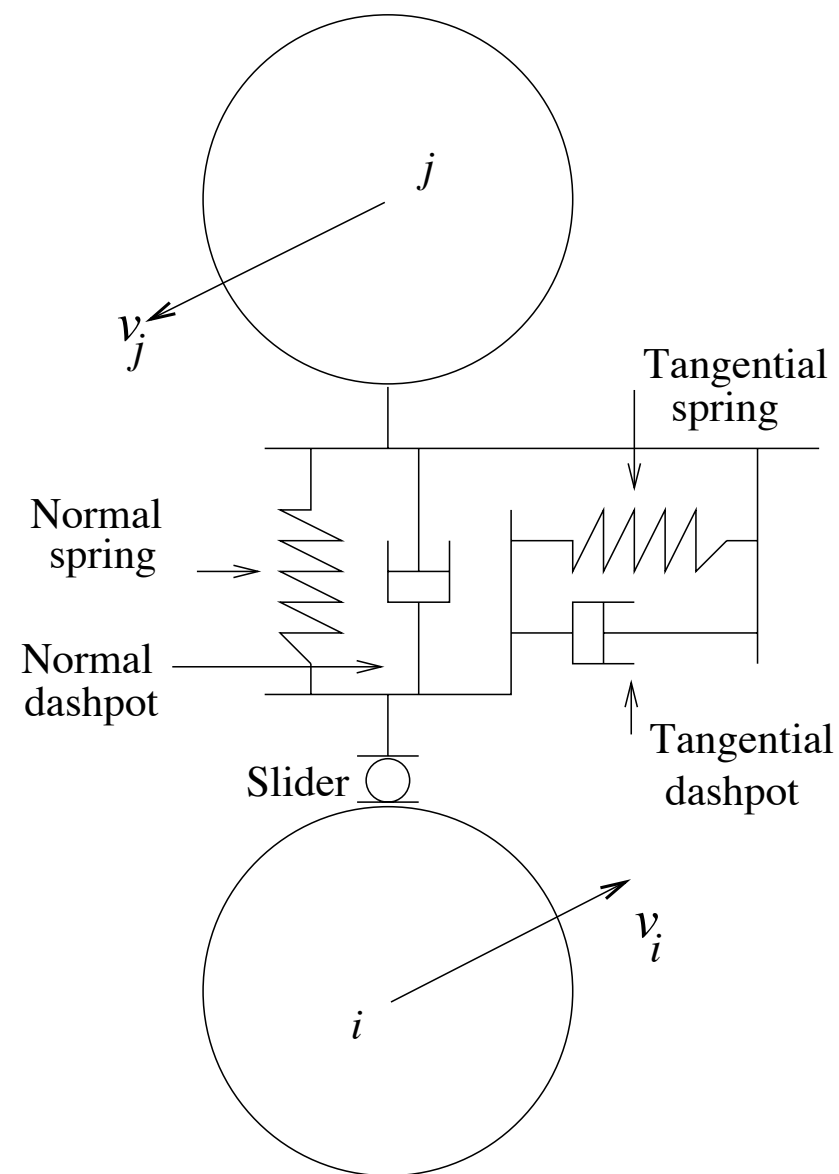
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Non-linear (Hertzian) model:

$$\mathbf{F}_{ij\text{HZ}} = \sqrt{\delta_{ij} R^*} \mathbf{F}_{ij\text{HK}} \quad R^* = \frac{R_i R_j}{R_i + R_j}$$

# Stress and microstructure



● Stress  $\sigma = \frac{1}{V} \sum_i^N \left[ \sum_{j, j \neq i} \frac{1}{2} \mathbf{r}_{ij} \mathbf{F}_{ij} + m_i \mathbf{C}_i \mathbf{C}_i \right]$

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• **Coordination number**: average number of contacting neighbors

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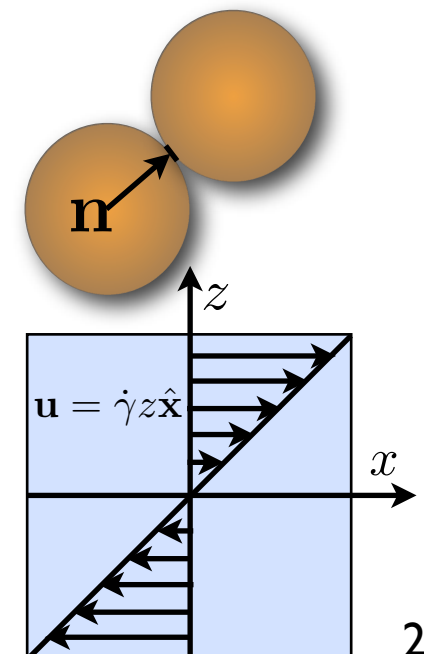
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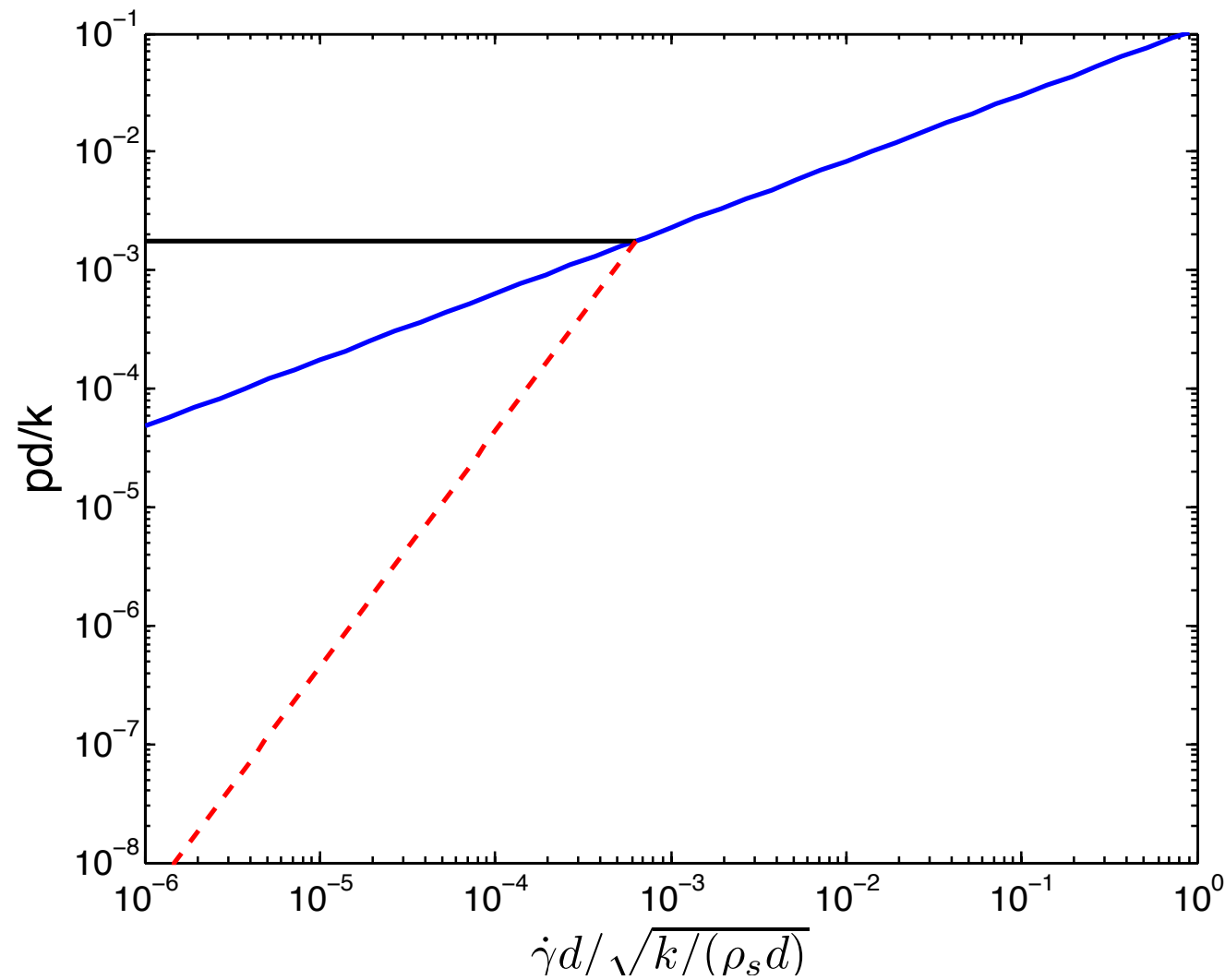
- Fabric tensor**: average of dyadic product of unit contact normals

$$\mathbf{A} = \frac{1}{N_c} \sum_{\alpha=1}^{N_c} \mathbf{n}^\alpha \mathbf{n}^\alpha - \frac{1}{3} \mathbf{I} \quad N_c: \text{number of contacts}$$

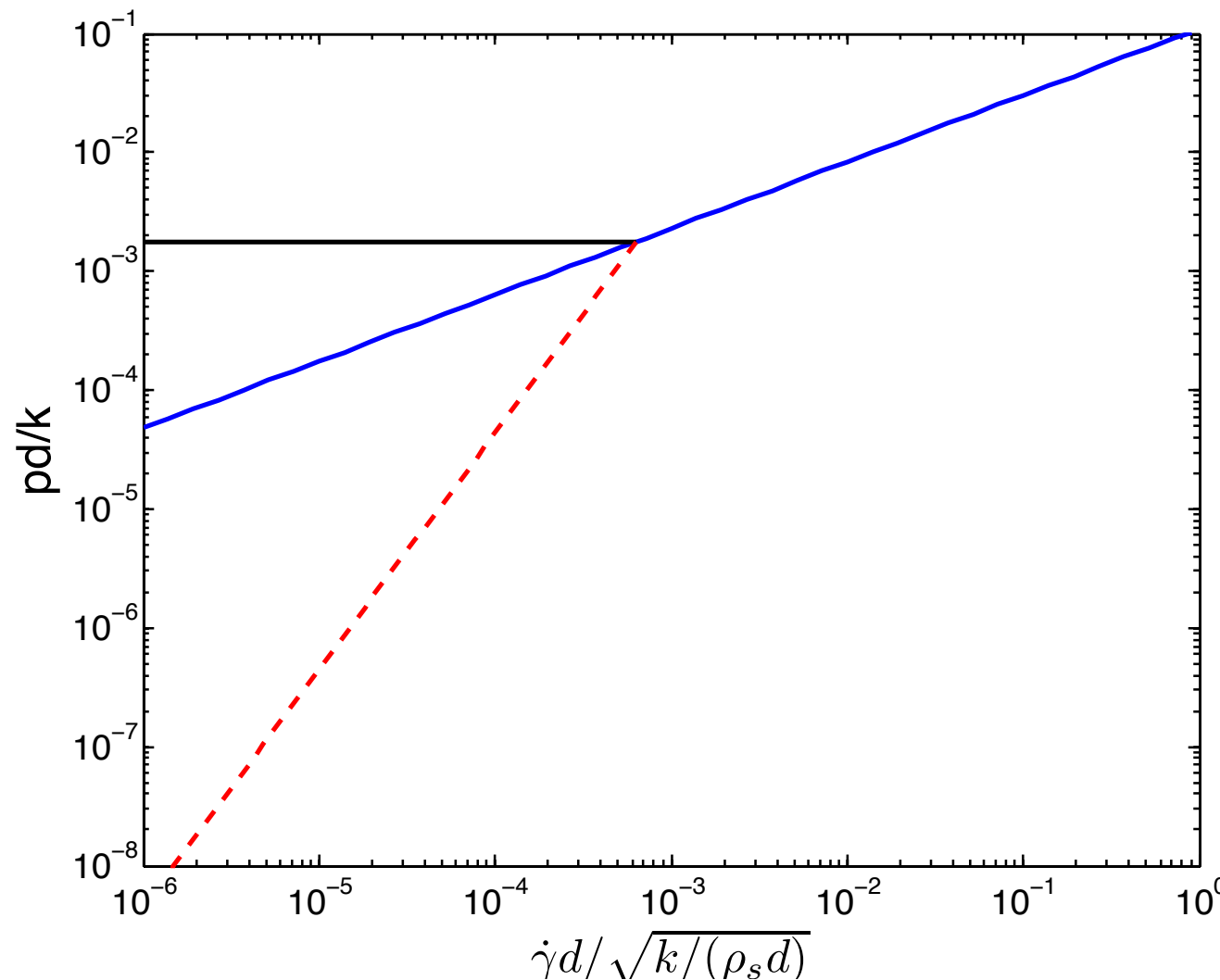
$A_{xz}$  magnitude indicates the microstructure anisotropy strength for simple shear flows; sign indicates the anisotropy direction for simple shear flows.



# Bridging the regimes

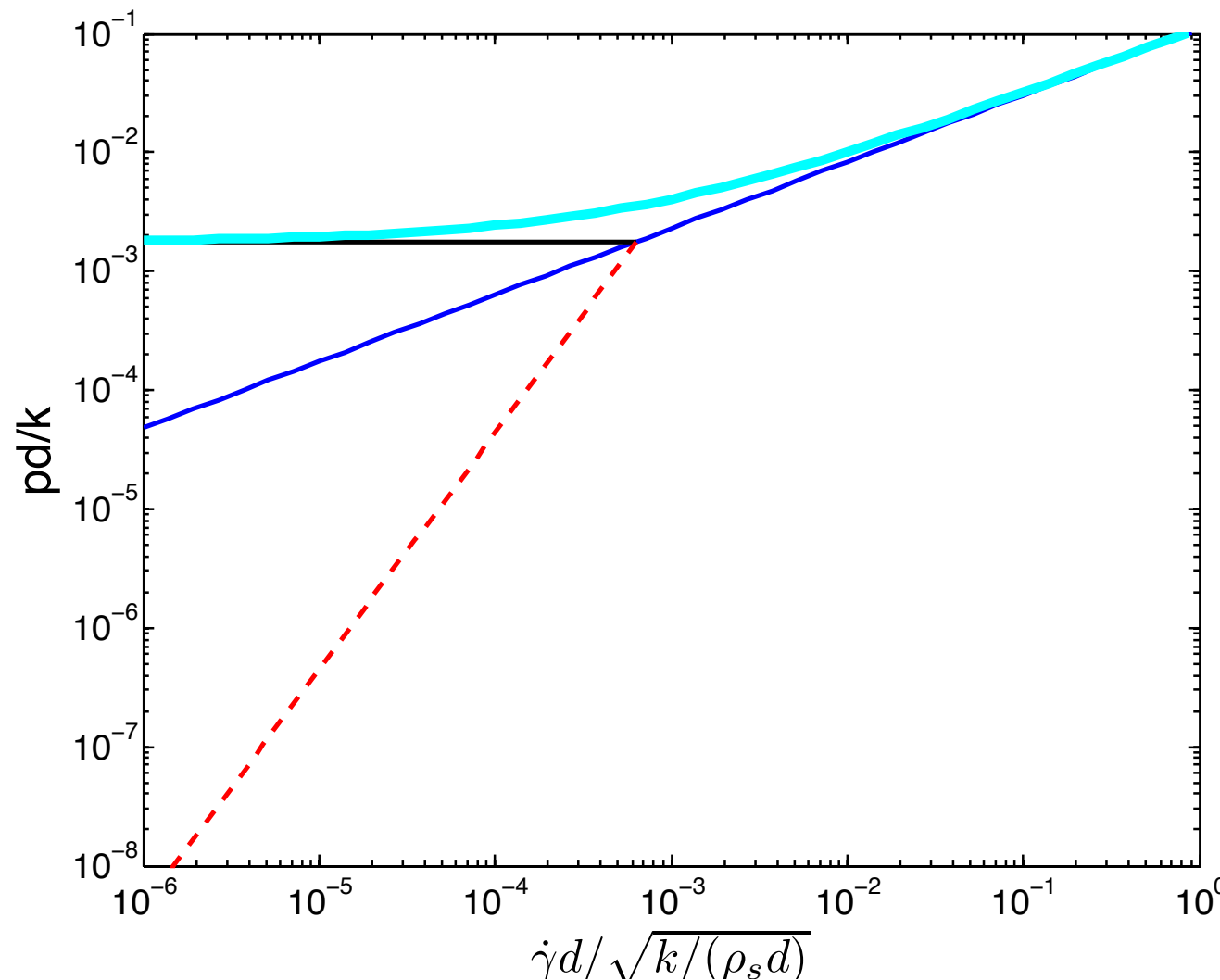


# Bridging the regimes



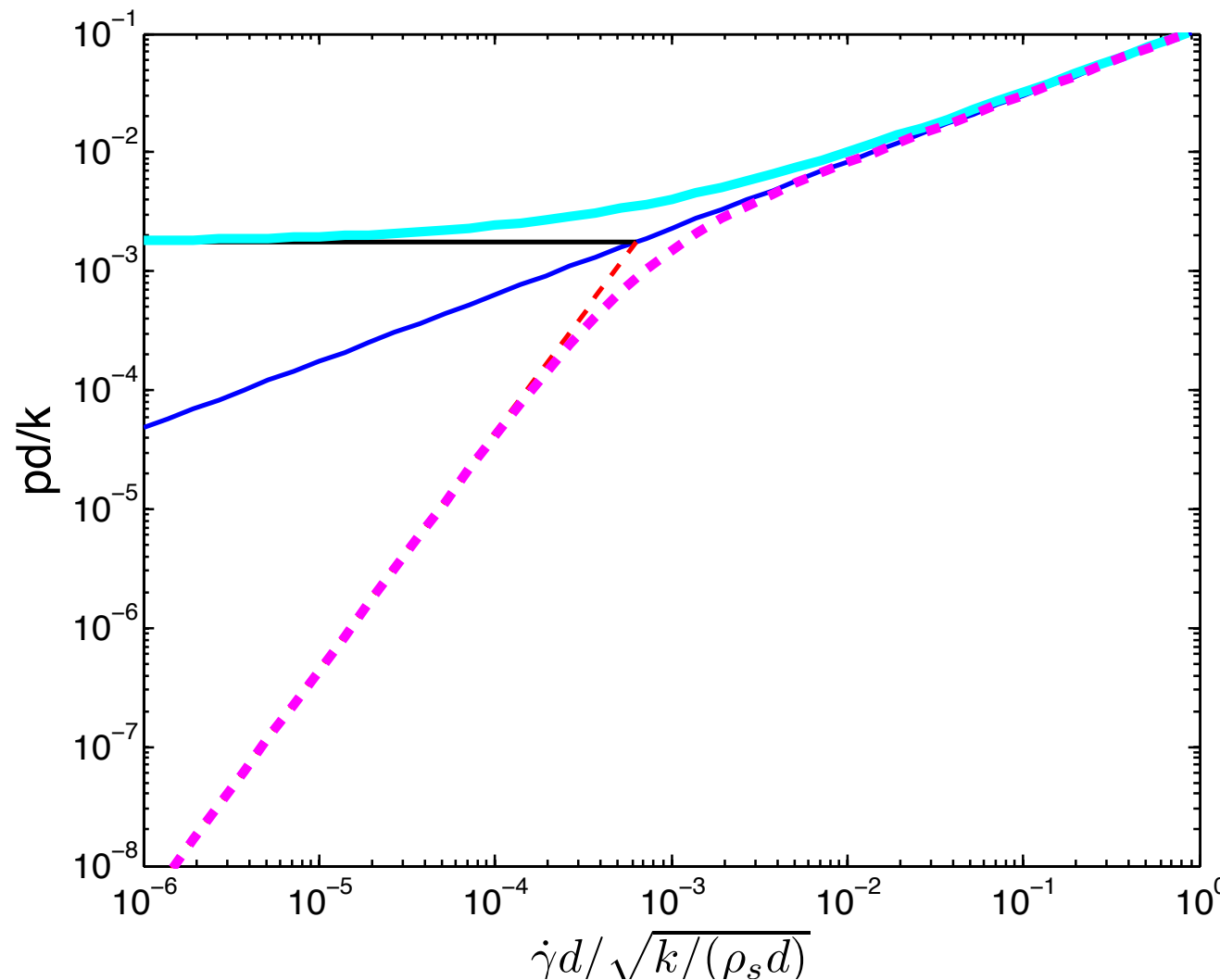
- Regime transitions can be modeled using a simple function to “blend” the asymptotes:  $f = (f_1^m + f_2^m)^{1/m}$ ,  $m = 1$  or  $-1$  for quasi-static and inertial to intermediate transitions, respectively.

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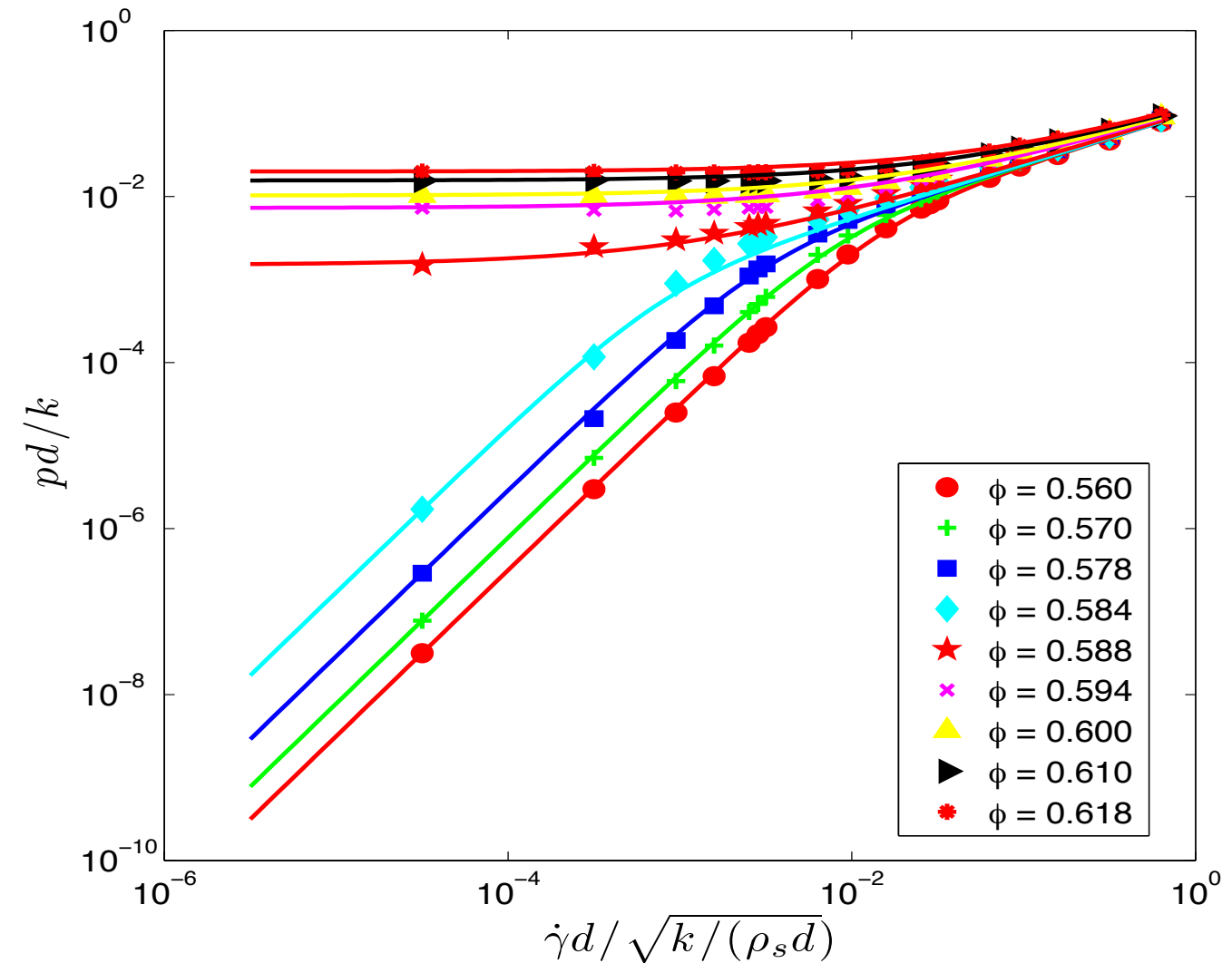
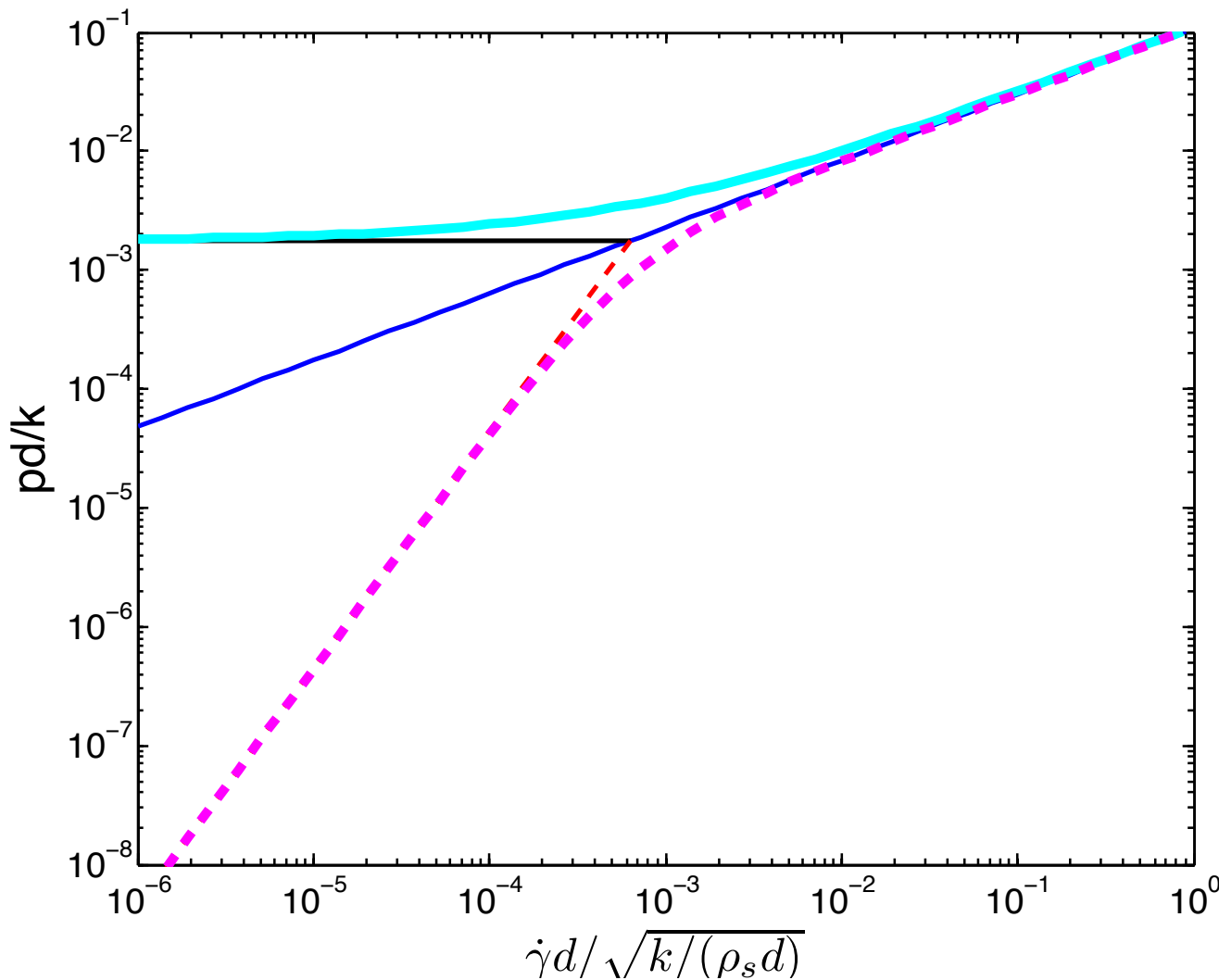
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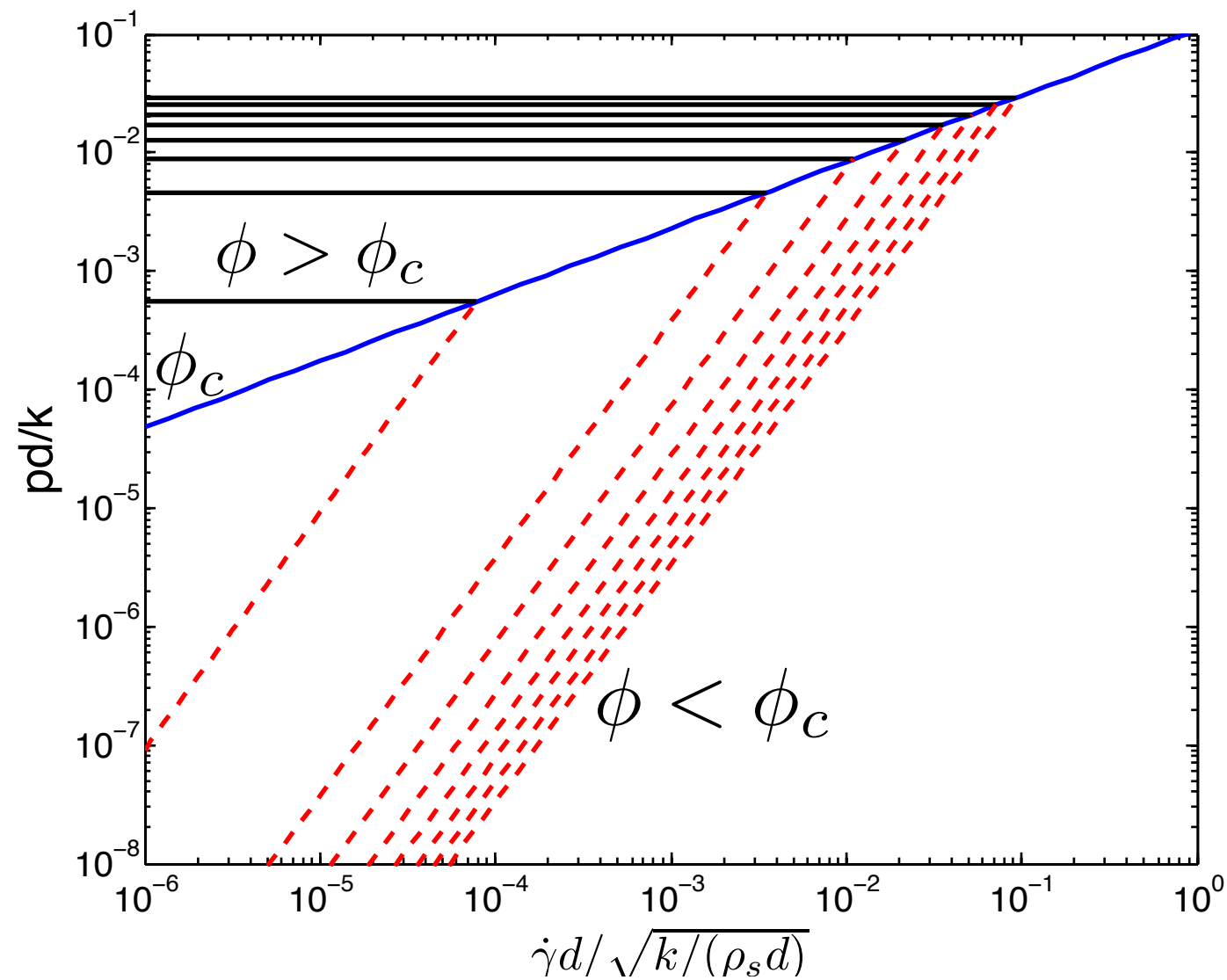


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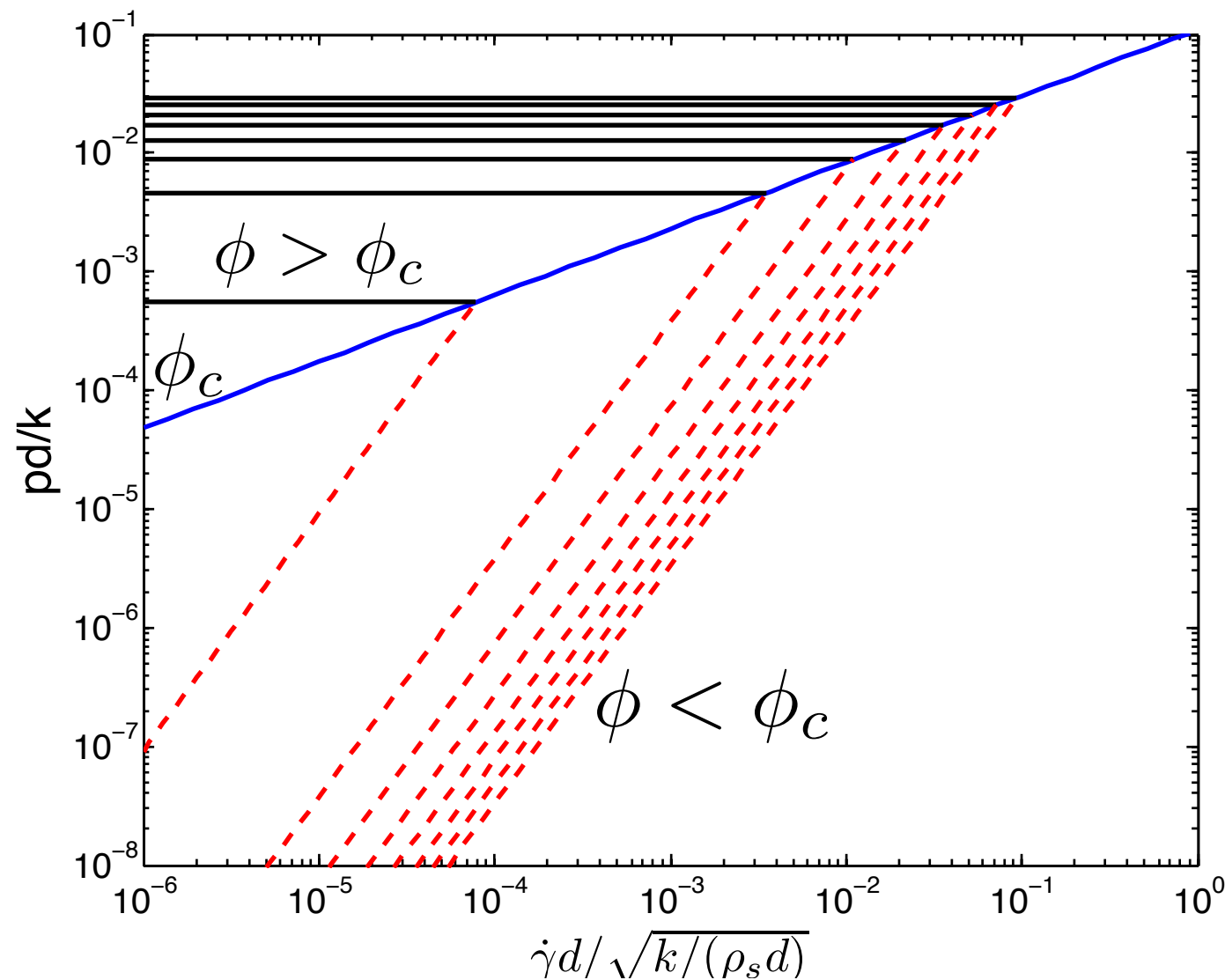


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- Agree reasonably well with DEM data

# Flow regime map

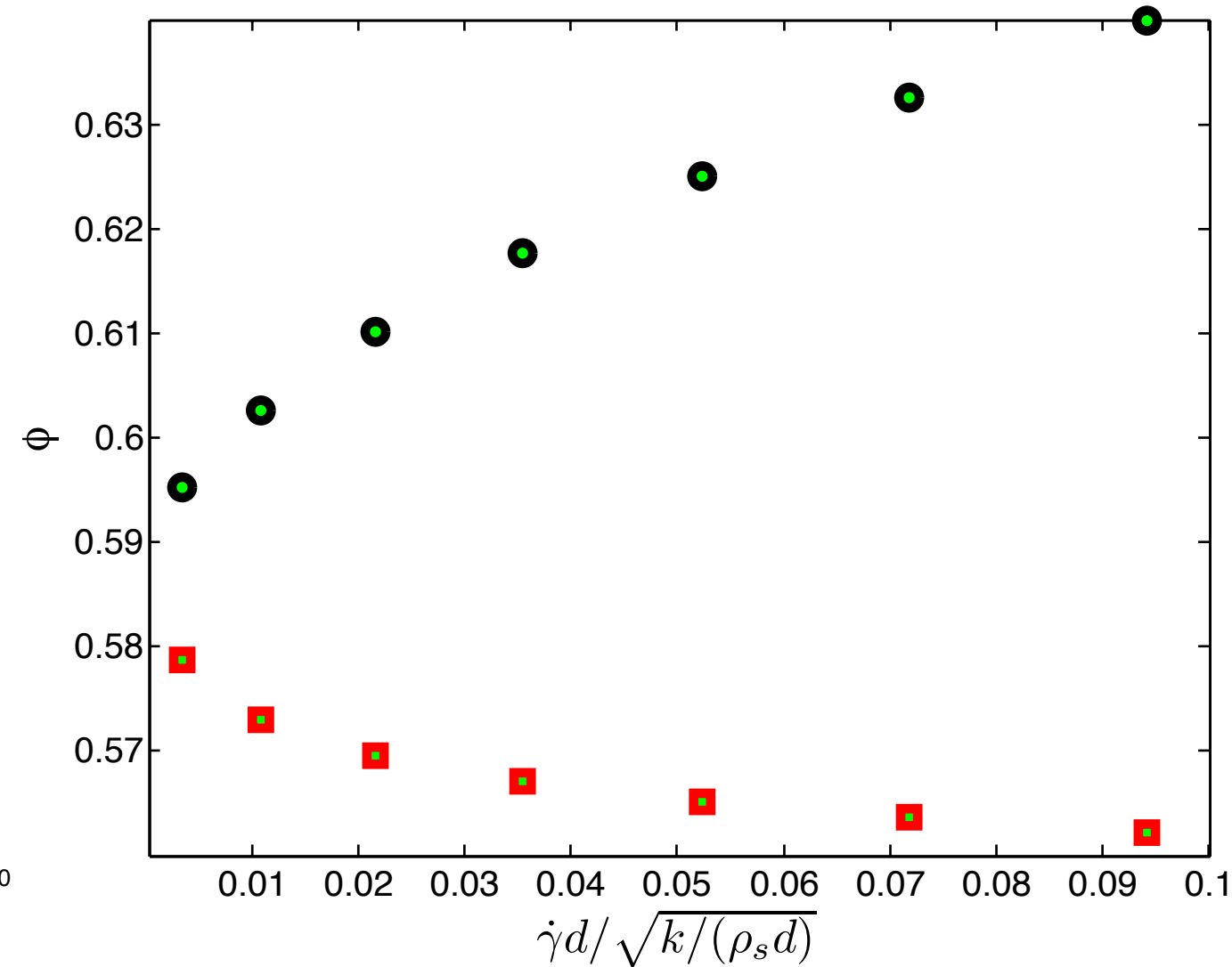
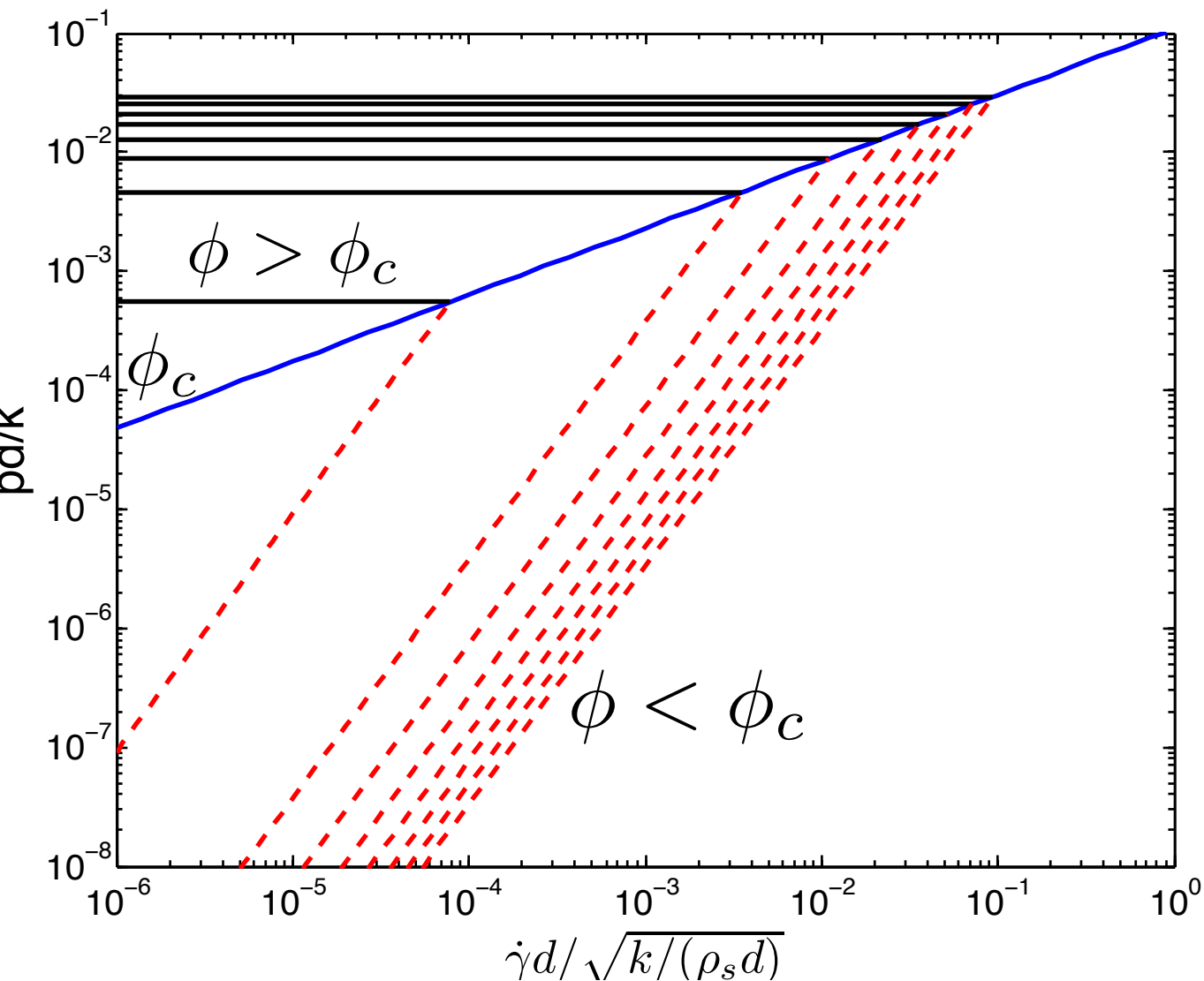


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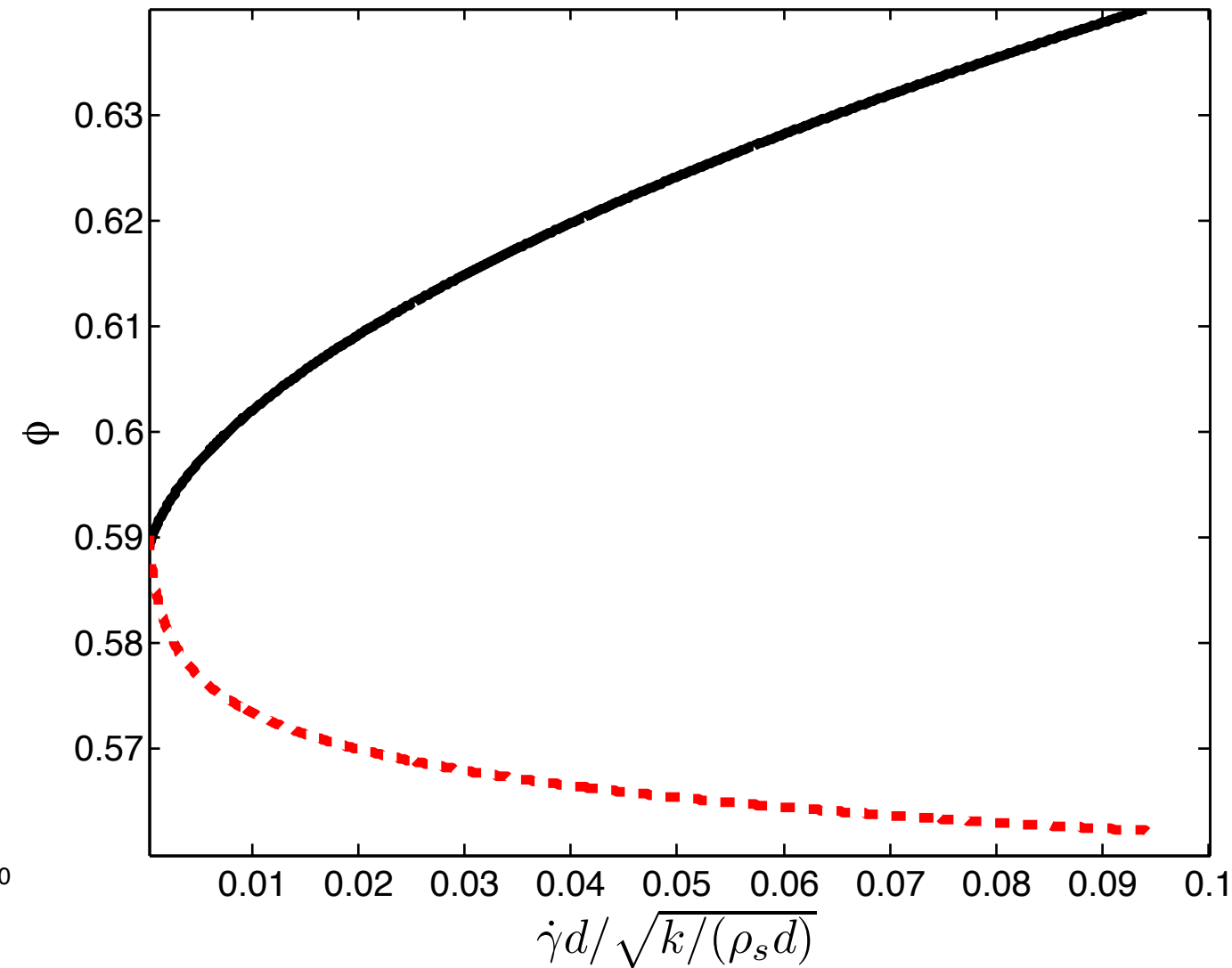
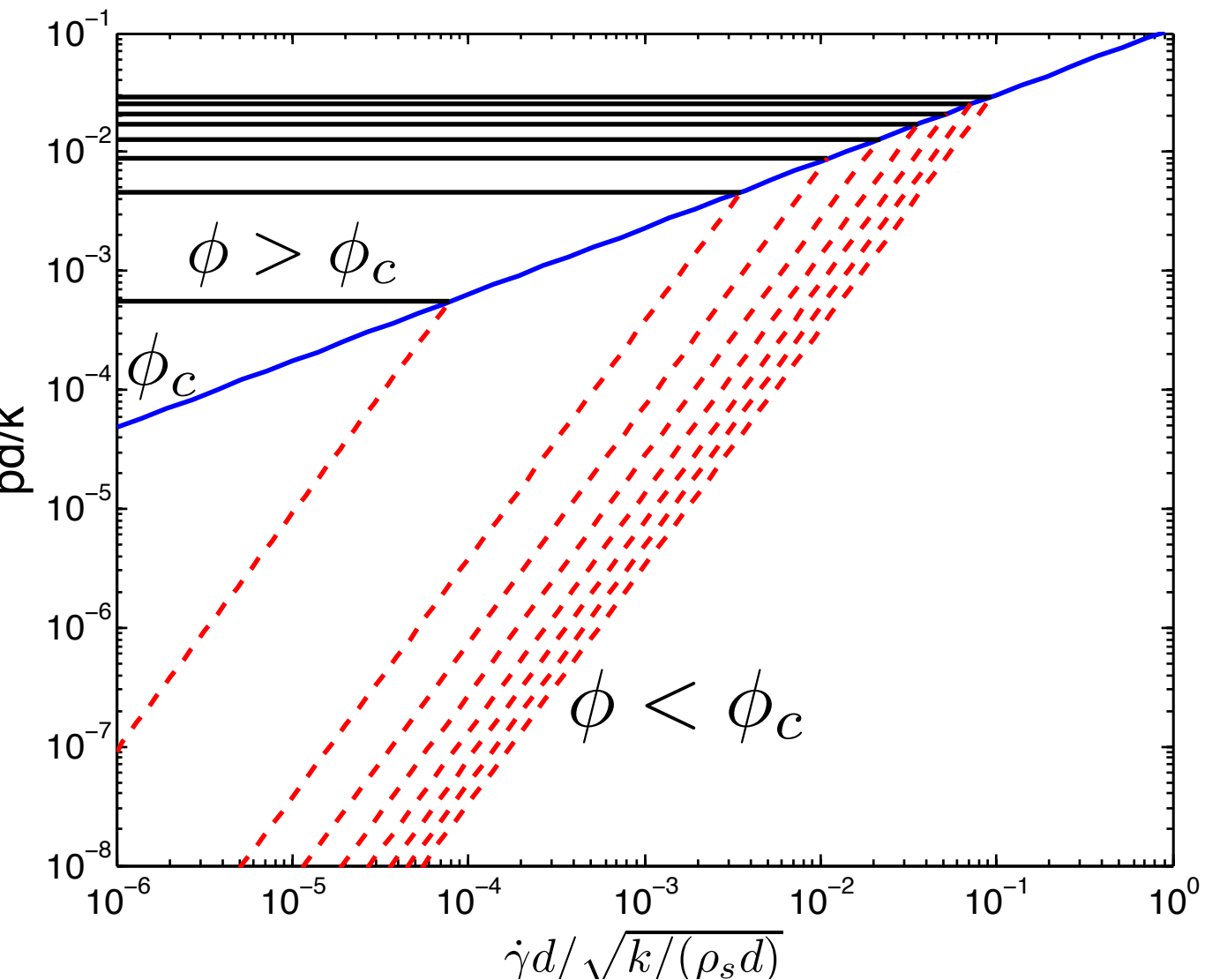
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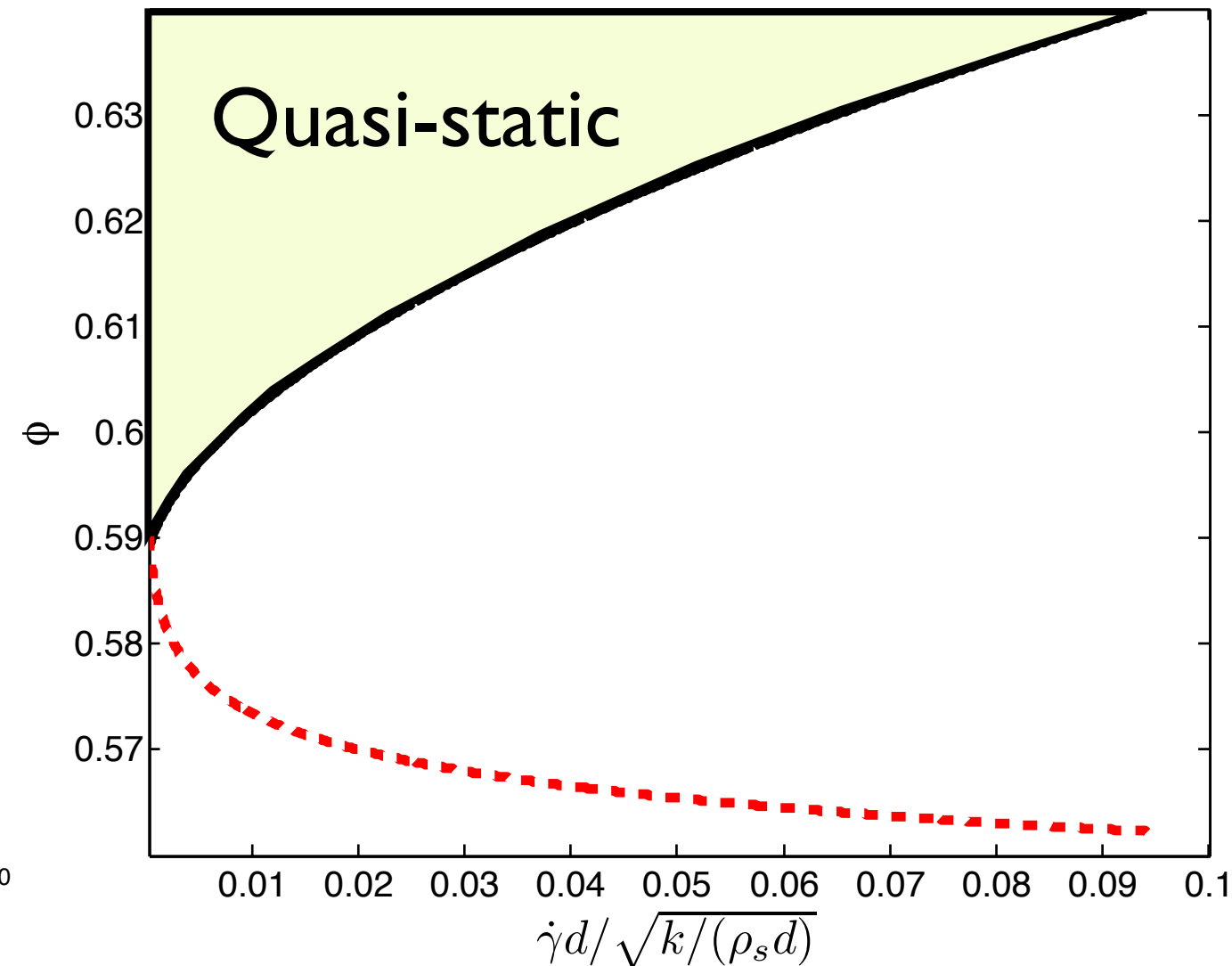
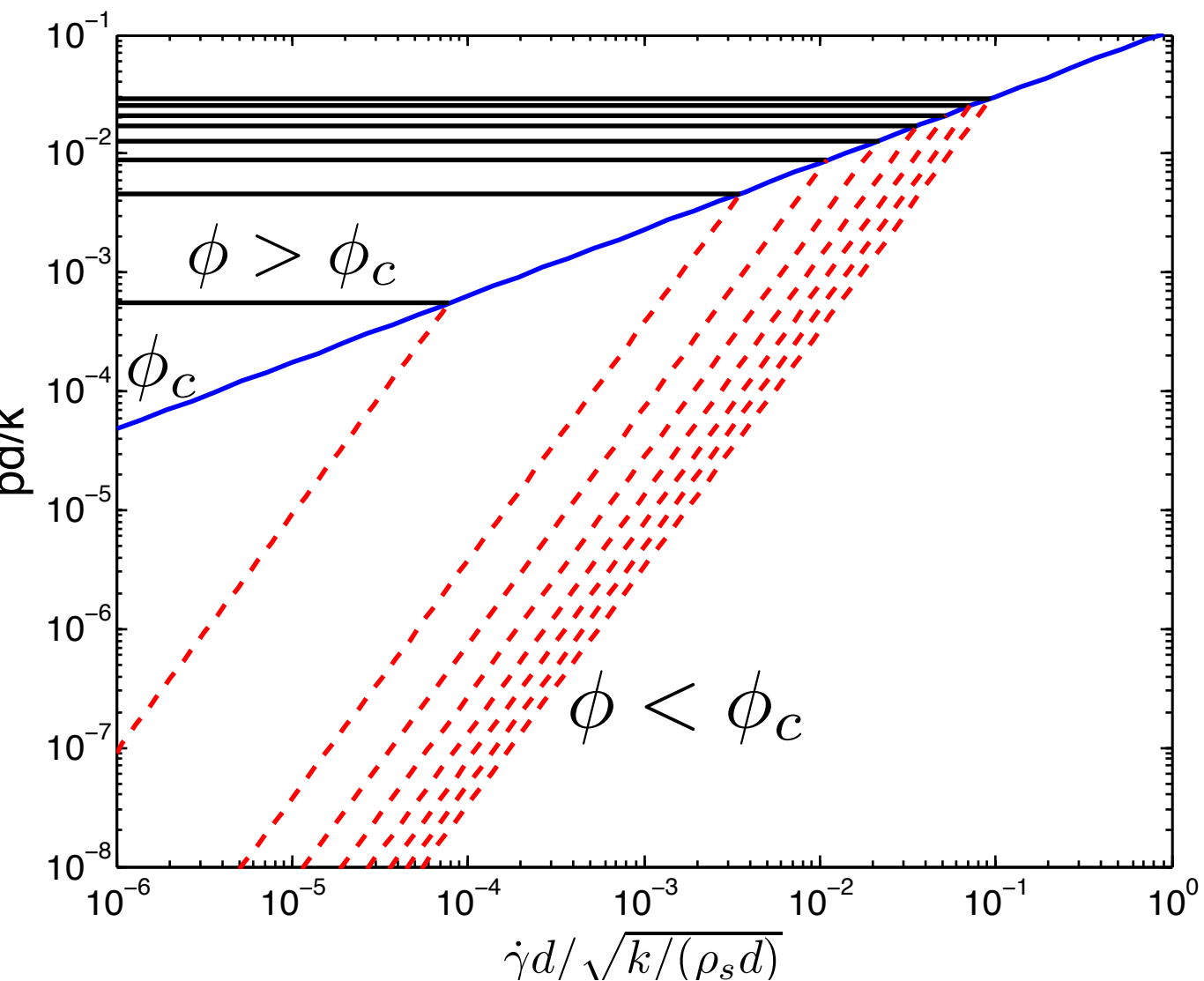
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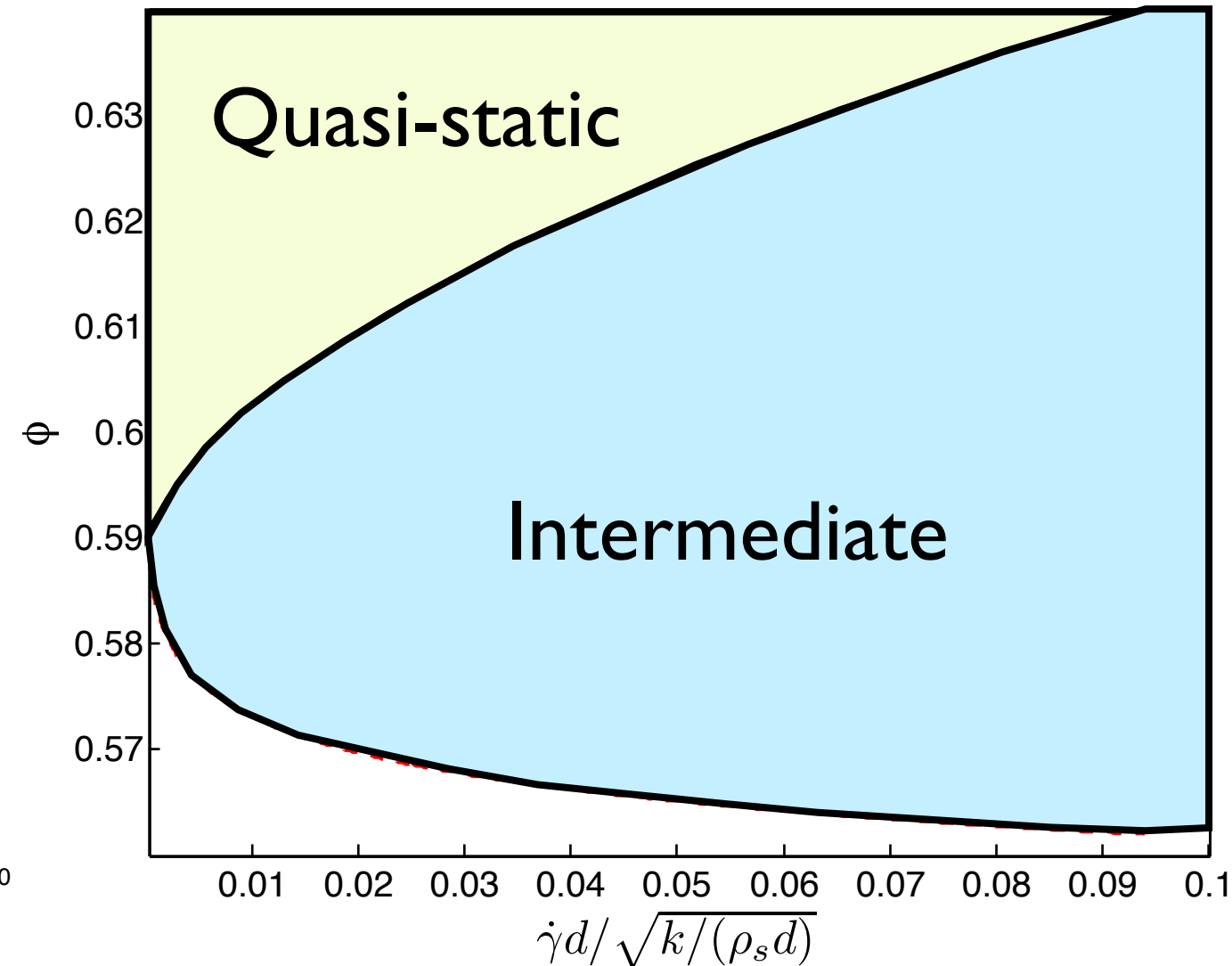
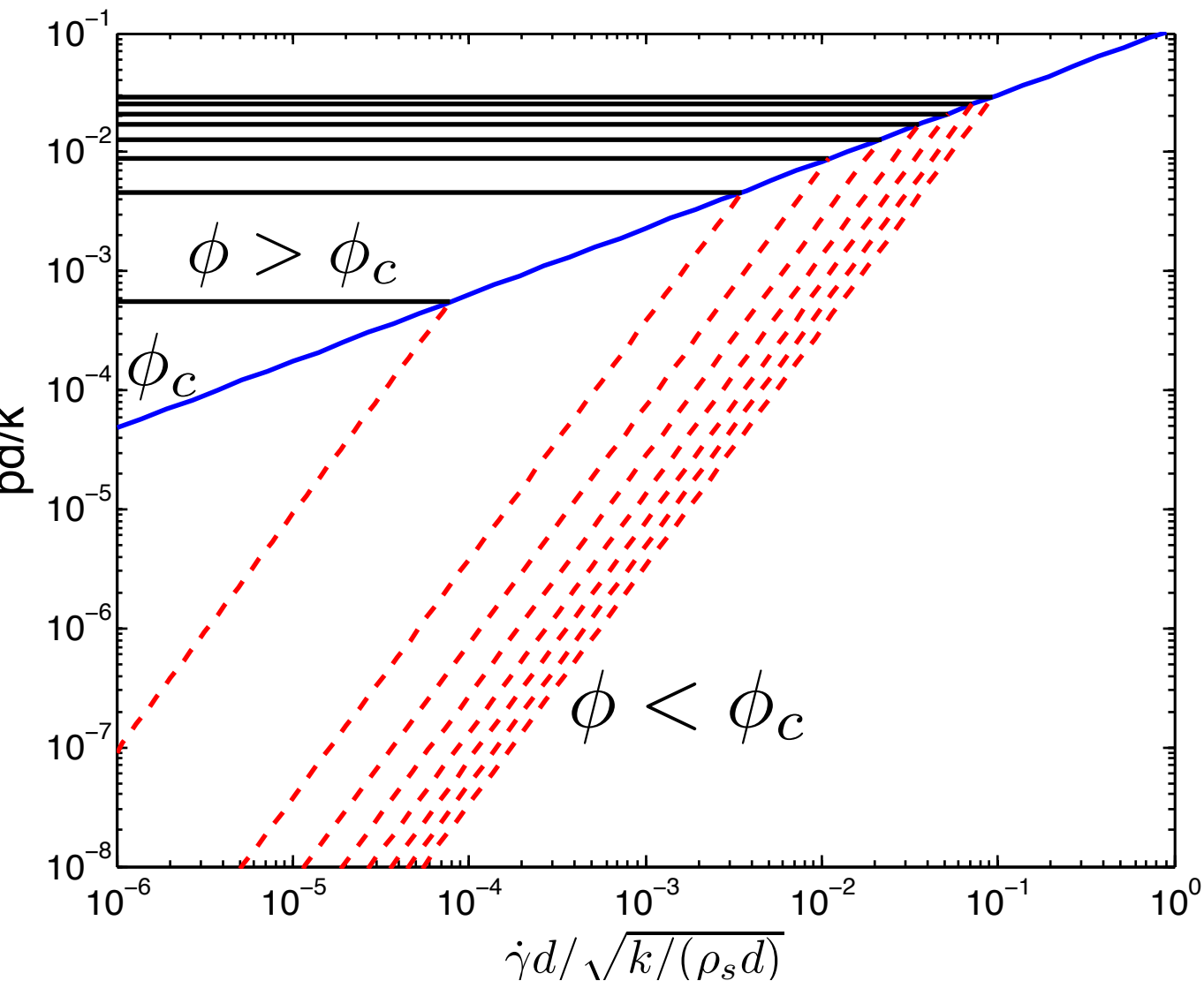
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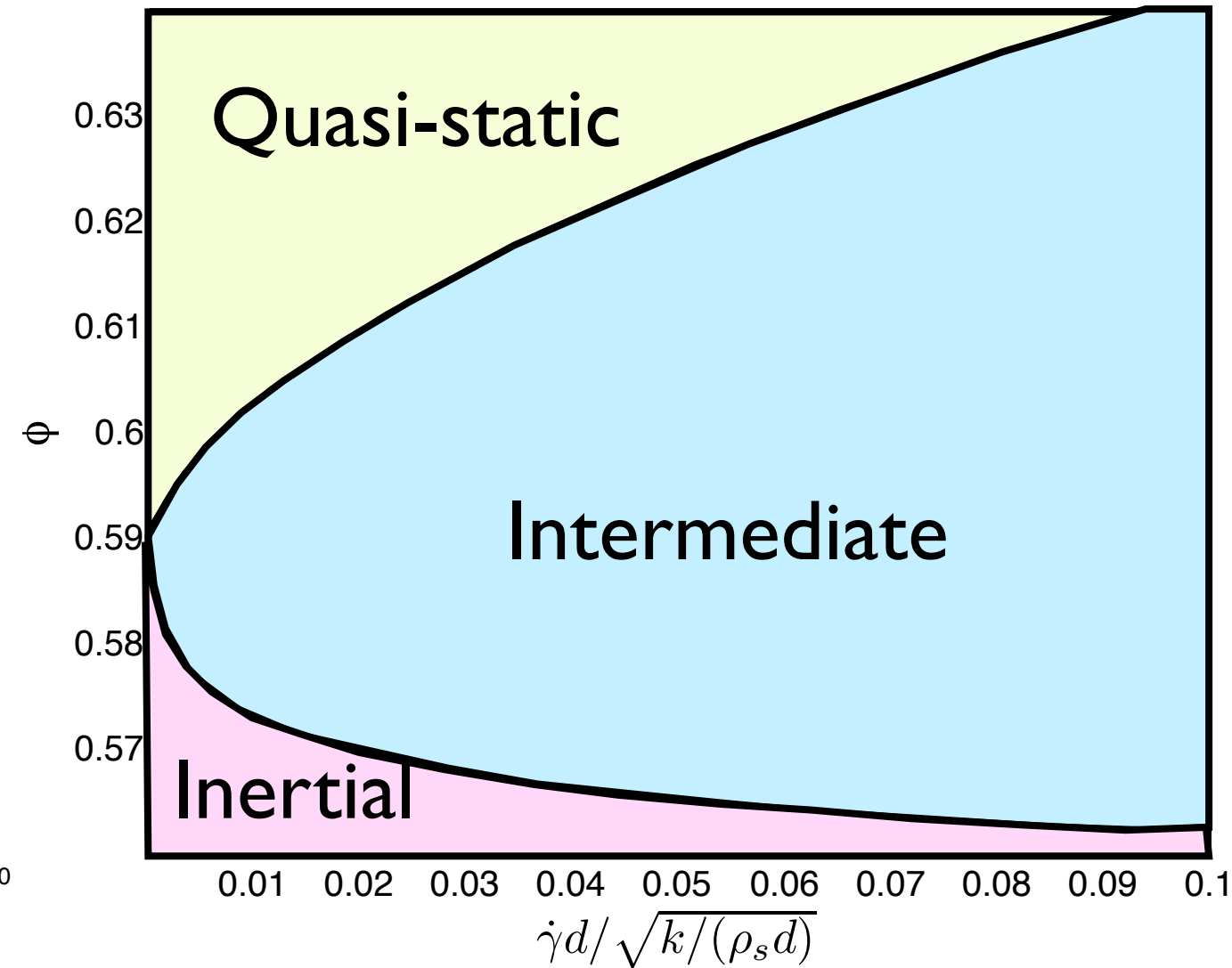
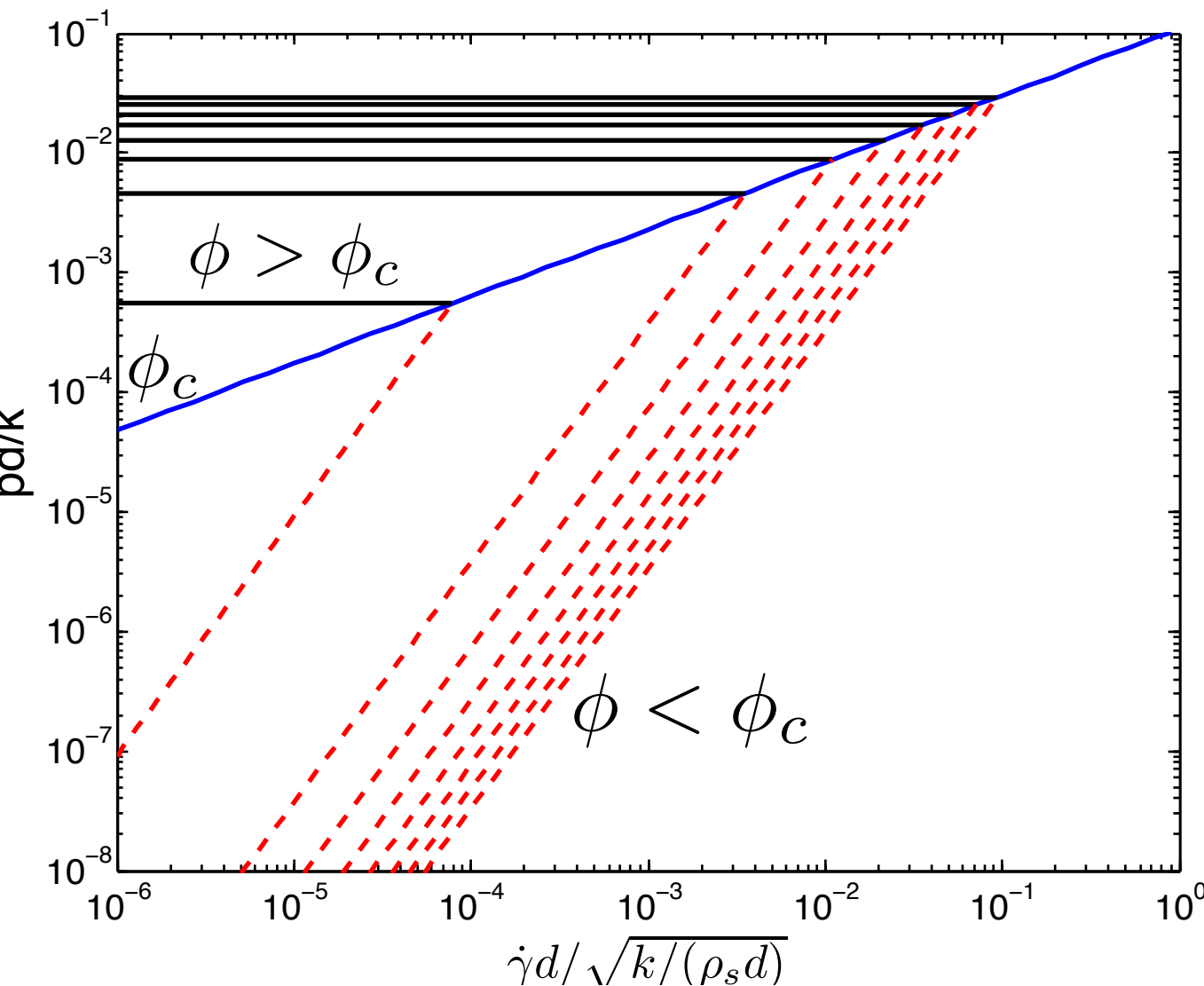
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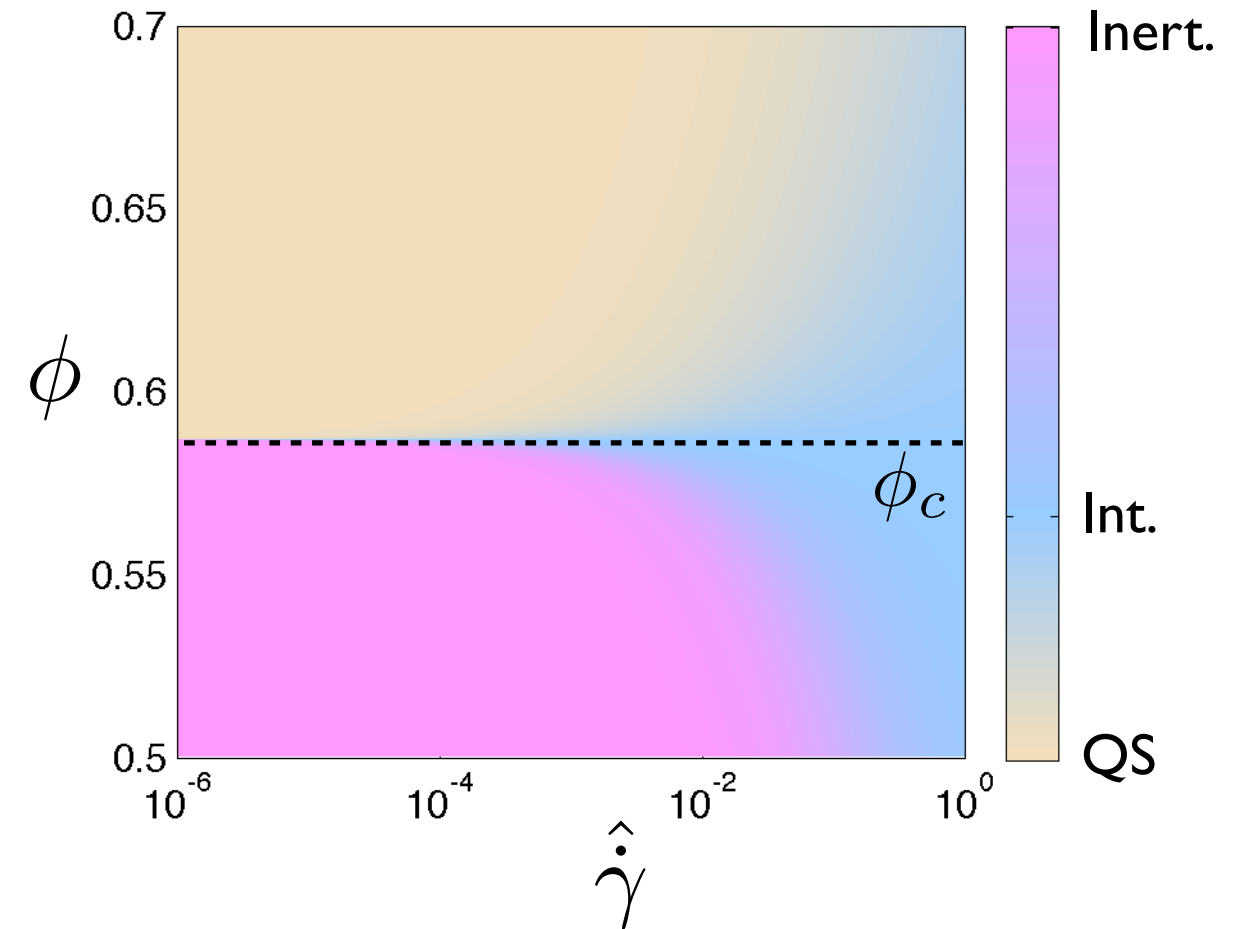
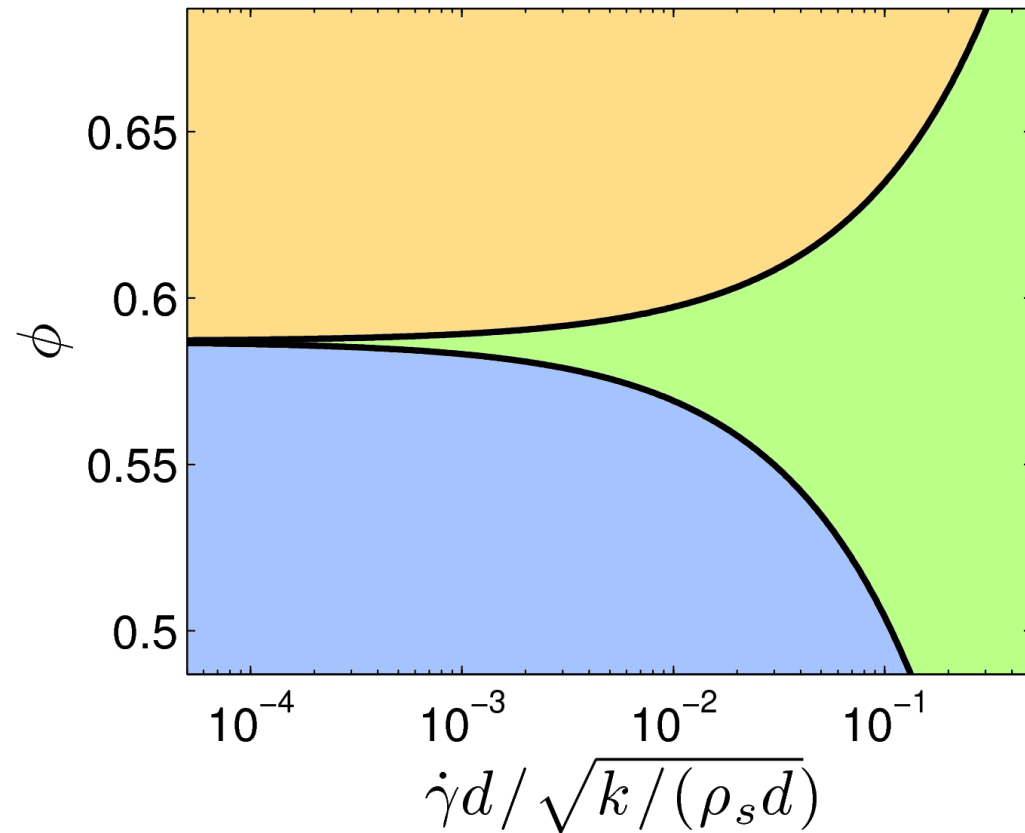
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[1] C. S. Campbell. Journal of Fluid Mechanics, 465:261–291, 2002.

[2] G. Lois and J. M. Carlson. Europhysics Letters, 80(5):58001–1–5, 2007.



# Regime maps



$$p = \begin{cases} B(p_{QS}, p_{Int}) & \text{for } \phi \geq \phi_c \\ B(p_{Inert}, p_{Int}) & \text{for } \phi < \phi_c \end{cases}$$

$$\tau = \begin{cases} B(\tau_{QS}, \tau_{Int}) & \text{for } \phi \geq \phi_c \\ B(\tau_{Inert}, \tau_{Int}) & \text{for } \phi < \phi_c \end{cases}$$

# Outline



- Introduction
- Models for different flow regimes
- Bridging across flow regimes
- Summary and future work