

Quantifying Uncertainty In Computational Knowledge Engineering Rapidly

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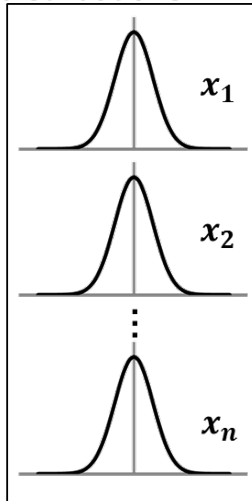
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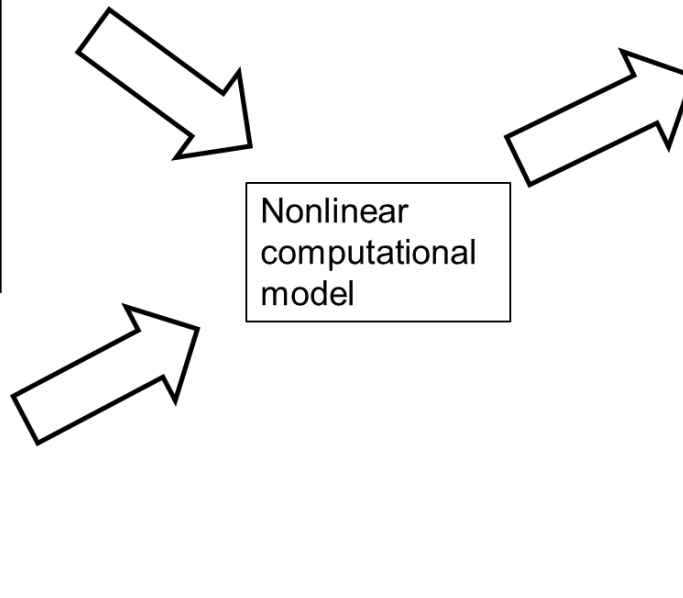
- ❑ **Multiphase systems operate in an environment of uncertainty**
 - This uncertainty exists in both the parameters governing the system and in the process behavior
 - The interactive effect of uncertainty leads to variability in the system performance or the process outcomes
 - Uncertainty quantification, through stochastic computational modeling and analysis, is an important tool for investigating these effects

Uncertain input distributions

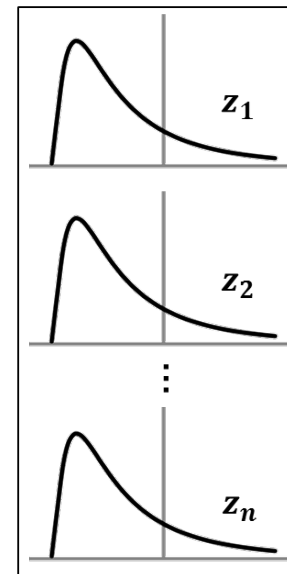


Deterministic inputs

y_1
 y_2
 \vdots
 y_n



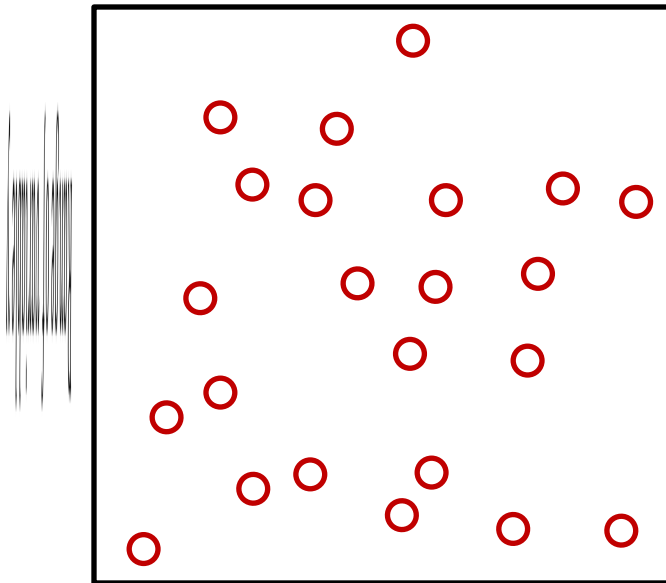
Output distributions



- ❑ **Conventional methods seek to mimic physical processes**
 - **Monte Carlo methods randomly select inputs from the input distributions**
 - **Stratified methods (such as the Latin Hypercube method) seek to reduce the number of experiments, but still generate a representative sample**
 - **Both methods are VERY computationally intensive**

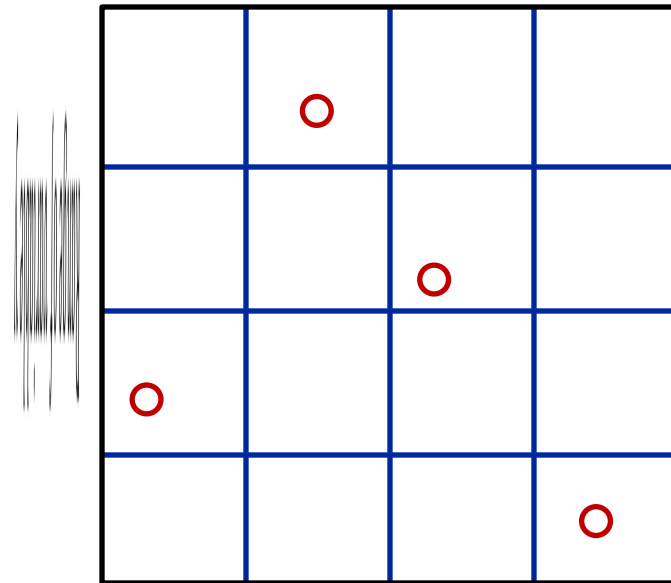
Monte Carlo Sampling

Range of variable x



Latin Hypercube Sampling

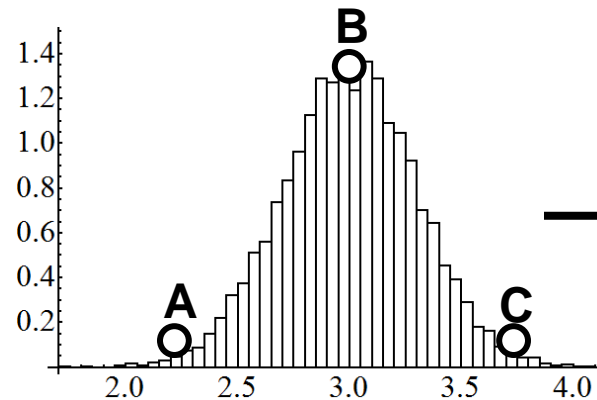
Range of variable x



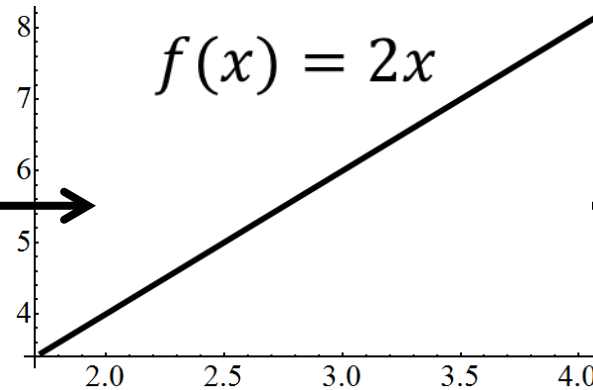
- ❑ **QUICKER (Quantifying Uncertainty In Computational Knowledge Engineering Rapidly)**
 - QUICKER is a new methodology that is intended to be used instead of conventional sampling methods such as Latin Hypercube Sampling, Monte Carlo Sampling, Quasi-Monte Carlo Sampling, etc.
 - Since sampling, effectively running computational simulations, is the most time consuming aspect of Uncertainty Quantification, the significant reduction in computational costs from using QUICKER make Uncertainty Quantification far more affordable
- ❑ **QUICKER is orders of magnitude faster than conventional sampling**
 - Through the use of QUICKER, it is typical to see computational time reductions in excess of 99% of the time required for conventional methods
- ❑ **QUICKER does not sacrifice accuracy**
 - Typical RMS differences between QUICKER and conventional methodologies are less than 8%
- ❑ **QUICKER is noninvasive and transparent**
 - QUICKER can be implemented without modifying the simulation source code
 - The QUICKER methodology does not require esoteric math or complicated algorithms

Identifying key points to sample

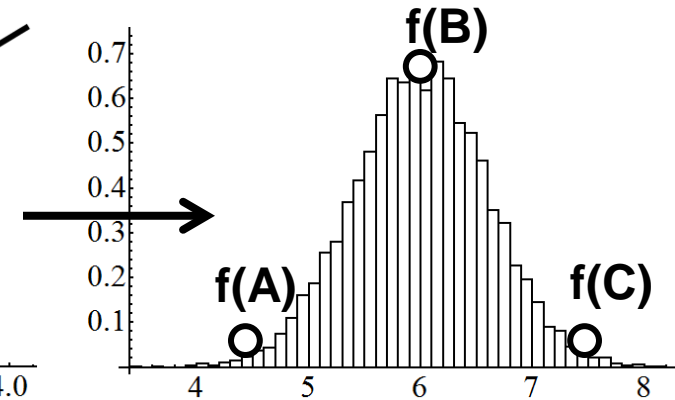
Gaussian input distribution



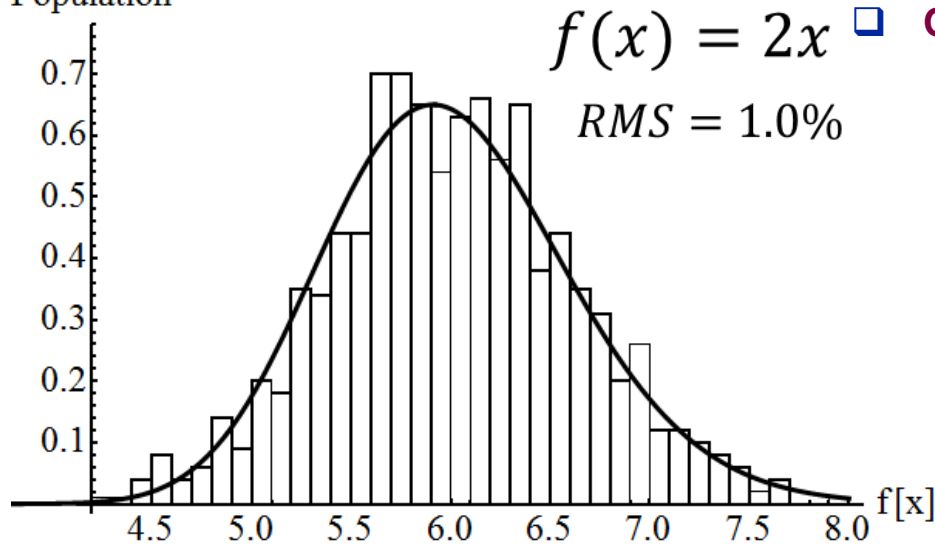
Monotonic system



Unimodal output distribution



Population

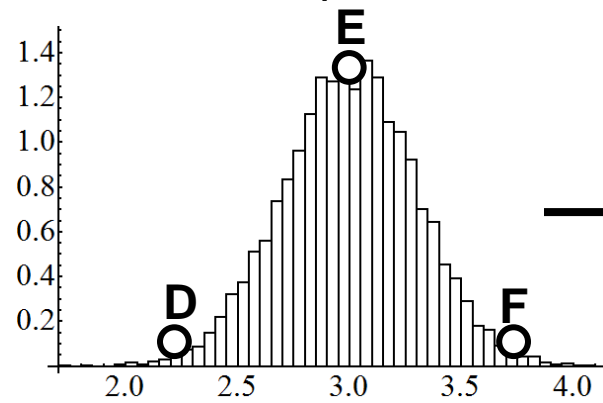


Only a small number of key points are necessary

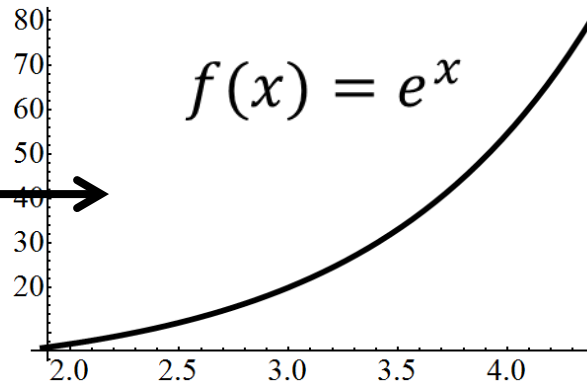
- For a monotonic system with a Gaussian input, it is necessary to select only a few input points in order to completely define the output distribution
- These points are chosen at the mean and equal standard deviations

Using a lognormal output distribution

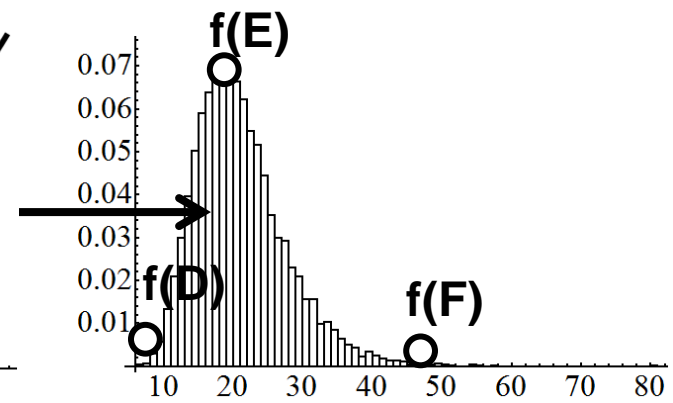
Gaussian input distribution



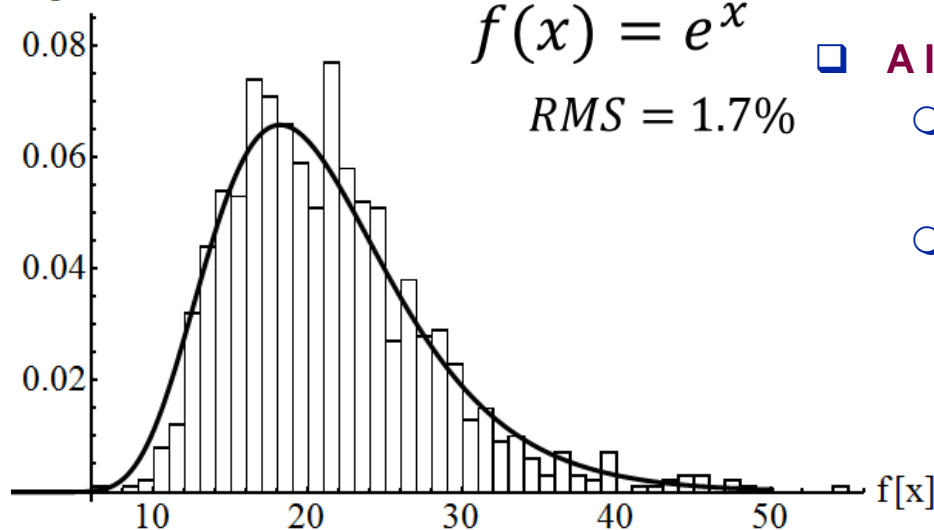
Monotonic system



Unimodal output distribution



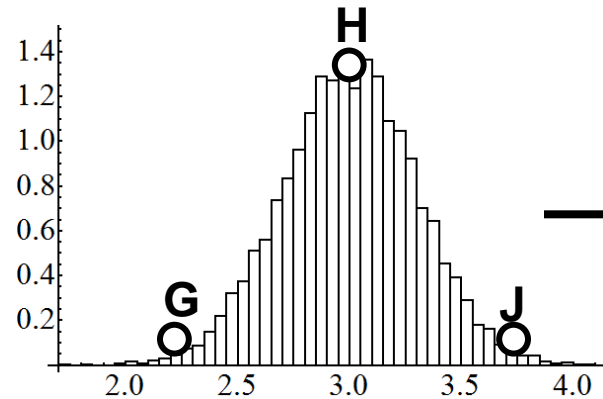
Population



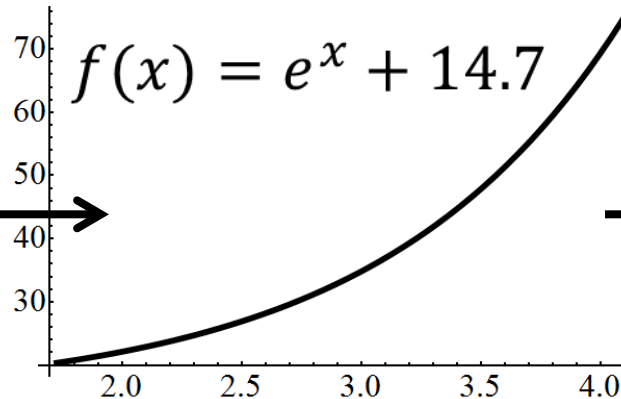
- **A lognormal distribution is versatile**
- **A lognormal distribution can be used to represent symmetric or positive skewness**
- **Therefore, lognormal distributions will be used in QUICKER**

Accounting for constant offset

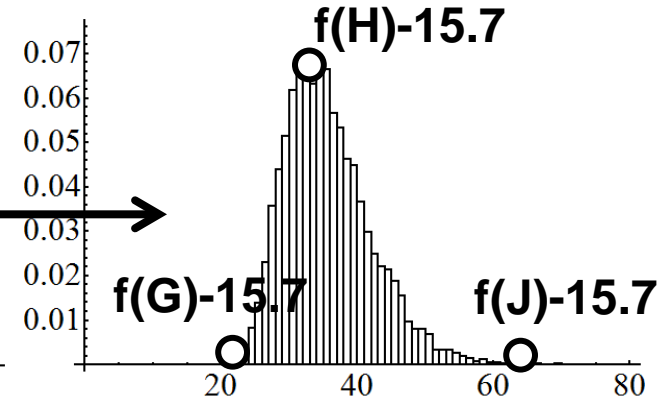
Gaussian input distribution



Offset monotonic system

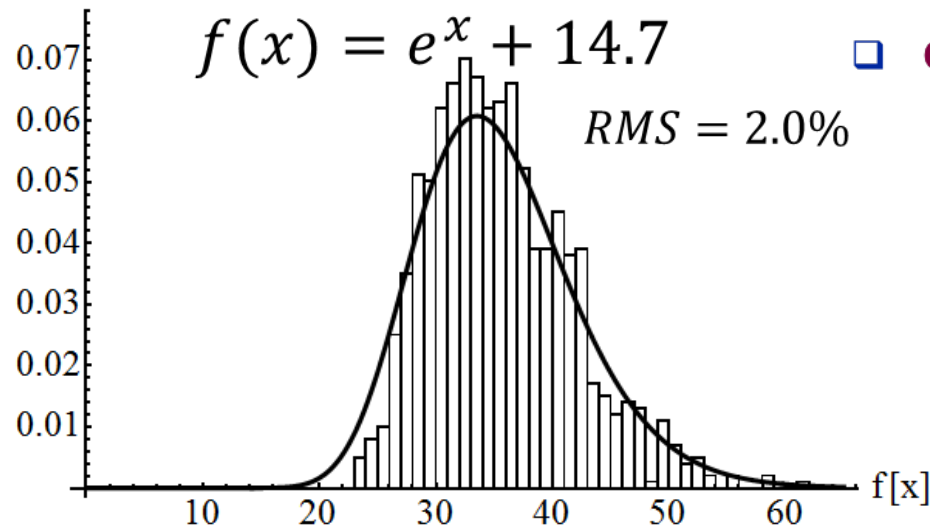


Unimodal output distribution



Axis is increased by $f(0)$,
15.7 in this instance

Population

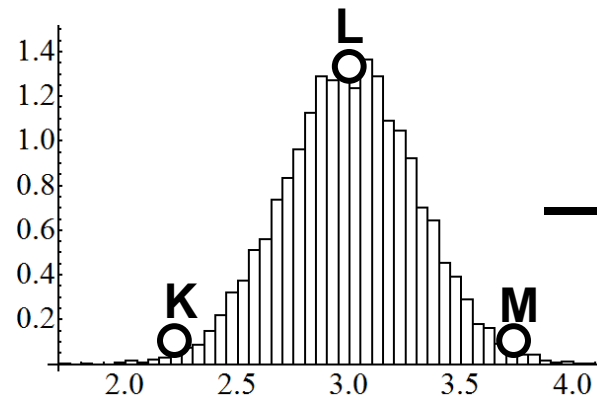


□ Certain systems have a constant offset

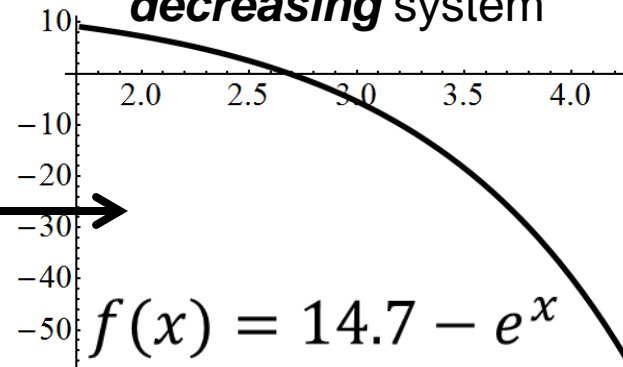
○ The lognormal distribution assumes that $f(x=0) = 0$, and therefore it is necessary to account for any systematic offsets by taking an additional data point

Accounting for negative skewness

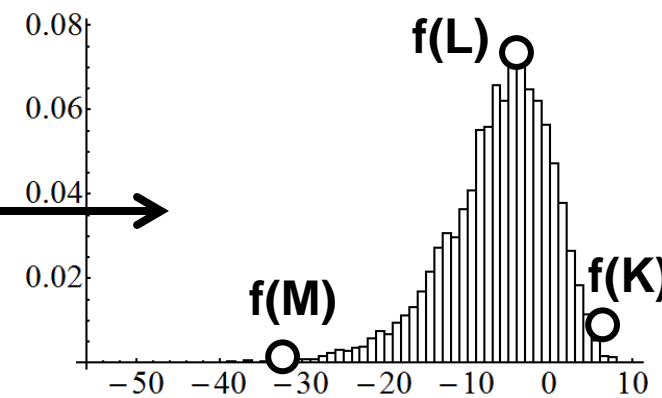
Gaussian input distribution



Monotonically
decreasing system

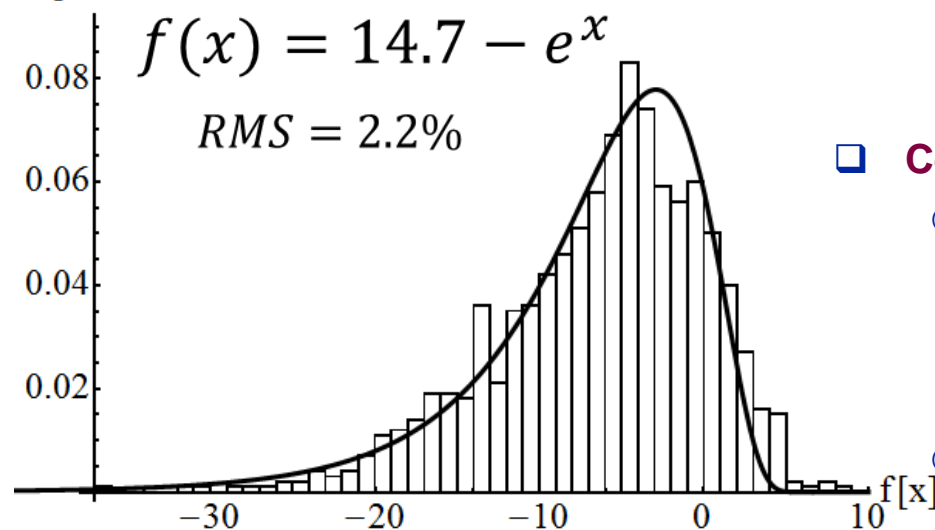


Unimodal output distribution



Axis is flipped about the max result, $f(K)$ in this instance

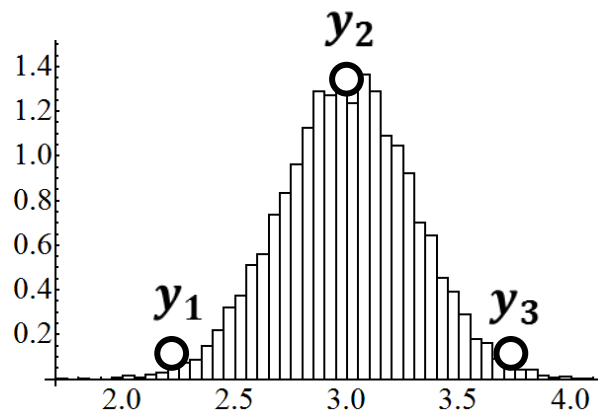
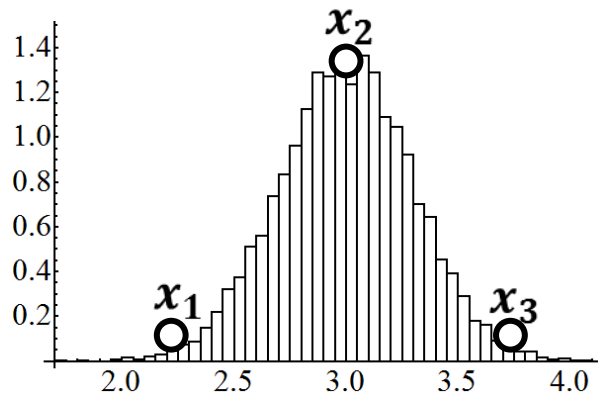
Population



- **Certain outputs have a negative skewness**
 - The lognormal distribution has a positive skewness, and in order to account for this, the plot needs to be “flipped” about the maximum point
 - Note that the function reverses the relative magnitude of the inputs

Sampling within QUICKER

For a system with two input distributions, three points are selected on each input distribution



Input distr.	$\mu - N\sigma$	μ	$\mu + N\sigma$
x	x_1	x_2	x_3
y	y_1	y_2	y_3

The minimums and means are simulated, and then an orthogonal array is used to combine the extremes

Simul. #	x	y
min	min	min
1	x_2	y_2
2	x_1	y_1
3	x_1	y_3
4	x_3	y_1
5	x_3	y_3

A specific example of QUICKER

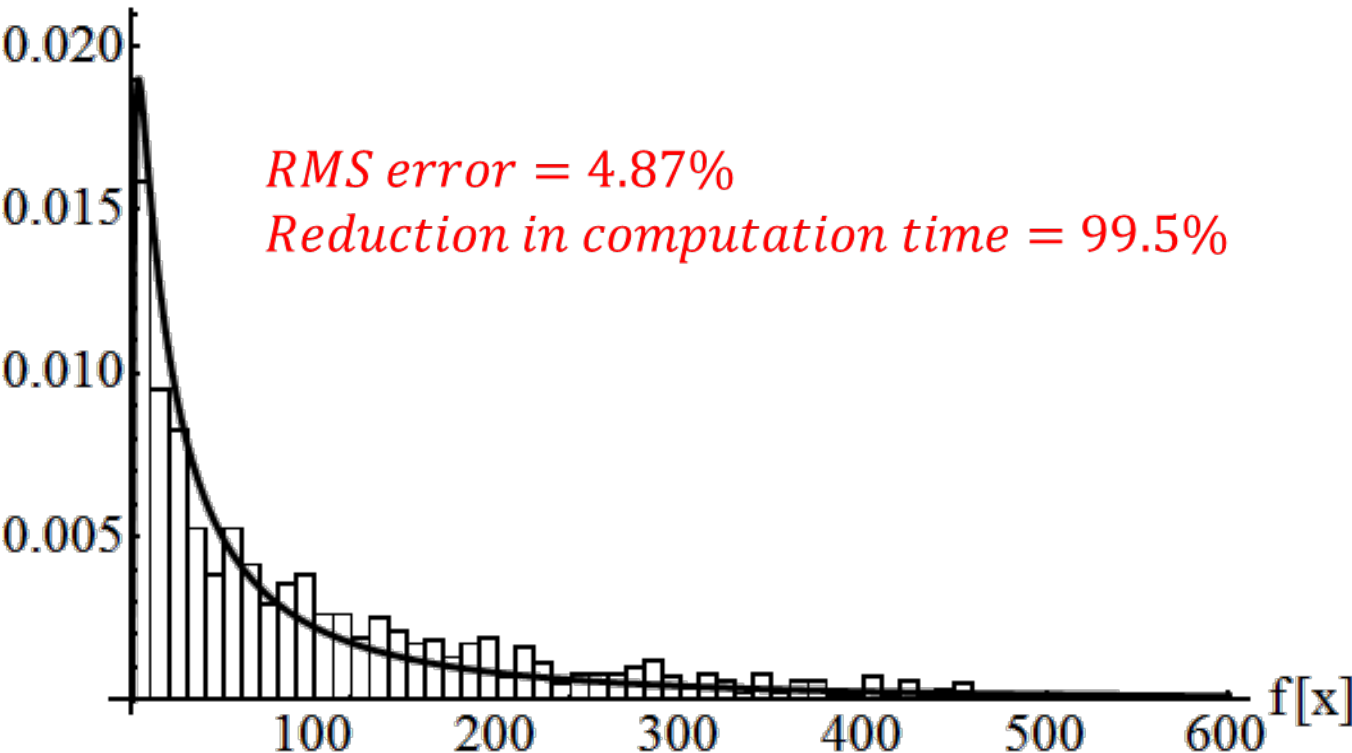
The Rosenbrock function is a typical test case for optimization routines

$$f(x, y) = 100 * (y - x^2)^2 + (1 - x)^2$$

$$\mu_x = 0, \sigma_x = 0.67$$

$$\mu_y = 1, \sigma_y = 0.67$$

Population



Input distr.	$\mu - 3\sigma$	μ	$\mu + 3\sigma$
x	-2.01	0	2.01
y	-1.01	1	3.01

Simul. #	x	y
min	1	1
1	0	1
2	-2.01	-1.01
3	-2.01	3.01
4	2.01	-1.01
5	2.01	3.01

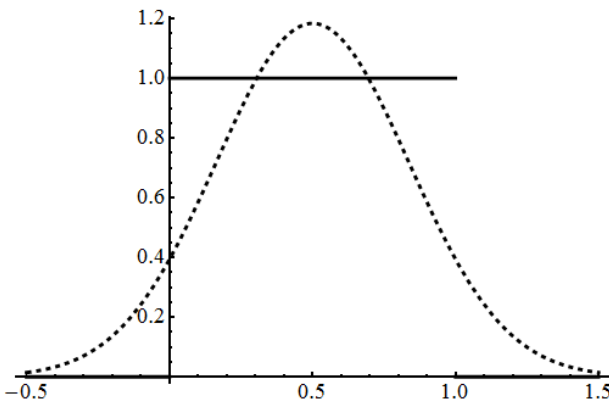
Composite representation of uniform

$U = \text{length of uniform range}$

$U_0 = \text{lower bound}$

$$\mu = 0.5U + U_0$$

$$\sigma = 0.337U$$

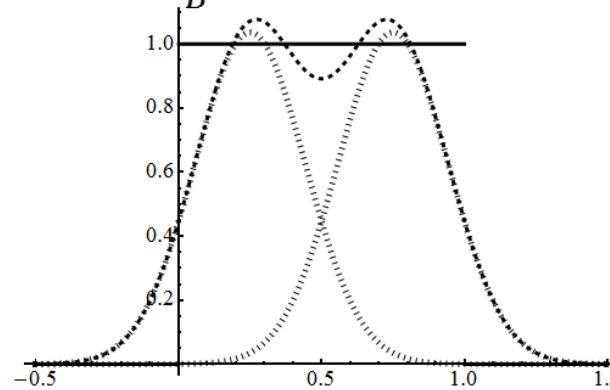


$$\mu_A = 0.25U + U_0$$

$$\mu_B = 0.75U + U_0$$

$$\sigma_A = 0.1925U$$

$$\sigma_B = 0.1925U$$



$$\mu_A = 0.16U + U_0$$

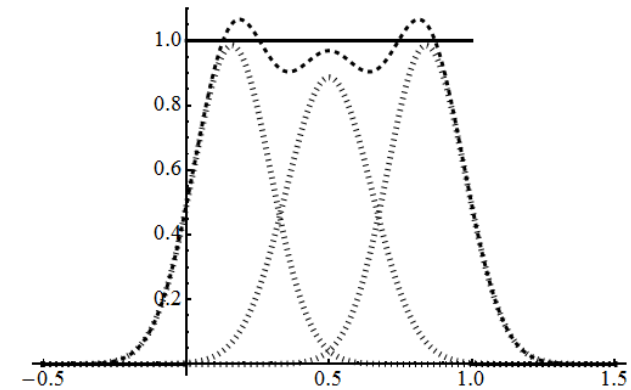
$$\mu_B = 0.5U + U_0$$

$$\mu_C = 0.84U + U_0$$

$$\sigma_A = 0.135U$$

$$\sigma_B = 0.15U$$

$$\sigma_C = 0.135U$$



- **Epistemic uncertainty is typically represented as a uniform distribution**
 - **A combination of Gaussian distributions can be used to represent a uniform distribution**
 - **Note that the Gaussian distribution is scaled depending on the uniform distribution**

Results of composite uniform

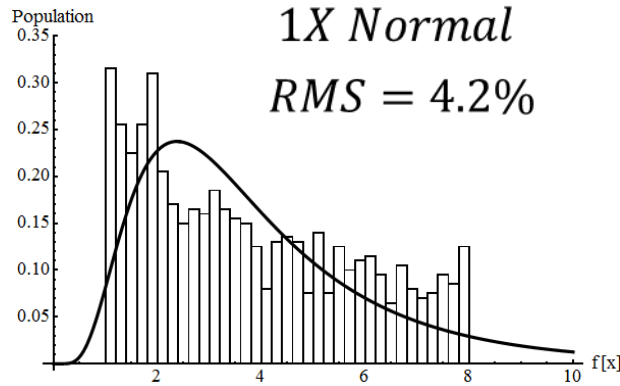
Uniform input distribution: $[1, 2]$

$$f(x) = x^3 + 1$$

Time reduction = 99.7%

1X Normal

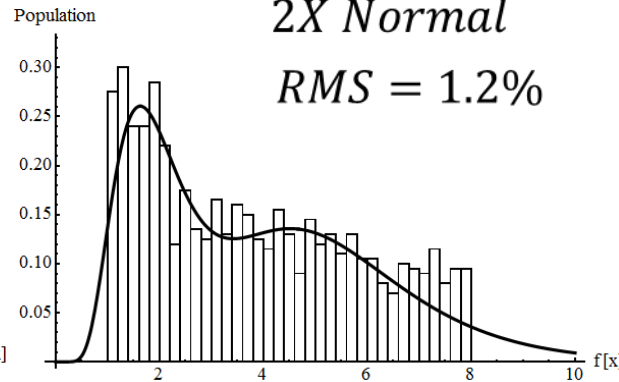
RMS = 4.2%



Time reduction = 99.4%

2X Normal

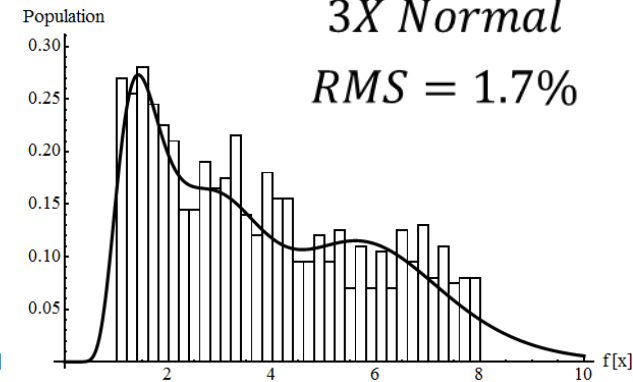
RMS = 1.2%



Time reduction = 99.1%

3X Normal

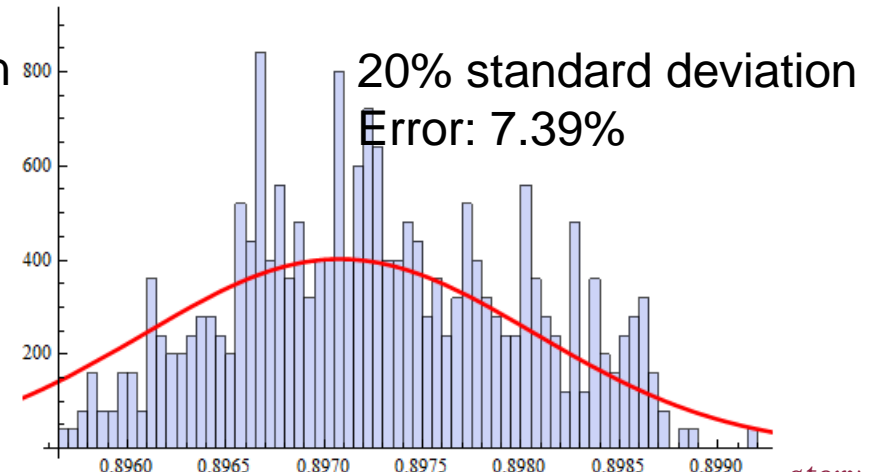
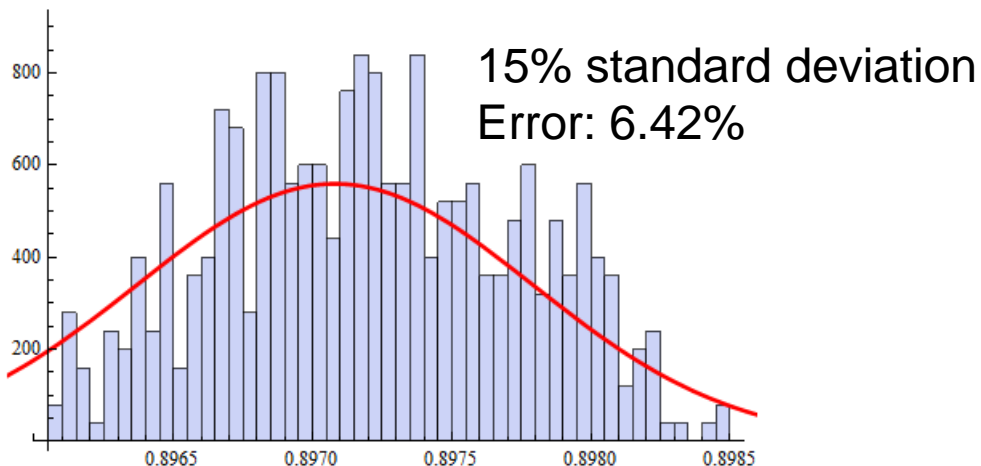
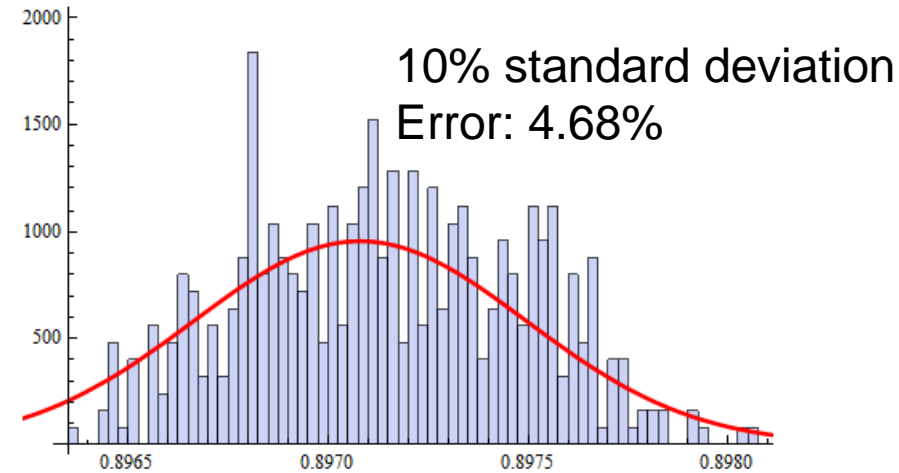
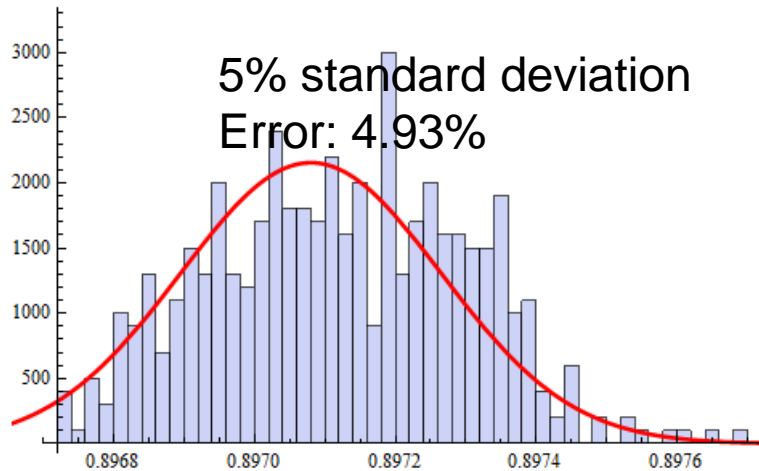
RMS = 1.7%



- ❑ **To a point, composite distributions can provide a more accurate prediction**
 - **Functions of only one variable are typically the hardest to represent with uniform composite distributions**
 - **Note that the improvement from 2X to 3X composite distribution is negligible**

LHS computation time: 125.56 hours
QUICKER computation time: 4.52 hours
Computational time savings of 96.4%

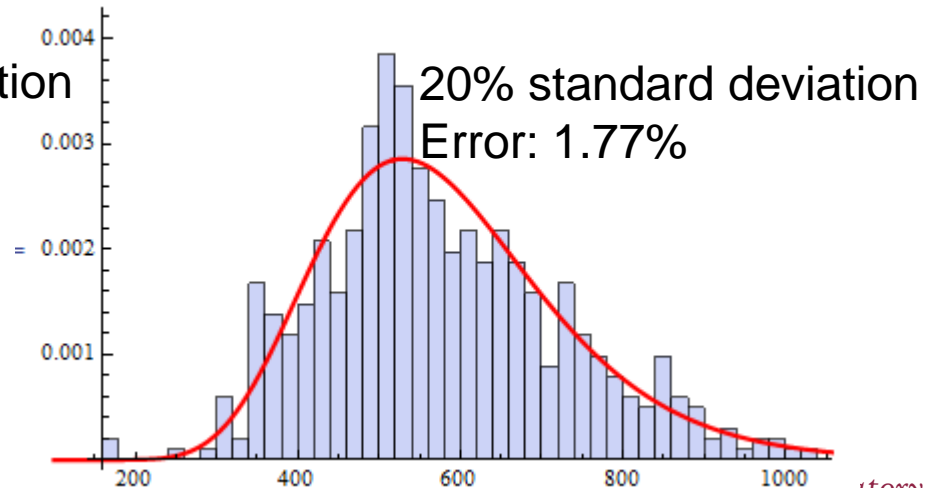
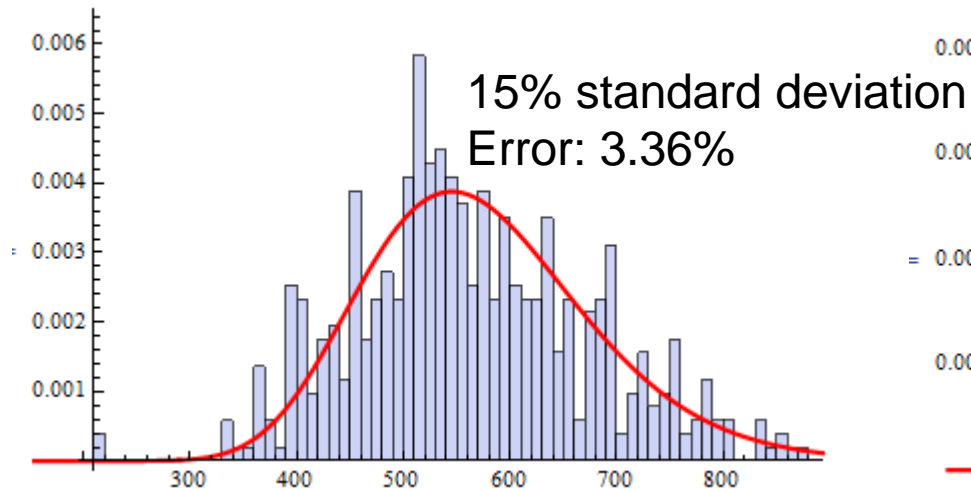
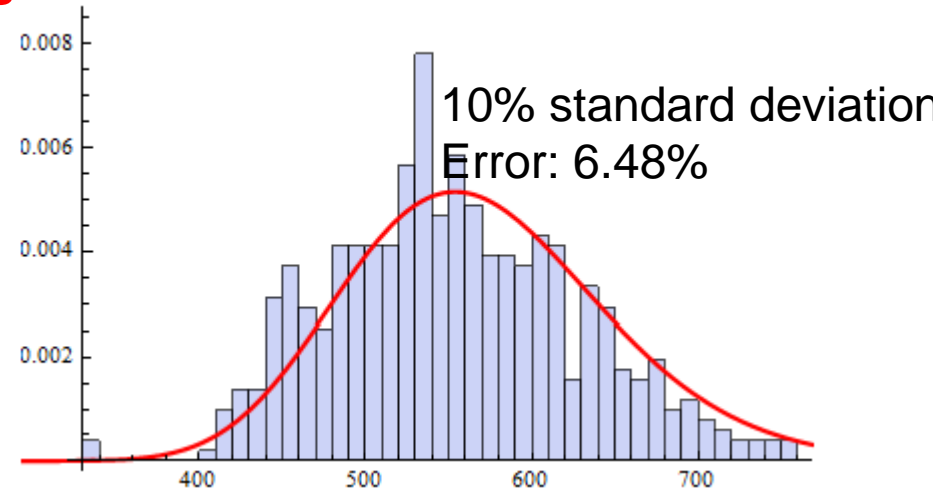
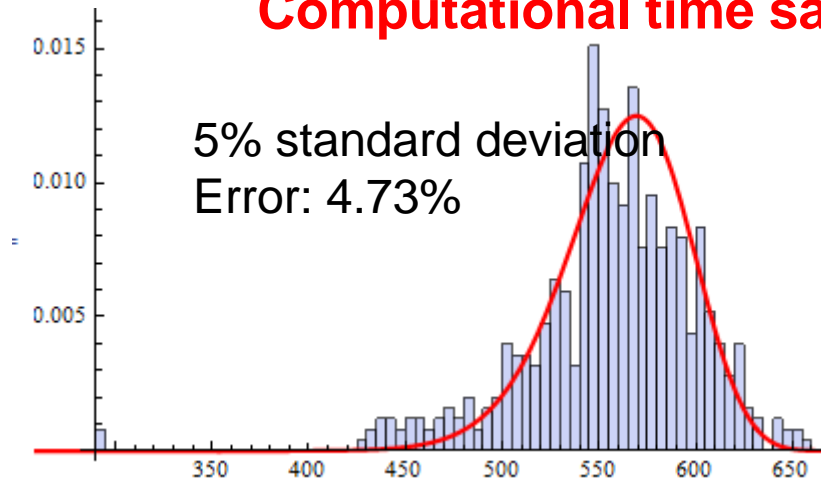
**Measuring porosity at
a specified location**



Ahmadi MFX scenario with 1X uniform

LHS computation time: 4.58 hours
QUICKER computation time: 0.10 hours
Computational time savings of 97.8%

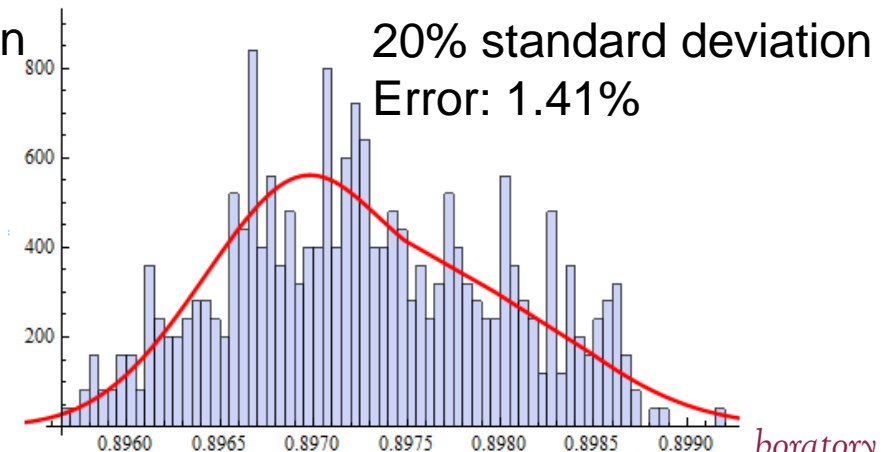
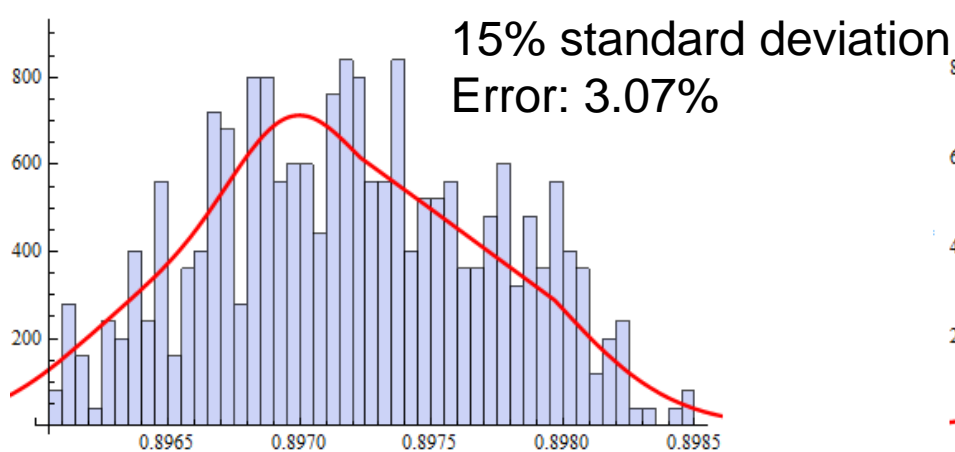
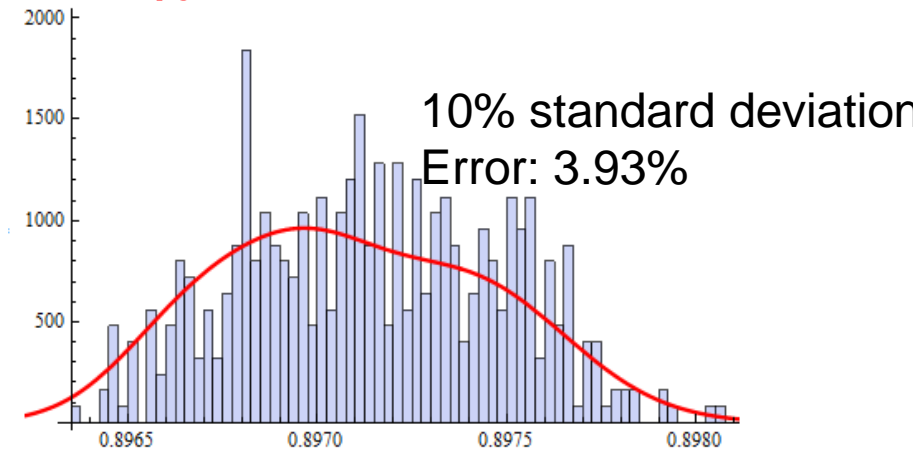
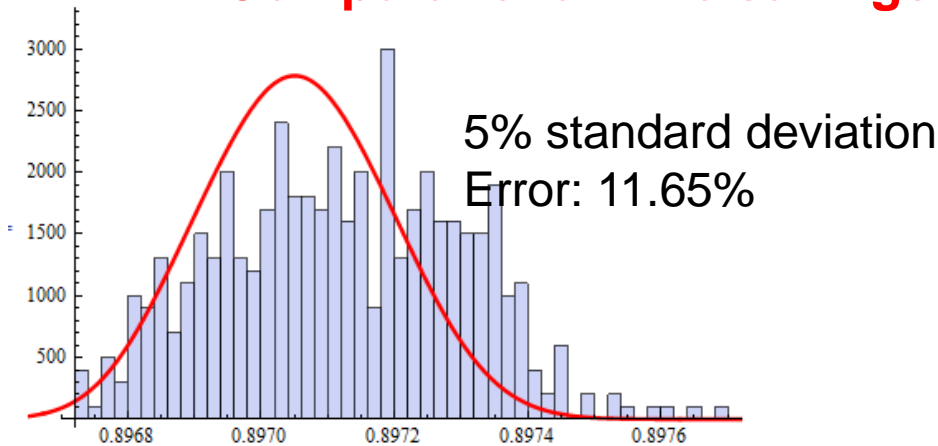
Measuring solid velocity at a specified location



3dCfb MFIX scenario with 2X uniform

LHS computation time: 125.56 hours
QUICKER computation time: 36.16 hours
Computational time savings of 71.2%

**Measuring porosity at
a specified location**



Results of a blind study

Results of a blind chemical kinetics study

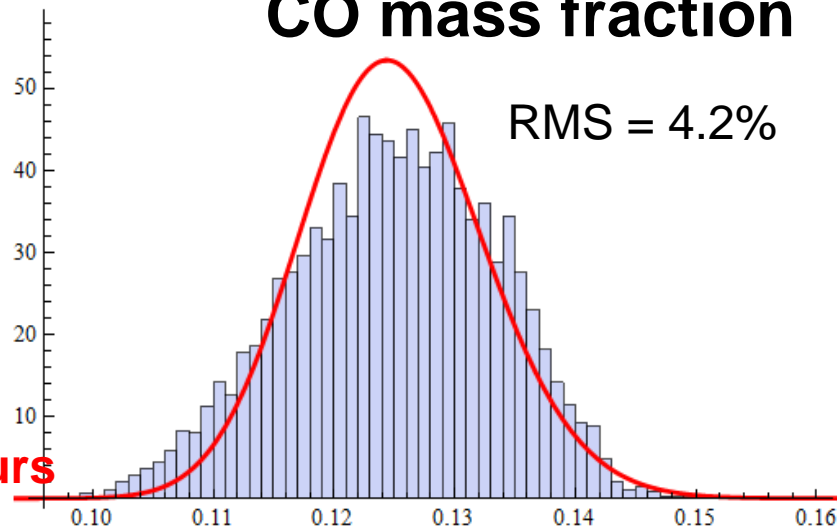
- Using the QUICKER methodology, a set of samples points were provided to Dr. Aytekin Gel to run through his simulation
- The developers of QUICKER had no prior knowledge of the specifics of this kinetics model

MC computation time: 1.52 hours

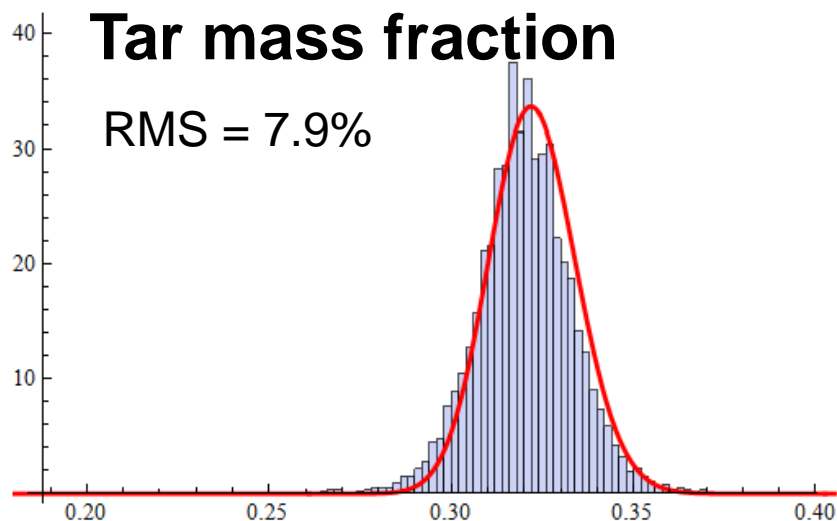
QUICKER computation time: 0.0019 hours

Computational time savings of 99.9%

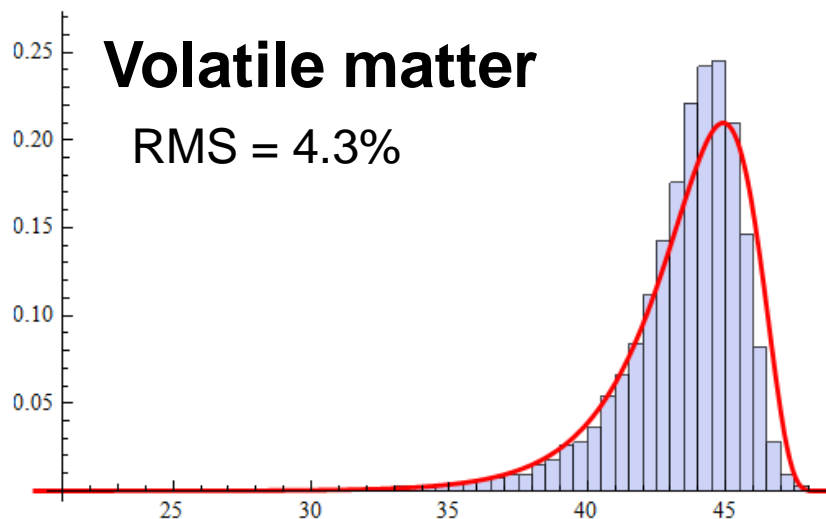
CO mass fraction



Tar mass fraction

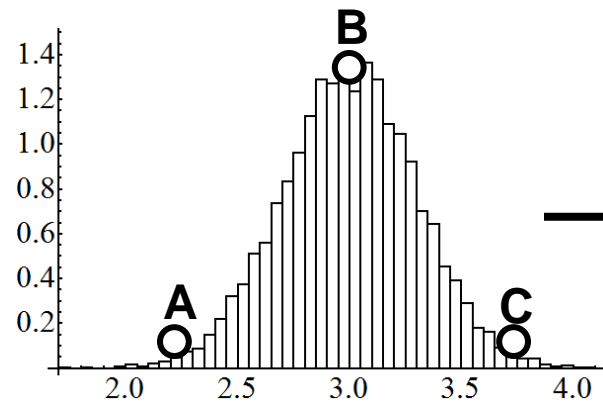


Volatile matter

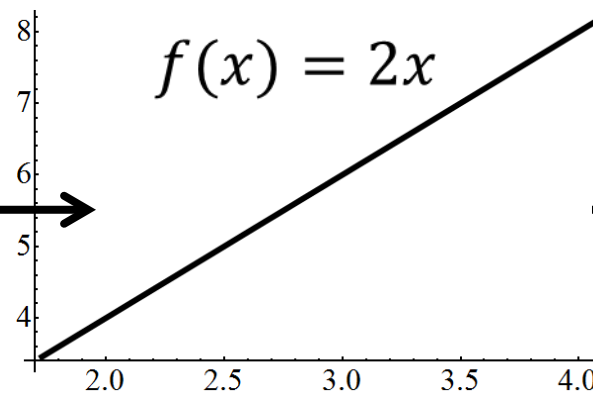


Support from the U.S. Department of Energy, National Energy Technology Laboratory (NETL), is gratefully acknowledged

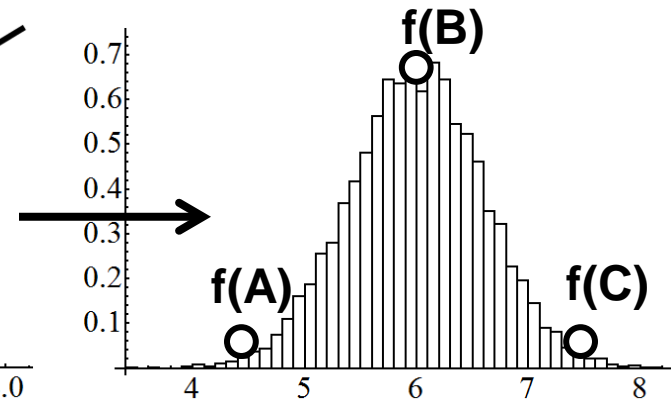
Gaussian input distribution



Monotonic system



Unimodal output distribution



Composite functions

