

OpenMP parallelism for fluid-particulate system

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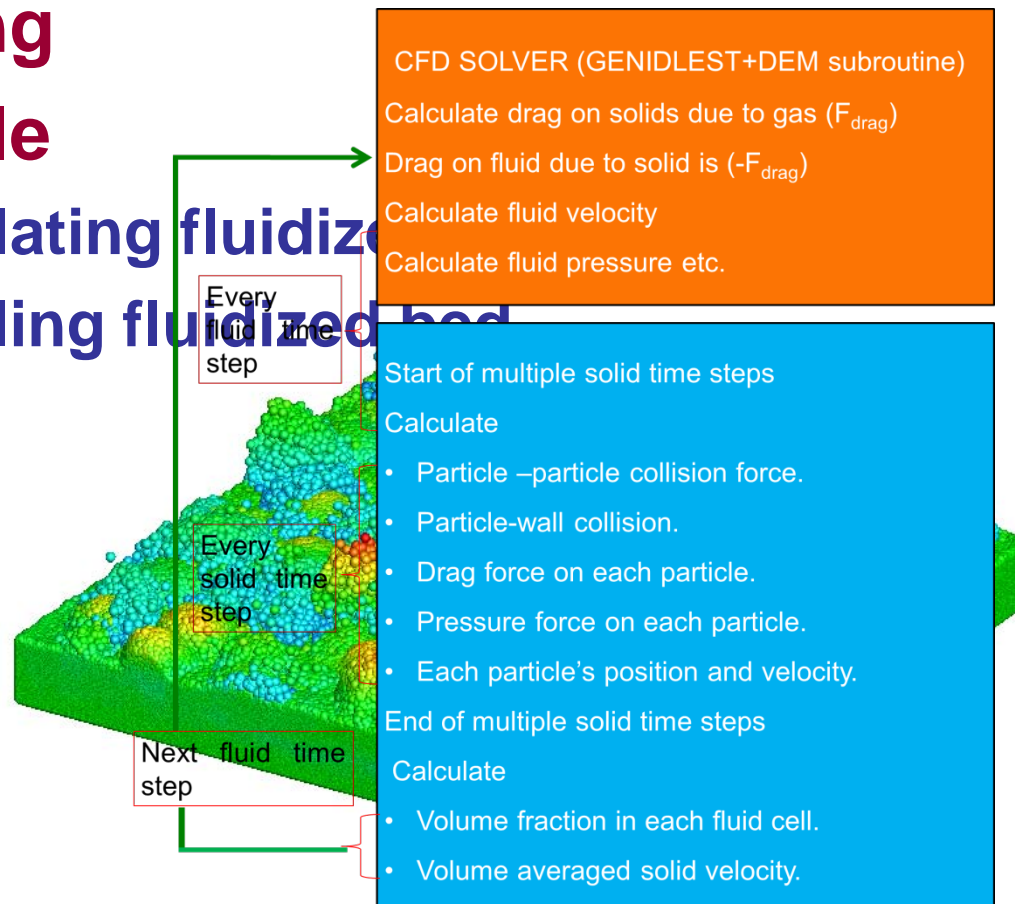


Outline

- **CFD-DEM and parallelization**
- **Algorithm**
- **Results**
 - Validation
 - Scaling study
- **Future work**

Coupled fluid-particulate system

- Procedure of Fluid(CFD) + Particulate(DEM) coupling
- Example
 - Circulating fluidized bed
 - Bubbling fluidized bed

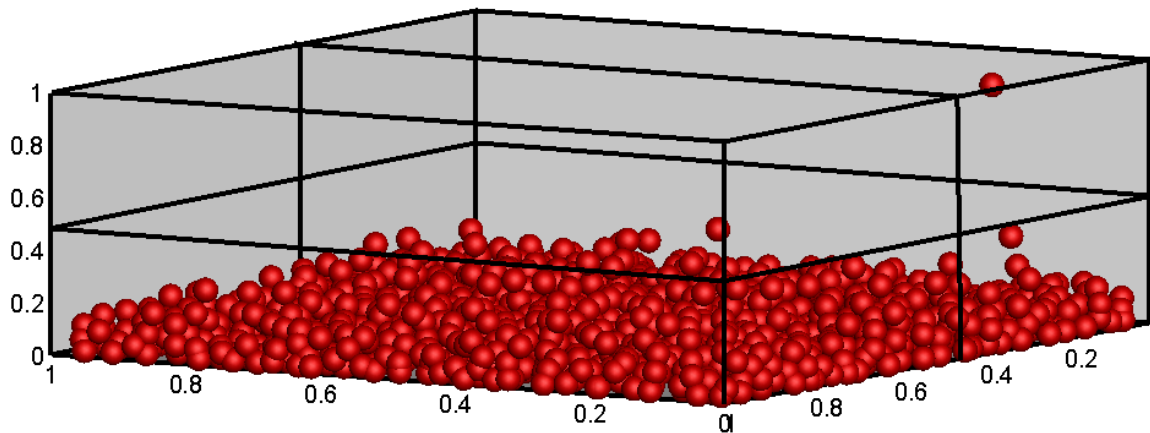


Parallelization Techniques

- **Fluid phase (CFD code) parallelism**
 - Grid based field equations mapped to domain decomposition
- **Particulate phase parallelism**
 - N-body type of computations
 1. **Mirror domain technique**
 - Each CPU has copy of all the particle data but only works on part of it
 - No communication during computations
 - Large memory foot print
 2. **Particle subset method**
 - Particle workload is evenly divided amongst CPUs
 - Ideal load balancing
 - Communication during computations
 3. **Domain decomposition**
 - Spatial decomposition irrespective of number of particles in each domain
 - Easy to implement
 - Poor load balancing

Parallelization of Eulerian-Lagrangian system

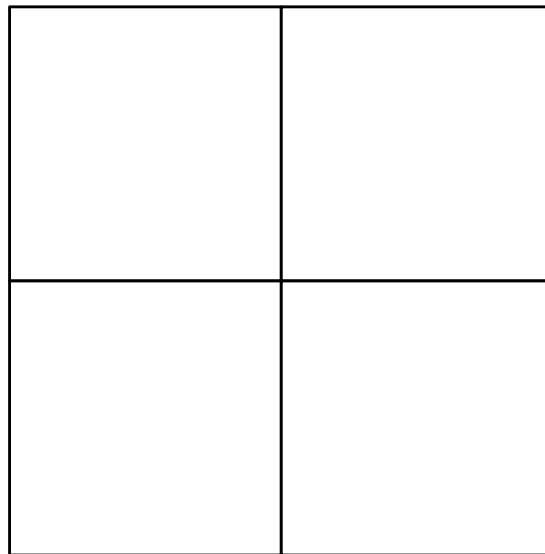
- **Parallelization of fluid-particulate systems**
 - **Domain decomposition**
 - **Poor load balancing for particulate system**



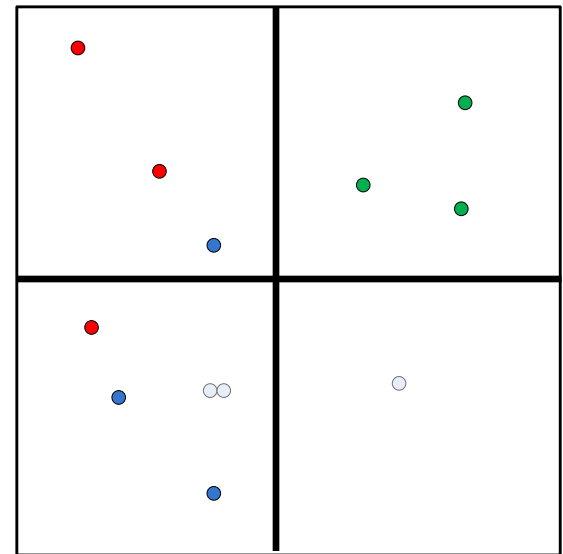
Parallelism for fluid-particulate system

- **Fluid – domain decomposition**
- **Particles – N-body decomposition**
 - Particle subset method

Fluid domain
decomposition



Particle domain



Implementation of multi-mode parallelism

- **Implementation in the MPI framework**
 - All particle data needs to be gathered onto a single processor and evenly scattered across all the processors
 - After the particulate phase calculations, the drag forces need to be gathered and scattered to perform the fluid field calculation
 - Entire data structure is reshuffled twice every time step
- **MPI implementation is inefficient for multi-mode parallelism**
- **MPI has high programming, development, and maintenance costs**

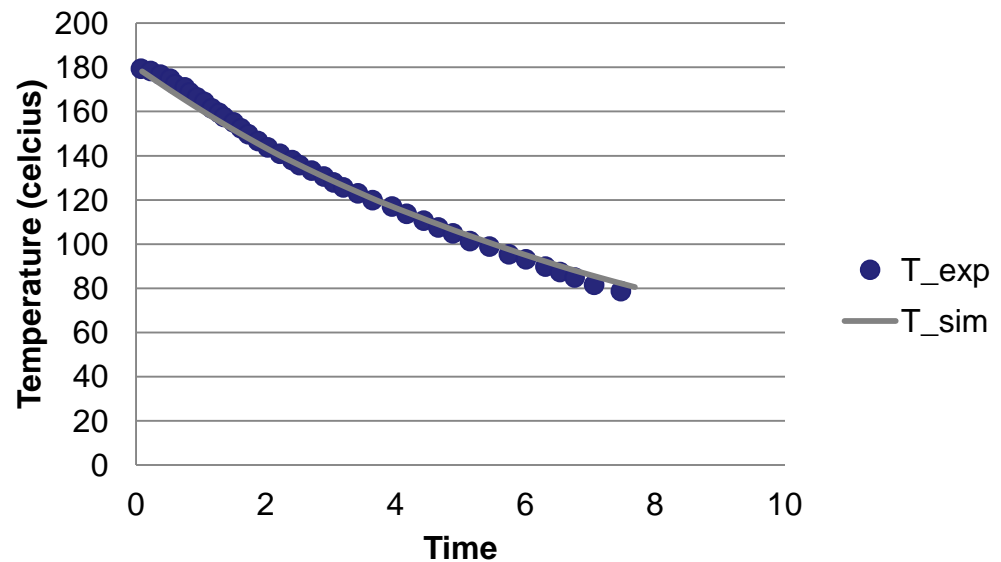
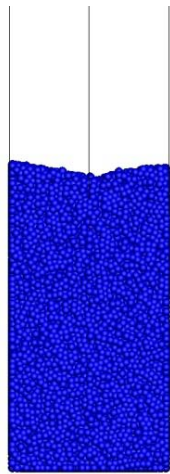
Implementation of CFD-DEM parallelism

- **Motivation for using OpenMP**
 - OpenMP has flexible programming model
 - Domain decomposed (fluid phase)
 - Particle Subset (dispersed phase)
 - OpenMP is relatively easy to implement
 - OpenMP will have extensions (OpenACC) to support heterogeneous computing
 - GPGPU
 - Intel – Many Integrated Core (MIC)
 - AMD Fusion

Micro scale heat transfer validation of OpenMP parallel implementation

- **Validation study # 1**

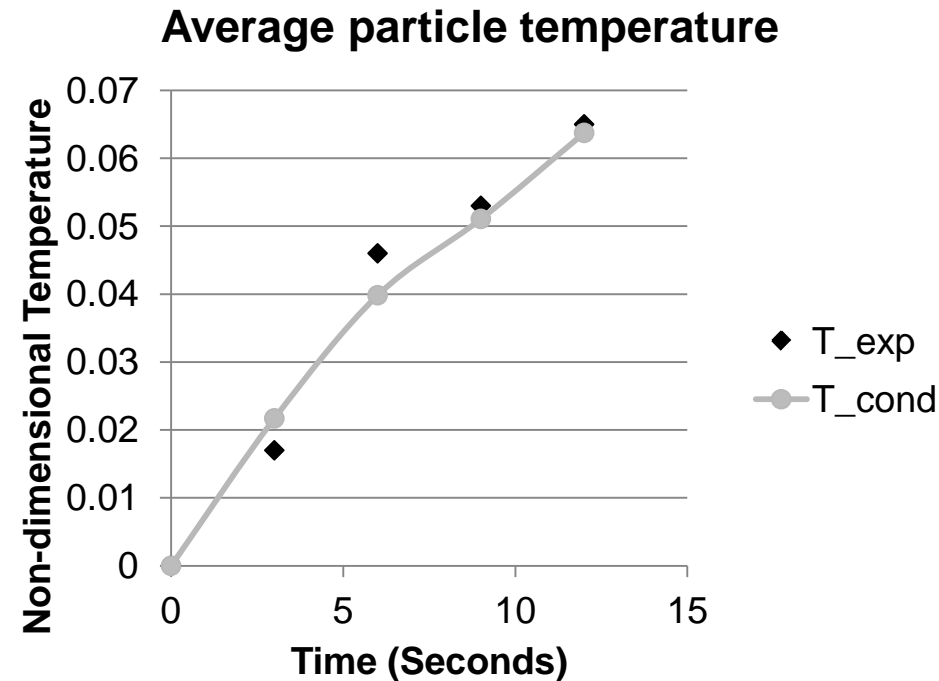
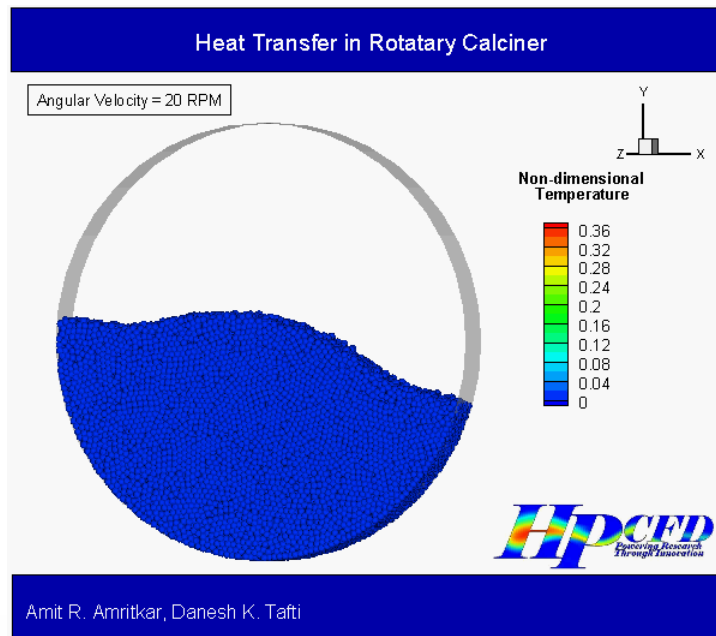
- Hot particle is inserted in a dense bed (Collier et al., 2004)
 - 3D periodic boundary condition
 - 16,000 particles on 2 processors
 - $0.58 \cdot u_{mf}$



Micro scale heat transfer validation of OpenMP parallel implementation

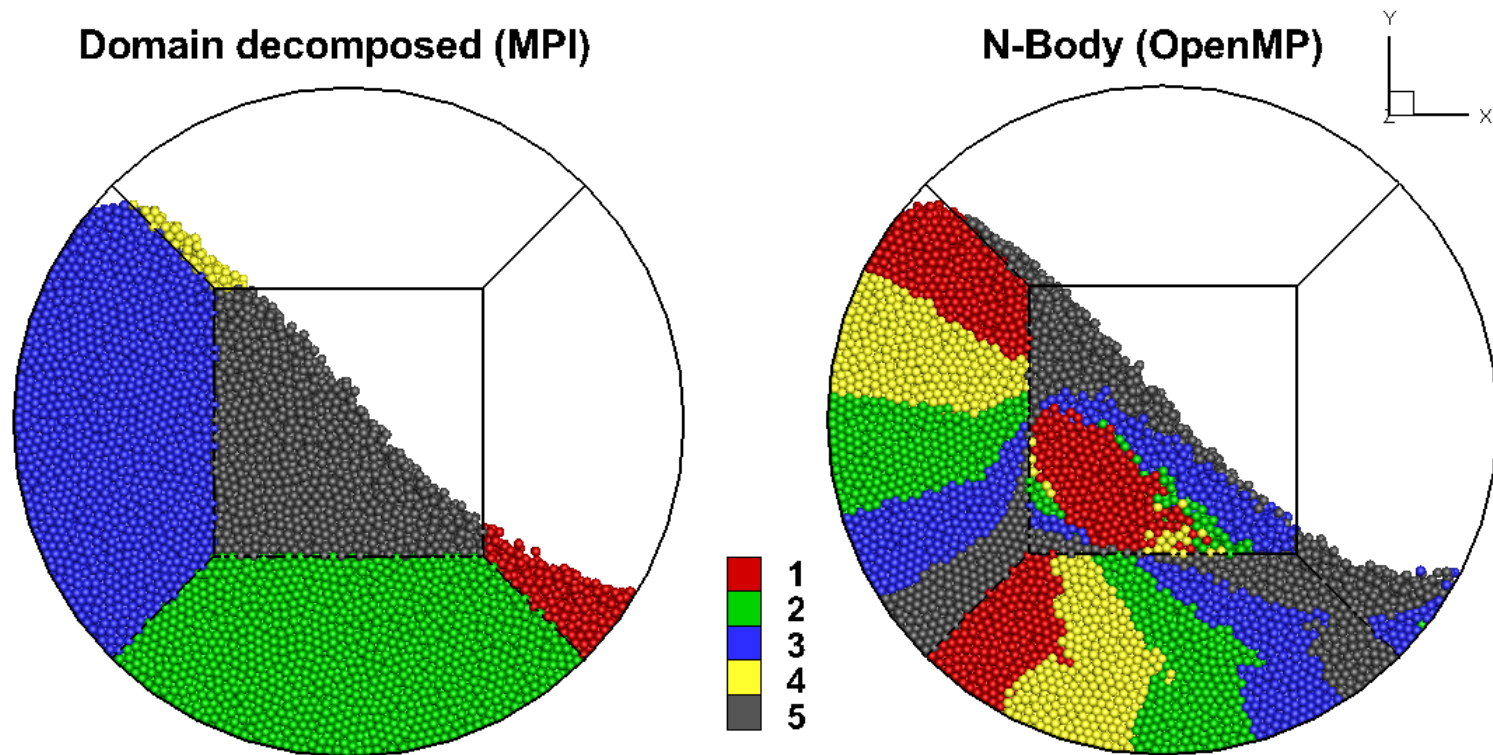
• Validation study # 2

- Heat transfer in rotary calciner (Chaudhuri et al., 2010)
 - Heated walls (curved surface) with particles rotating in a cylindrical drum
 - 20 RPM with 20,000 particles



Comparison of particle workload division in a rotary calciner

- **Load imbalance in domain decomposed mode**



Rotary calciner simulation

- Calculations on HokieOne (SGI – UV100) shared memory machine
- 10 milliseconds (1000 time steps) of simulation at 20 RPM

	Number of Mesh Blocks	OpenMP	MPI
Time (seconds)	5 (20,000 particles)	159	329
Time (seconds)	25 (100,000 particles)	275.5	443

Performance of MFIx with OpenMP parallelism

- **Evaluation of OpenMP implementation performance for DEM**
 - **Top five most time-consuming subroutines**

calc_force_des	Threads	Total wall clock Time (s)	Time in calculating drag_fgs (s)
drag_fgs	1	128	36
cfnewvalues	2	125	39
leq_msolve	4	94	37
des_time_march	8	83	38

Future Work

- **Improve OpenMP performance**
 - Immediate work will focus on parallelizing 'drag_fgs' of the OpenMP implementation to obtain higher performance
 - Investigate key subroutines and evaluate modifications for OpenMP parallelism to be effective
- **Investigate OpenMP scalability for larger particle counts on tens of threads**

Summary

- **OpenMP is very effective in modeling fluid-particulate systems**
 - Comparative ease of programming
 - Dynamic load balancing
 - Future support for accelerator (GPU/MIC)
- ***MFIX-DES parallelization***
 - *Drag force calculations*
 - *Large scale computations*

Thank you

- Questions?

