

# INVESTIGATING ERRORS AND CONVERGENCE IN STOCHASTIC LAGRANGIAN-EULERIAN METHODS FOR DISPERSE MULTIPHASE FLOWS

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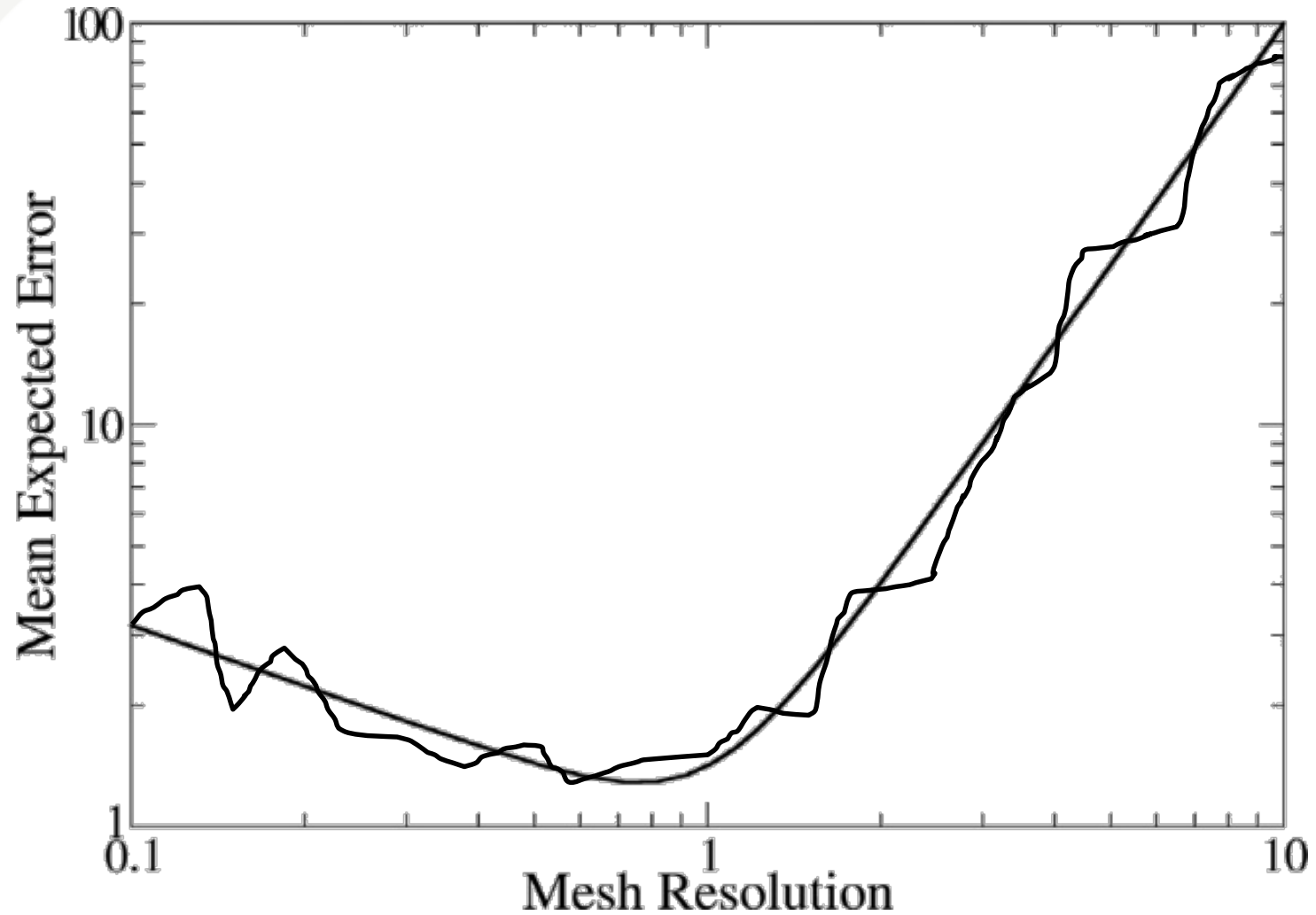
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# OUTLINE

- Introduction and Background
  - Motivation
  - Literature review
  - Derivation of Asymptotic Mean Square Error and L2 error norm estimates
- 2D static test case
  - Global error comparison
  - Local error comparison
- Future directions

# MOTIVATION

PREDICT ERRORS & CONVERGENCE AS CELL SIZE AND PARCEL COUNT CHANGE



# LITERATURE REVIEW

## SINGLE TIME STEP – UNIFORM KERNEL

- Schmidt (2006) and Schmidt and Bedford (2018)\*

- $$E^2 = \frac{f}{n(\Delta x)^d} + \frac{1}{4} \frac{1}{12^2} \left[ \sum_{m=1}^d \frac{\partial^2 f}{\partial x_m^2} \Delta x^2 \right]$$

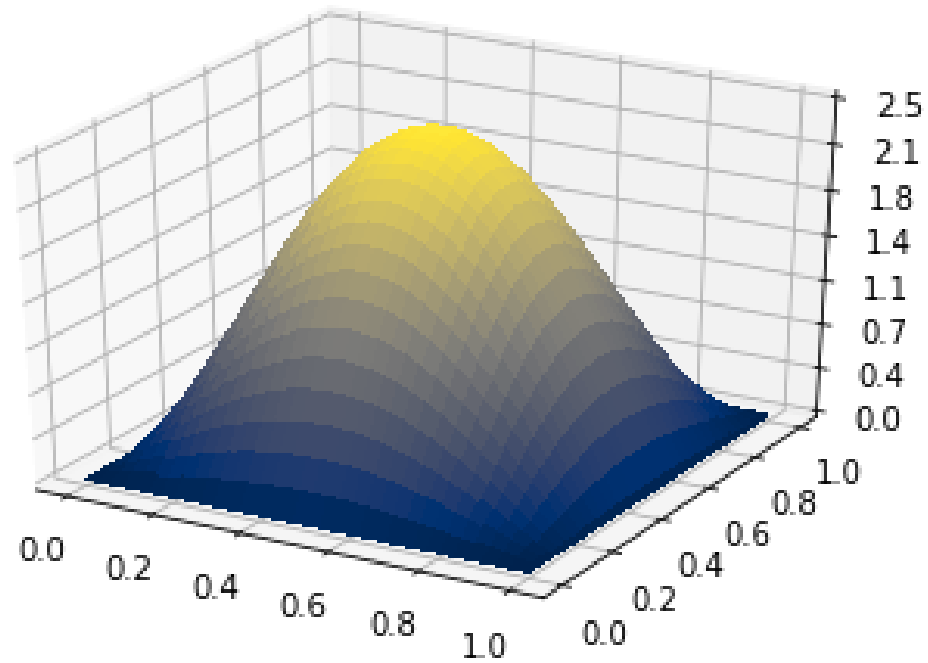
- $$n = \frac{b}{\Delta x^a}$$

- $$L_2^2 = \Delta x^d \sum_{cells} E^2$$

- $$L_2 \approx \sqrt{\frac{\Delta x^{a-d}}{b} \sum_{cells} f \Delta x^d + \frac{\Delta x^4}{576} \sum_{cells} \left[ \sum_{m=1}^d \frac{\partial^2 f}{\partial x_m^2} \right]^2 \Delta x^d}$$

- $$\Rightarrow c = \frac{a-d}{2}; a = 2c + d$$

# STATIC TEST CASE

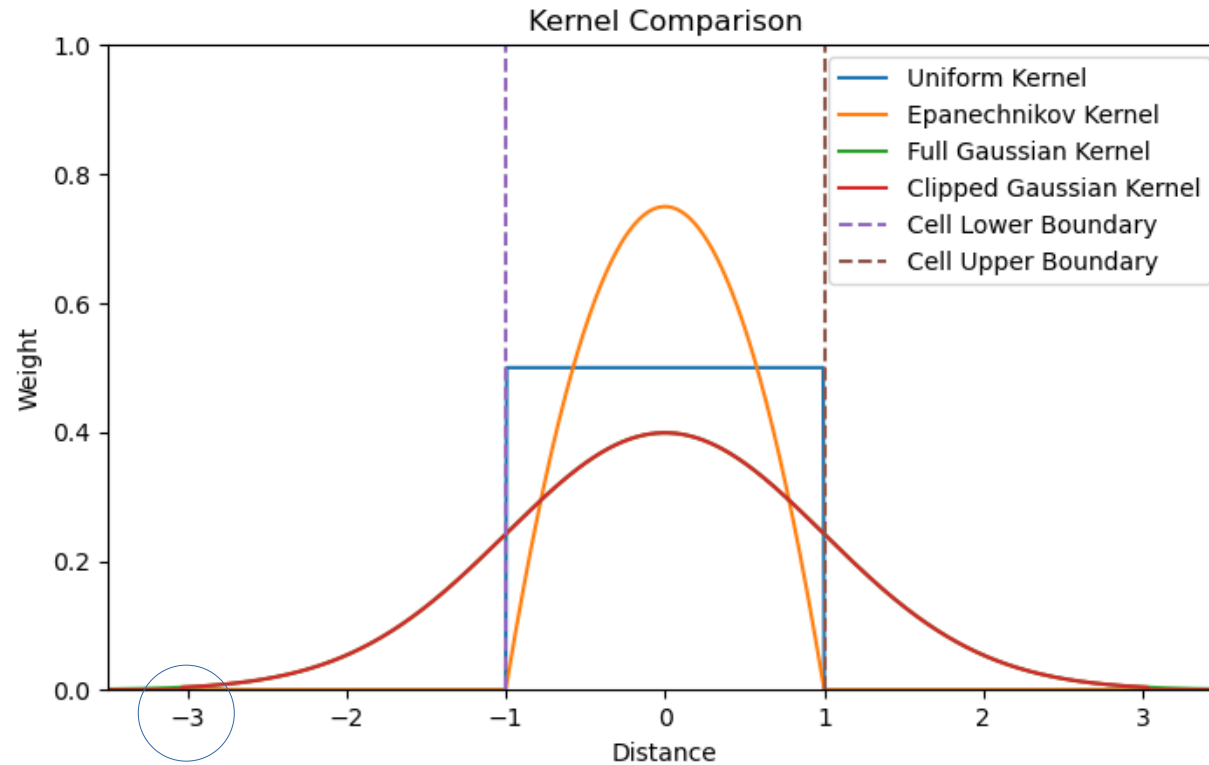


$$f_{exact}(x, y) = \frac{\pi^2}{4} \sin(\pi x) \sin(\pi y)$$

# NUMBER OF CELLS VS NUMBER OF PARCELS REQUIRED

Nx	-1 <sup>st</sup> order	0 <sup>th</sup> order	1 <sup>st</sup> order	2 <sup>nd</sup> order
2	32	32	32	32
4	32	128	512	2,048
8	32	512	8,192	131,072
16	32	2,048	131,072	8,388,608
32	32	8,192	2,097,152	536,870,912
64	32	32,768	33,554,432	34,359,738,368

# COMPARISON BETWEEN DIFFERENT KERNELS



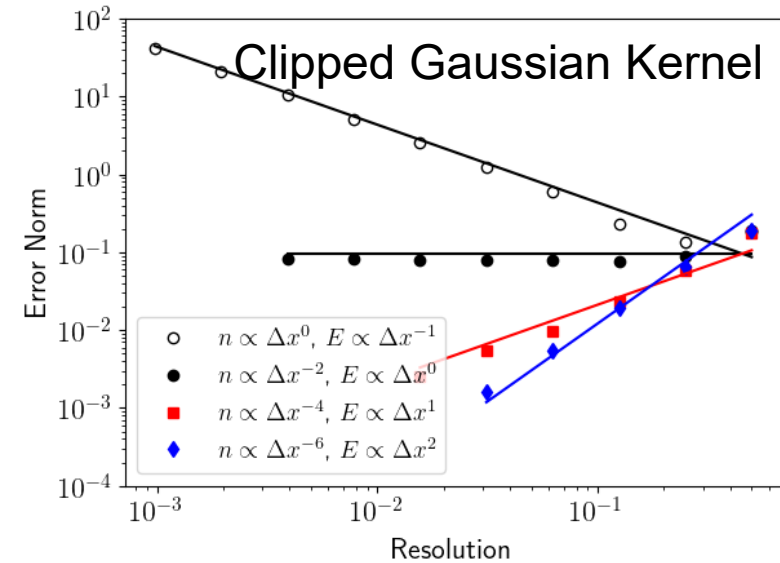
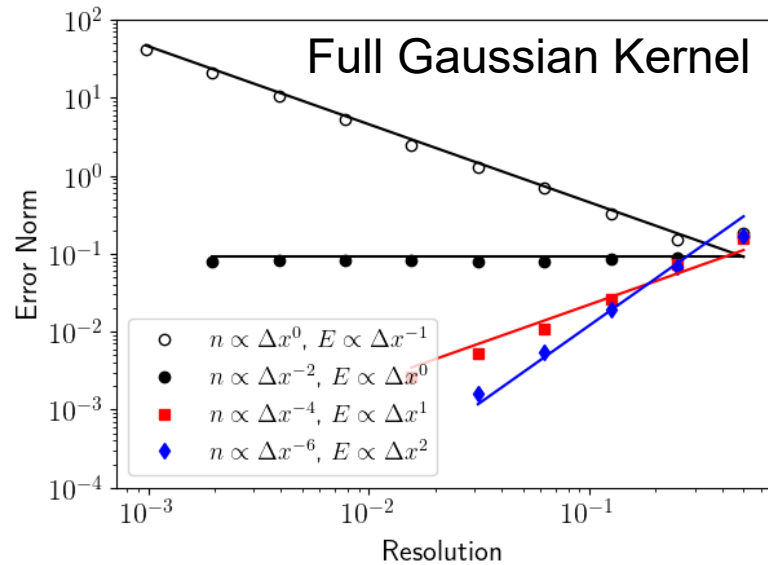
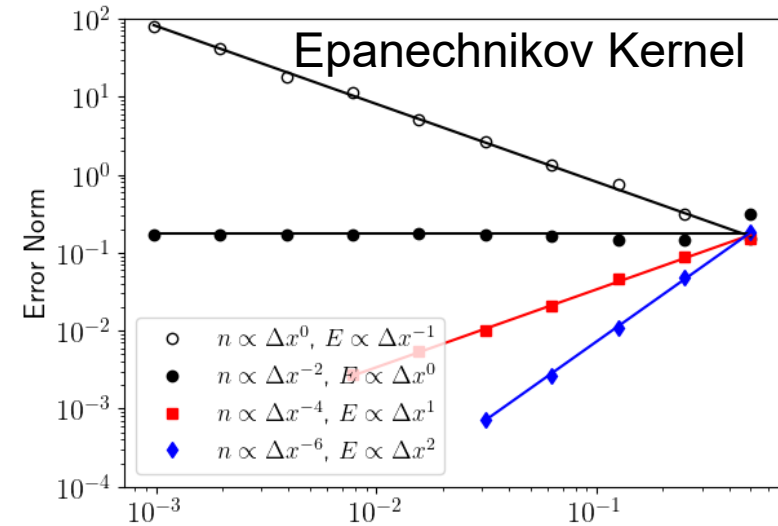
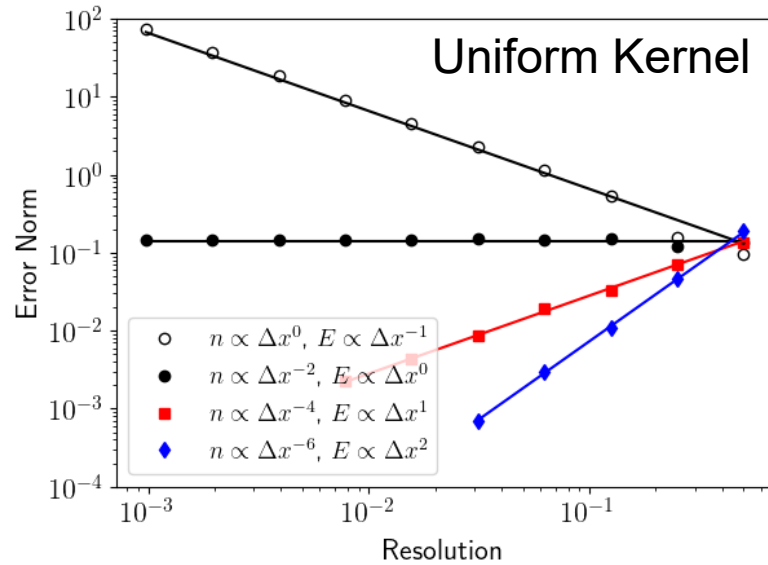
# KERNEL PARAMETERS

$$ASME = M^2 \left\{ \frac{f(\vec{x})R(K(w))^d}{n} \prod_{j=1}^d \frac{1}{h_j} + \frac{1}{4} \sigma_K^4 \left[ \sum_{j=1}^d h_j^2 \frac{\partial^2 f}{\partial x^2} \right]^2 \right\}$$

Kernel	Variance	Roughness	Support	Integral
Boxcar	0.3333	0.5	[-1,1]	1
Epanechnikov	0.2	0.6	[-1,1]	1
Gaussian	1	0.2821	$[-\infty, \infty]$	1
Gaussian Clipped	0.9734	0.2821	$[-3.03, 3.03]^*$	0.9976



# GLOBAL ERROR COMPARISON



# ASYMPTOTIC MEAN SQUARE ERROR

$$ASME = M^2 \left\{ \underbrace{\frac{f(\vec{x})R(K(w))^d}{n} \prod_{j=1}^d \frac{1}{h_j}}_{\text{Statistical Error}} + \frac{1}{4} \sigma_K^4 \underbrace{\left[ \sum_{j=1}^d h_j^2 \frac{\partial^2 f}{\partial x_j^2} \right]^2}_{\text{Spatial Error}} \right\}$$

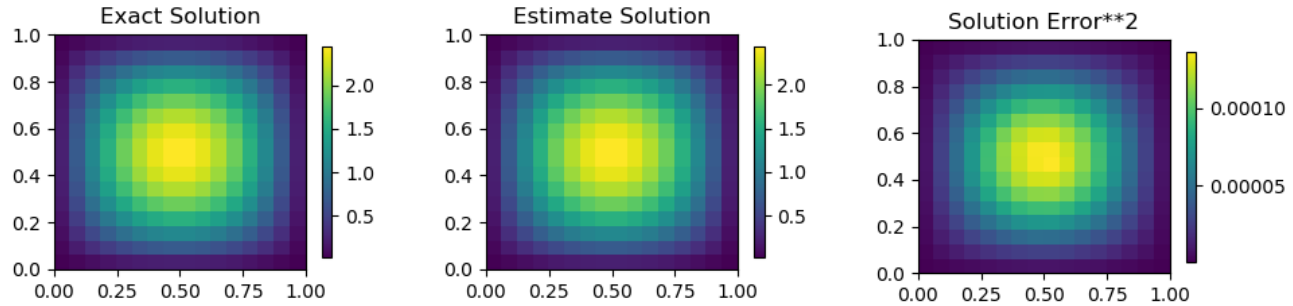
- Statistical Error
- “Noise”
- Spatial Error
- “Bias”

# KERNEL ERROR COMPARISONS, $NX=32$ , $NP=536,870,912$

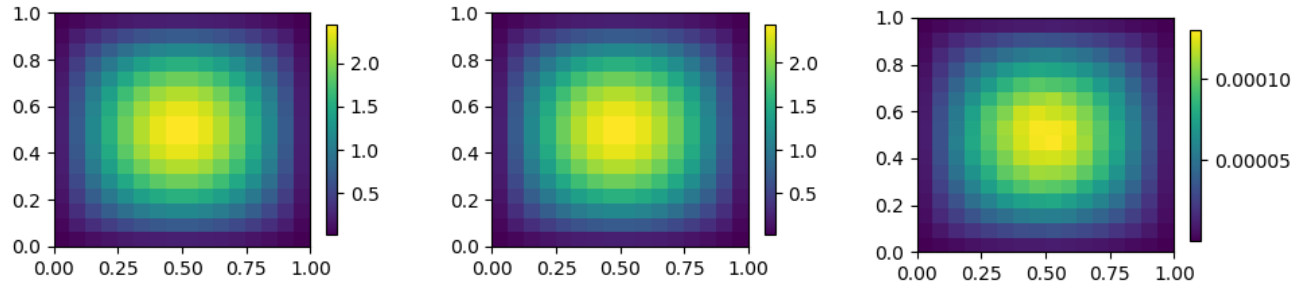
Kernel	• Expected L2	Empirical L2
Boxcar	• 0.000769	0.000693
Epanechnikov	• 0.000649	0.000719
Gaussian	• 0.001909	0.001589
Gaussian Compact	• 0.001859	0.001583

# LOCAL ERROR COMPARISON

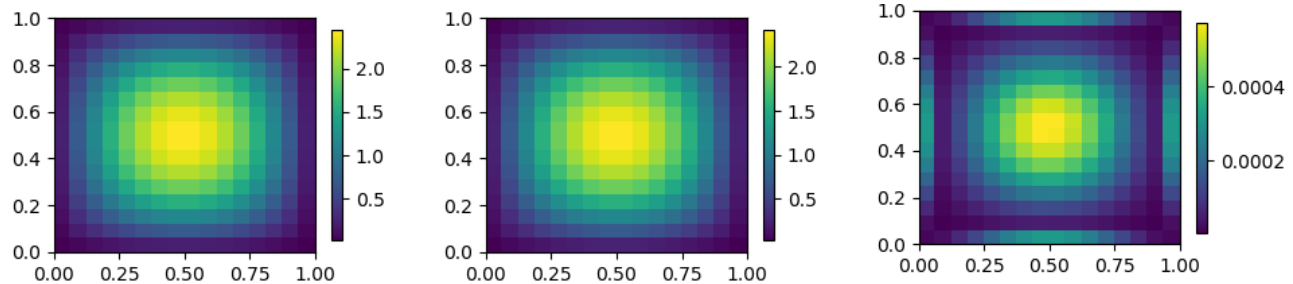
Uniform Kernel



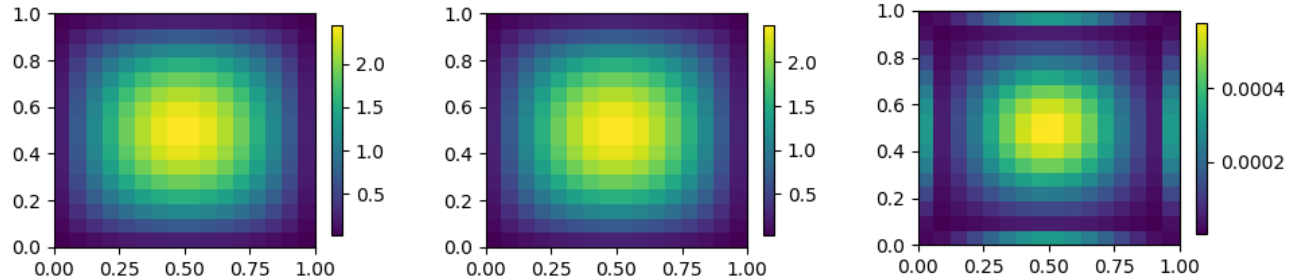
Epanechnikov Kernel



Full Gaussian Kernel

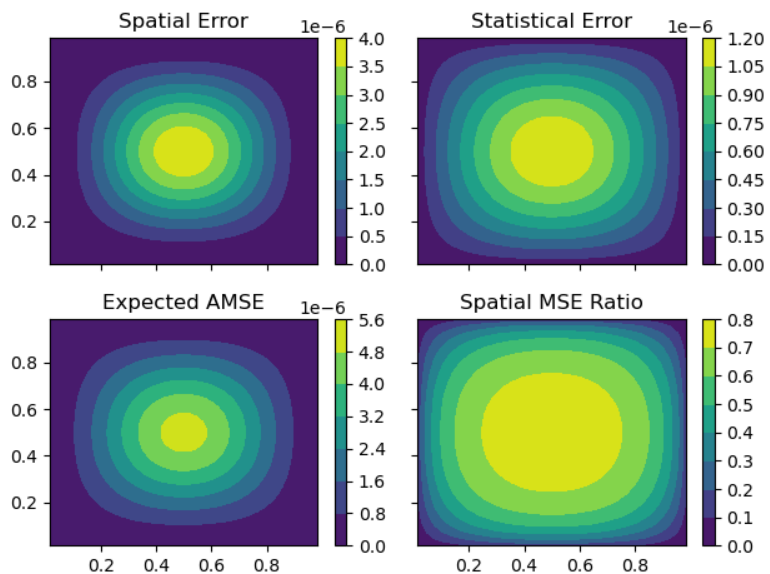


Clipped Gaussian Kernel

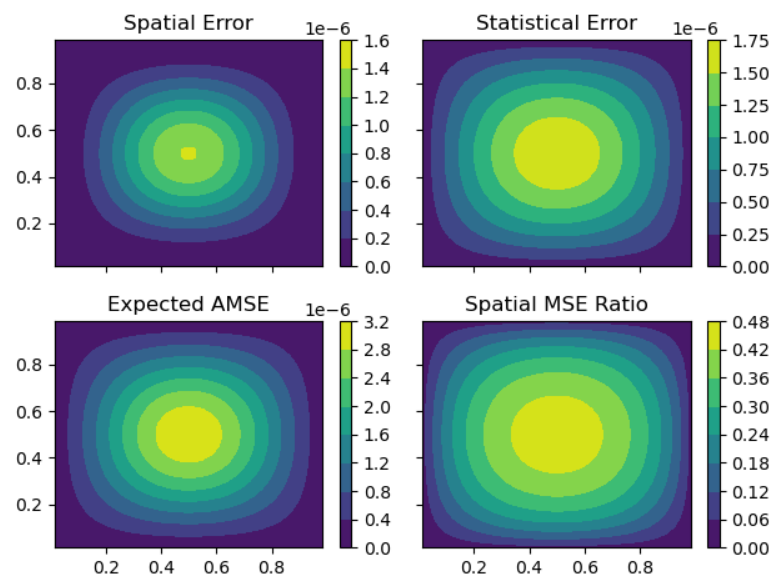


# SPATIAL AND STATISTICAL ERROR

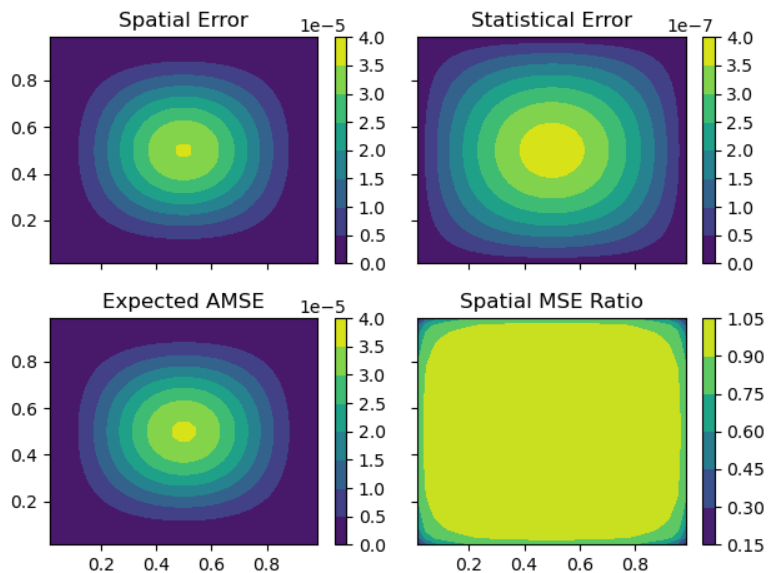
Uniform Kernel



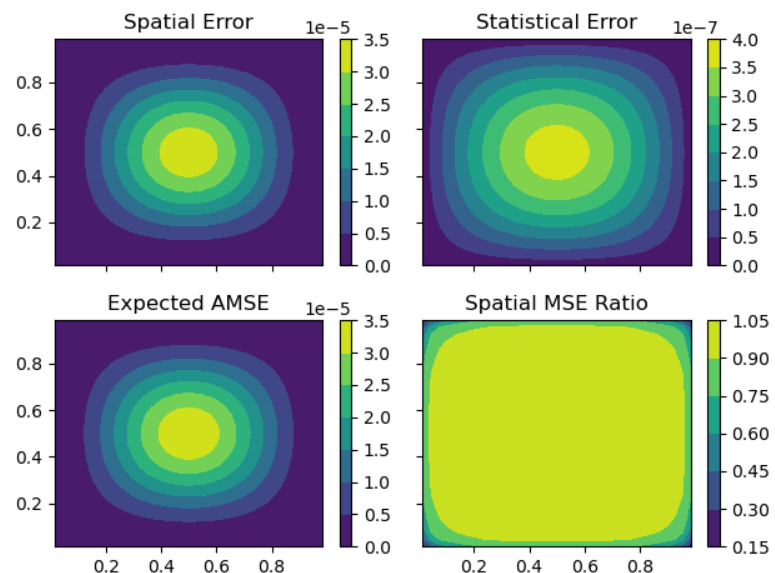
Epanechnikov Kernel



Full Gaussian Kernel



Clipped Gaussian Kernel



# COMPARISON OF SPATIAL AND STATISTICAL ERROR

Kernel	Expected Spatial Error	Expected Statistical Error
Uniform	0.001005	0.000489
Epanechnikov	0.000362	0.000704
Gaussian	0.009049	0.000156
Compact Gaussian	0.008574	0.000156

# FUTURE DIRECTIONS

- Transient Flow
- 3D simulations
- Higher order kernels

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## WORKS CITED

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# QUESTIONS?