



ACCES:

Autonomous Characterisation and Calibration via Evolutionary Simulation

Jack Sykes

PhD w/ Integrated Study
Topological Design CDT
School of Physics and Astronomy
University of Birmingham



EPSRC CENTRE FOR DOCTORAL TRAINING
**TOPOLOGICAL
DESIGN**



POSITRON
IMAGING CENTRE



Interactive
Example

Collaborators: **Leonard Nicusan & Dominik Werner**

PI: **Dr. Kit Windows-Yule**

Co-supervisor: **Dr. Tzany Kokalova Wheldon**

EPSRC MAPP-funded Project



BlueBEAR HPC Service
Positron Imaging Centre
University of Birmingham

Why Simulate and Calibrate?

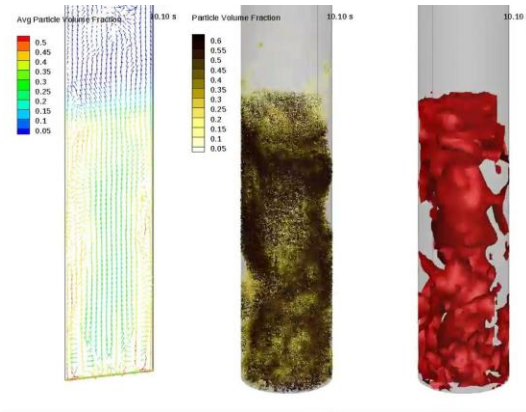


Compared to noisy experiments, simulations offer:

- Faster results
- Cheaper modifications
- More information
- Higher accuracy

If, and only if, they are **correctly calibrated** - otherwise the outputs cannot be trusted

- Leading project with IFPRI investigating current industrial **simulation calibration strategies**. Key findings:
 - **No two companies** use the same procedure
 - **>20** instruments used... each with a 5-figure price tag



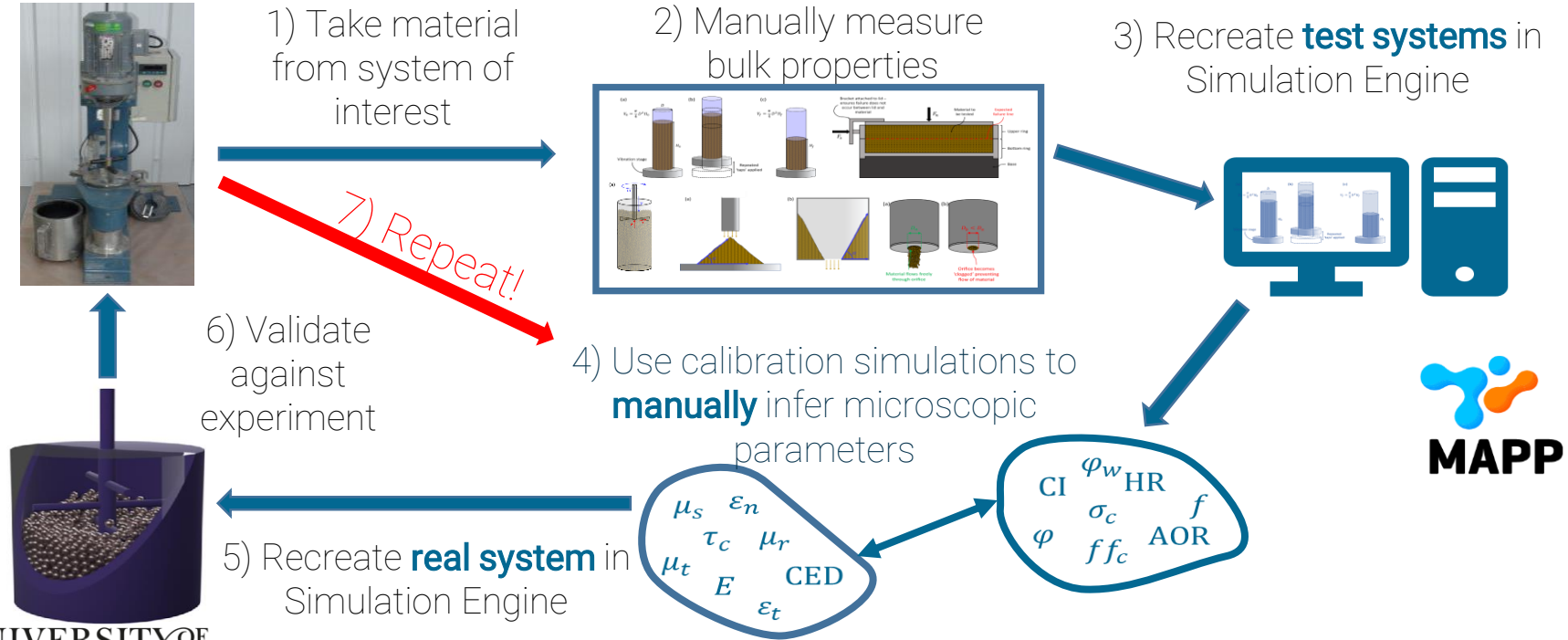
UNIVERSITY OF
BIRMINGHAM

HENRY
ROYCE
INSTITUTE



IFPRI
International Fine Particle Research Institute

Conventional Calibration



ACCES Calibration



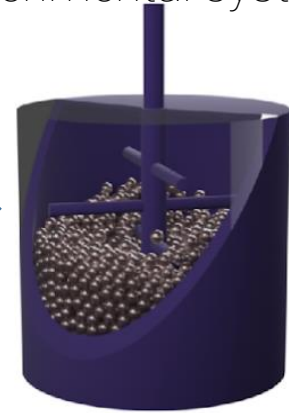
1) Run suitable set of test experiments



2) ACCES uses experimental data & a basic, uncalibrated simulation to autonomously **"learn"** the relevant parameters



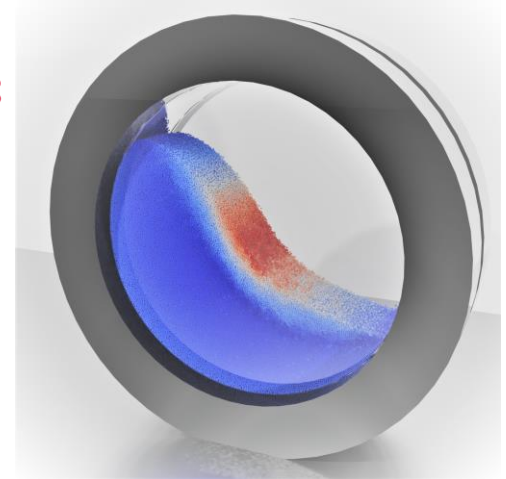
3) Comprehensively validated simulation of experimental system



UNIVERSITY OF
BIRMINGHAM

DEM Calibration as an Optimisation Problem

- I. Choose experimental system to model
- II. Define a **cost function** to quantify difference between experiment and simulation
- III. Choose a suitable optimiser
- IV. Set goal to minimise error function (i.e. maximum agreement between simulation and experiment)
- V. Iterate towards minimum (i.e. find optimal DEM parameters)

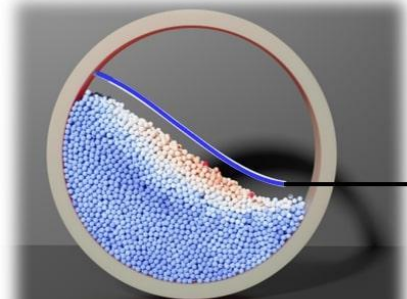


Characterising DEM Particles

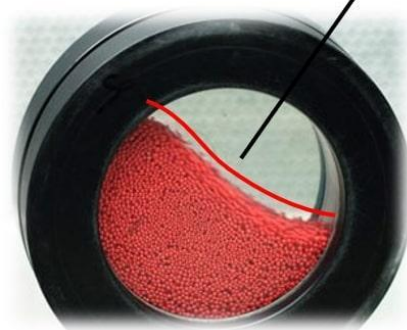


Example:

Characterisation of DEM particle friction, restitution and particle number against a GranuTools GranuDrum-imaged free surface shape.



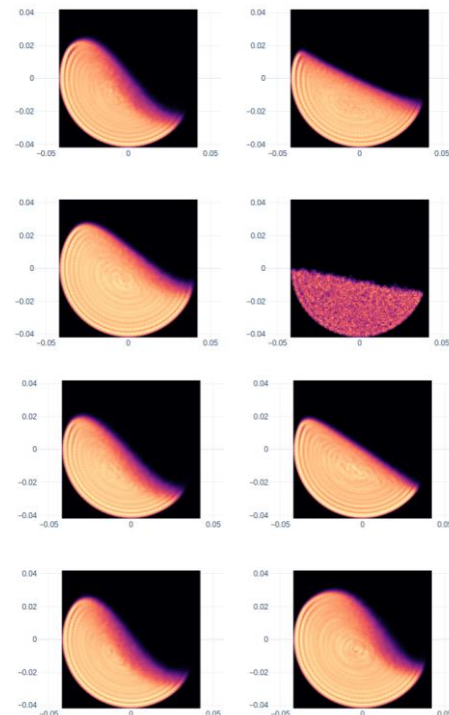
$$f(x) = 0.005x^3 + 0.002x^2 - 0.023x + 0.041$$



$$\epsilon = \int |f(x) - g(x)| dx$$

The model was effectively calibrated against a single experimental data point, but was able to **reproduce other uncalibrated properties** such as velocity vector fields.

Single Epoch



How do we optimise this?



Every function evaluation is an entire simulation run

~~Gradient-based optimisers~~

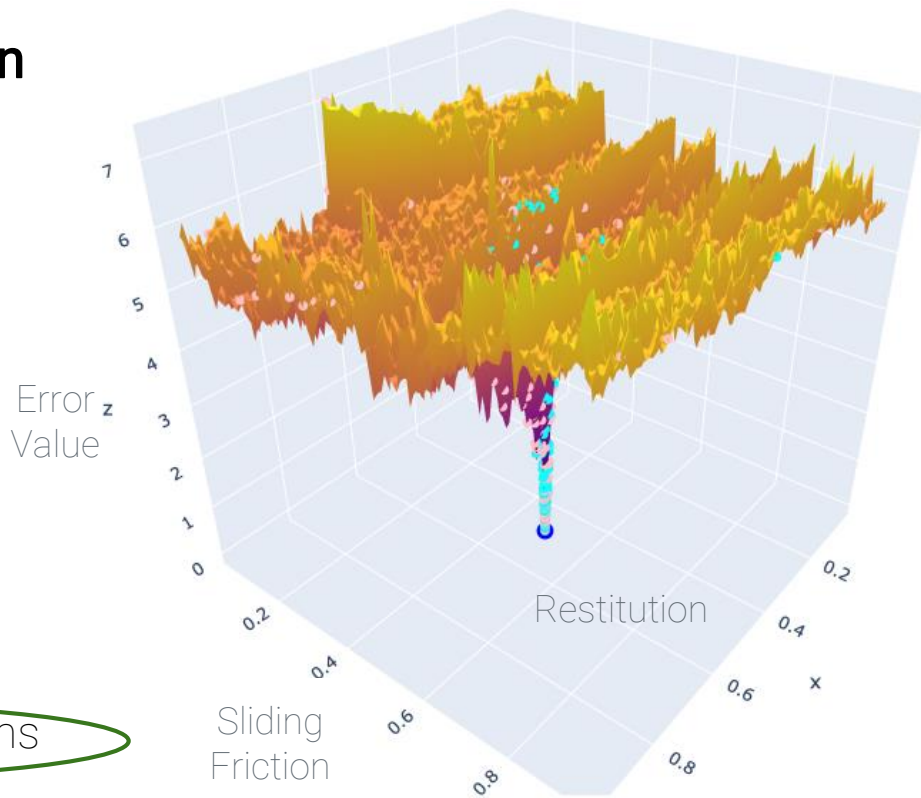
~~• 10s - 100s evaluations~~

~~Neural networks~~

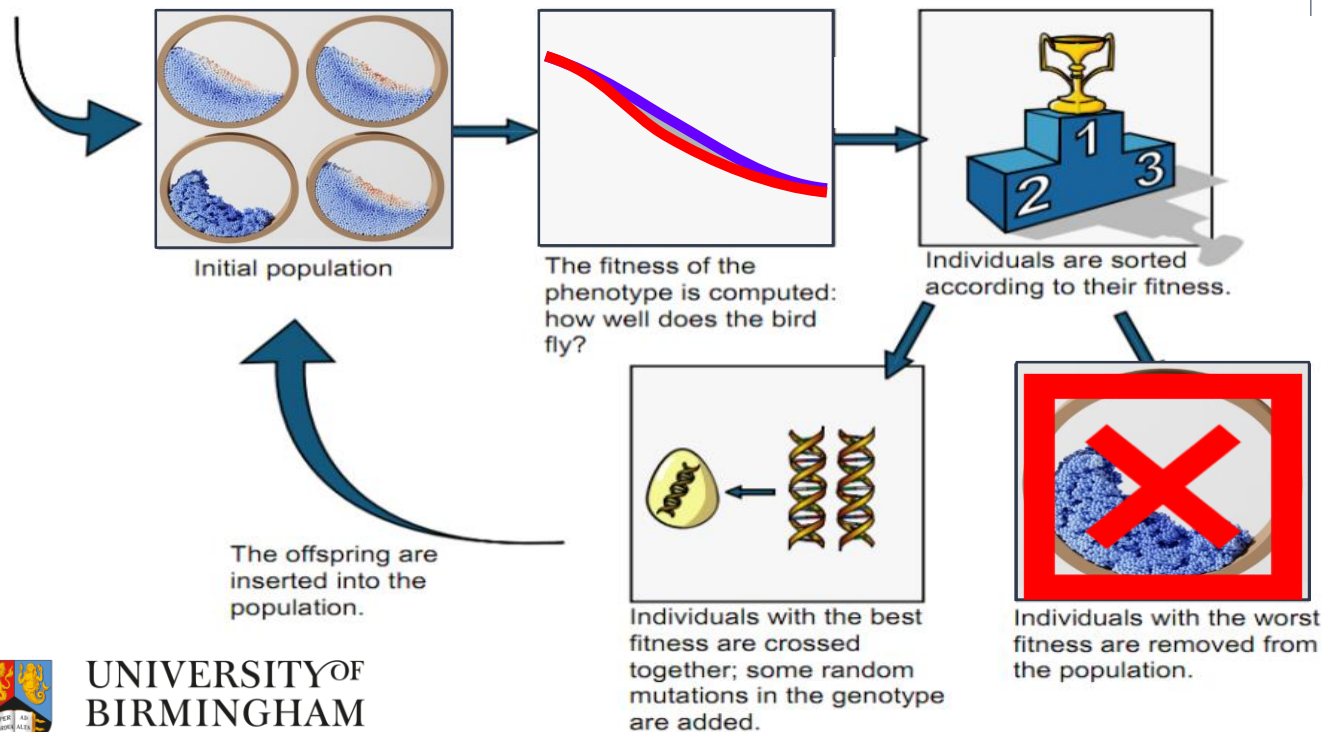
~~• 10,000+ evaluations~~

Evolutionary algorithms

- Used to be 1,000+ evaluations
- State of the art 100s evaluations



Evolutionary Optimisers



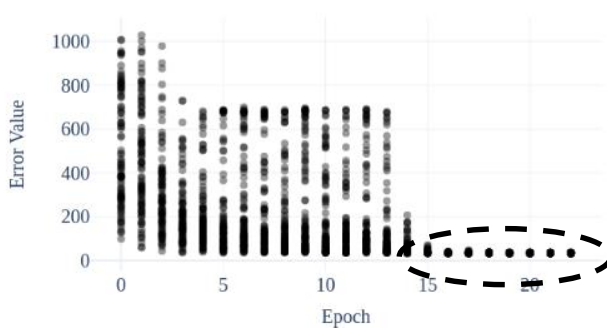
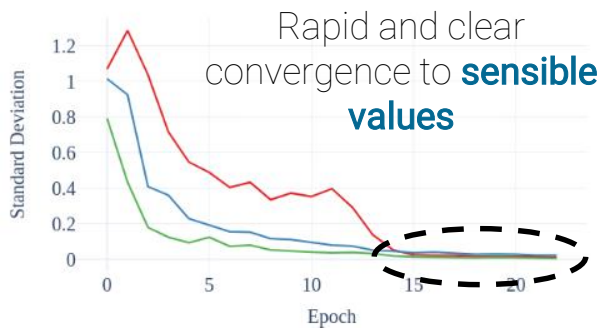
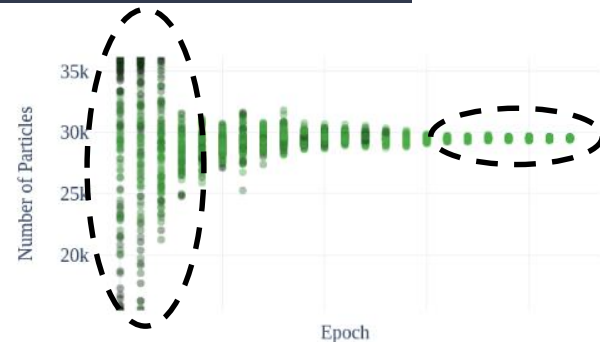
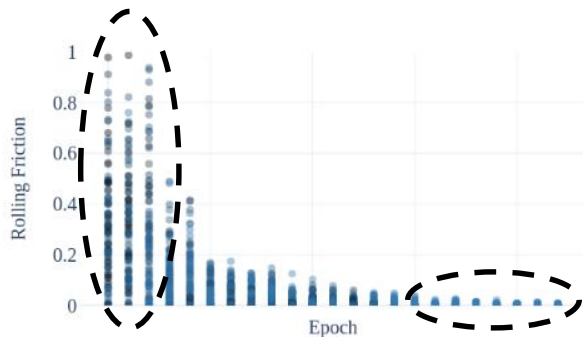
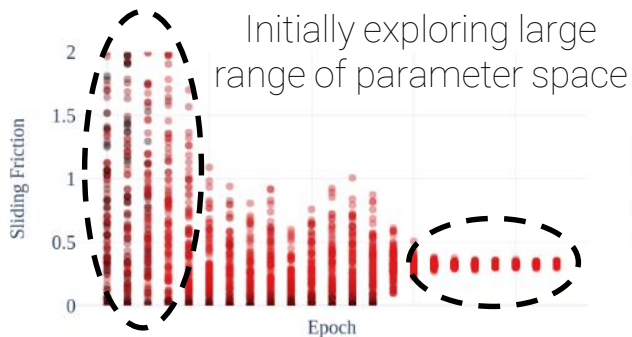
The problem with evolutionary algorithms: **lots of function evaluations**

Especially problematic when coupled to DEM

Utilise state-of-art **CMA-ES** algorithm, which adaptively changes as the cost function deforms



Finding Optimum Parameters



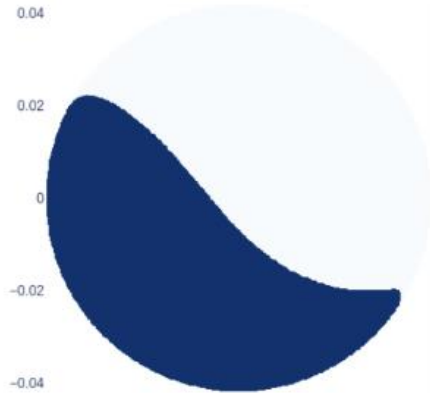
ACCES converges on the parameter values that minimise the error values. It evolves a family of solutions in epochs (x-axis) towards the fittest individuals.

Example ACCES Calibration

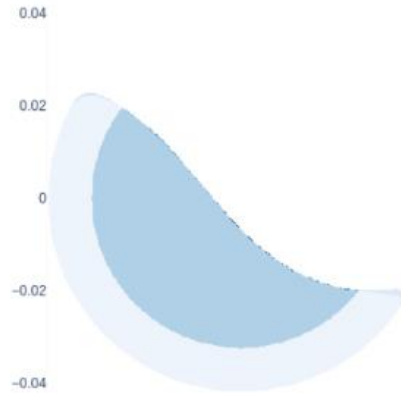


Example States

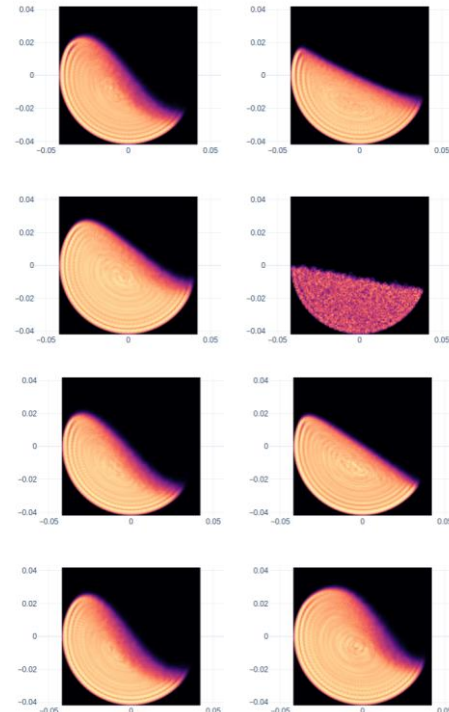
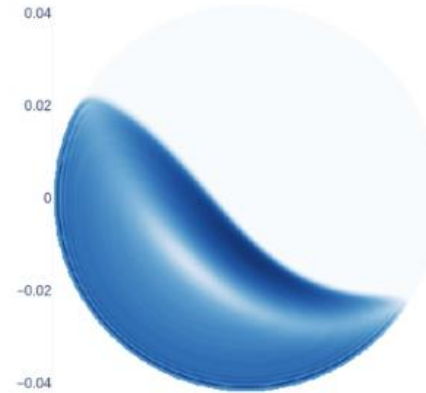
Experiment



Superimposed



Simulation

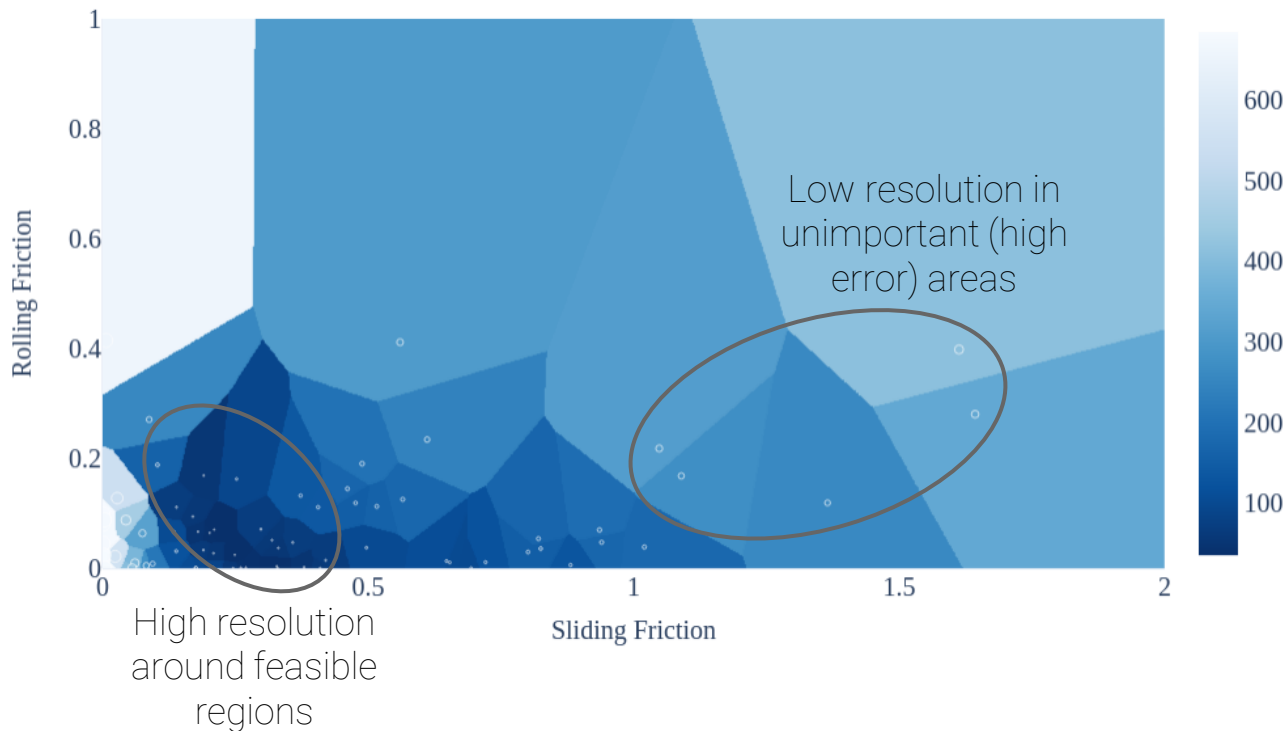


Efficient Parameter Space Exploration



ACCES can calibrate
virtually *any* parameters,
in arbitrarily high
dimensions

It is more precise, yet
less computationally
expensive than e.g. grid-
based calibration

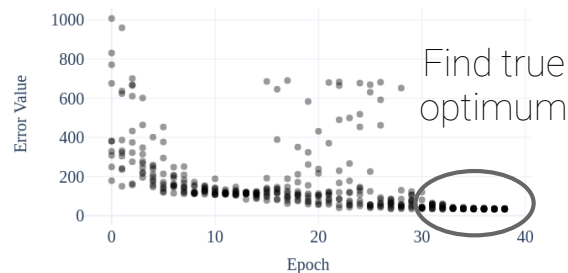
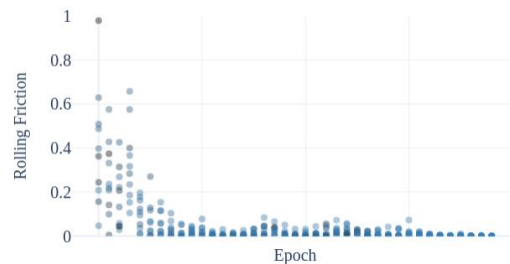
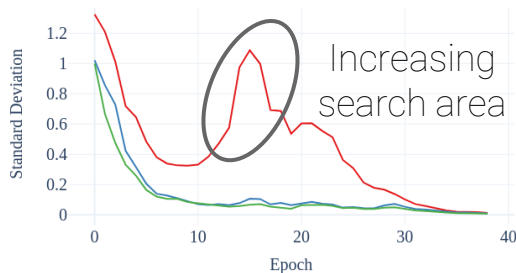


UNIVERSITY OF
BIRMINGHAM

Power of *Scalable* Evolutionary Algorithms



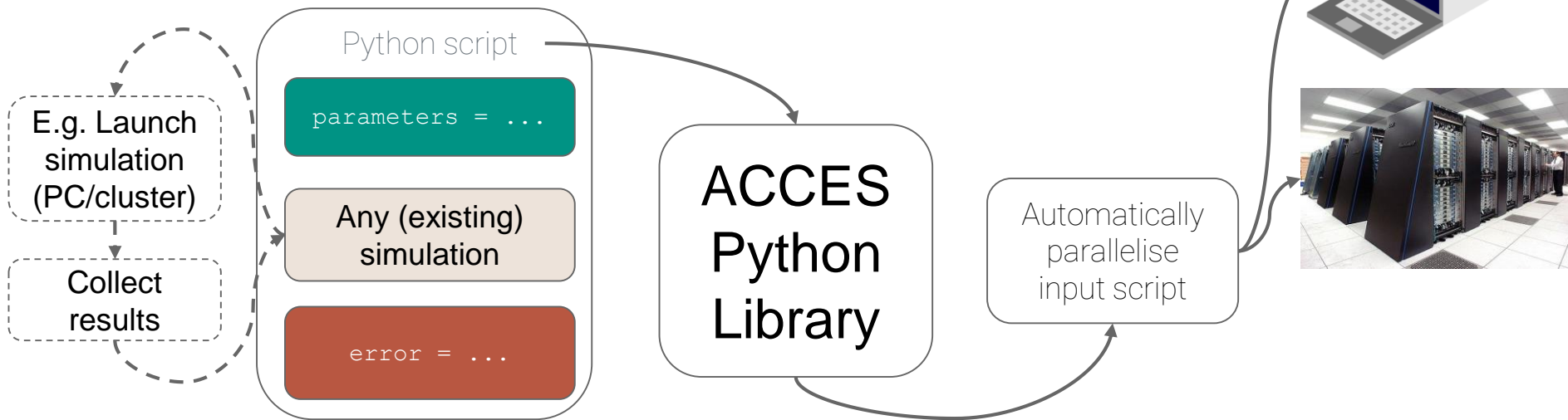
- ACCES robustly handles tough calibration problems
- It can naturally “escape” deep false optimums
- The only free parameter is the family size - the number of simulations run per epoch
- Larger family size - more global search, fewer epochs needed, more parallel computation
- Smaller family size - fewer simulations, more epochs needed



Minimally-Invasive, Scalable Optimisation



- As opposed to classic optimisation frameworks which need the simulation to be rewritten inside a function, ACCES **accepts entire simulation scripts**
- Straightforward calibration of already-developed simulations!



Thank you!



The ACCES framework would not have been possible without the continuous support and help from a great Birmingham team:

- **Dr. Kit Windows-Yule**, supervisor
- **Andrei Leonard Nicusan**, collaborator & lead ACCES developer
- **Dominik Werner**, collaborator & DEM hero

Interested? Email me at:

→ jas653@student.bham.ac.uk



Dr. Kit
Windows-Yule



Andrei Leonard
Nicusan



Dominik Werner



UNIVERSITY OF
BIRMINGHAM



POSITRON
IMAGING CENTRE

IFPRI



HENRY
ROYCE
INSTITUTE



Engineering and
Physical Sciences
Research Council