

Graph neural networks for particle drag force predictions in dynamic flows

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NETL WORKSHOP 2024



Contents





Introduction



Flow through porous fibers^[1]



Snapshots of rod like particles in a fluidized bed, adapted from CFD-DEM simulation of fluidization of rod-like particles in a fluidized bed [2] solid^[3]

Flow through a random array of

ellipsoidal particle^[4]

Flow through porous

- Flow across random arrangement of solid particles can be found in various applications.
- Studying them experimentally is challenging due to requirements of expensive experimental setups.
- Studying them numerically runs into the dilemma of accuracy vs computation expense.

Aim

- Develop Deep Learning (DL) based models for accurate drag predictions, to deploy in less computationally expensive methods (such as CFD-DEM) for PRS/DNS level accuracy.
- First attempt with DL for developing dynamic drag models.
- Investigate the generalizability of said models across different parameters of the dataset.



- State-of-the-art correlations/DL models are developed based on only fixed particle simulations.
- However, drag forces obtained from correlations developed from simulations of fixed particles show different statistics compared to drag forces obtained from dynamic particle simulations, as seen in the plots.
- The discrepancy between dynamic and stationary drag increases linearly with Reynolds number based on granular temperature.

• Particle mobility effects are crucial for dynamic drag force predictions.

Y. Tang, E.A.J.F. Peters, J.A.M. Kuipers, Direct numerical simulations of dynamic gas-solid suspensions, AIChE J. 62 (2016) 1958–1969. https://doi.org/10.1002/AIC.15197.

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TD0

Slide 4

TD0 at what density ratio is this study done? BTW FYI these predictions of unsteady drag forces are high but for here it is OK to show.

Tafti, Danesh, 2024-08-12T12:47:18.553

RA0 0 the density ratio is 500 Raj, Neil Ashwin, 2024-08-12T13:03:25.860



Computational domain along with particles for $\varphi = 0.1$ and $\varphi = 0.4$



Simulation setup and collision models

- The computational domain is cubic with each side being 5d_p, where d_p is the particle diameter. The flow is driven by a pressure gradient in the positive x-direction, and additionally, there is a gravitational force in the negative x-direction.
- The Immersed Boundary Method (IBM) is used to model the solid spheres, and all the simulations have been performed in the inhouse code GenIDLEST.
- The particle collisional forces are modeled using the soft sphere model, if two particles come closer than a critical distance of separation the particle forces are calculated and applied in the opposite directions for each of them.

Z. Cao, D.K. Tafti, Alternate method for resolving particle collisions in PRS of freely evolving particle suspensions using IBM, Int. J. Multiph. Flow 177 (2024) 104862. https://doi.org/10.1016/j.ijmultiphaseflow.2024.104862.

Slide 5

- **TD0**insert reference:
Cao Z, Tafti DK. "Alternate method for resolving particle collisions in PRS of freely evolving particle suspensions
using IBM". International Journal of Multiphase Flow. 2024 May 10:104862.
https://doi.org/10.1016/j.ijmultiphaseflow.2024.104862
Tafti, Danesh, 2024-08-12T12:58:46.906
- n0 0 added

neilashwinraj, 2024-08-12T14:51:14.244



Dataset Description



Summary of different experiments

Kernel density estimates of the PRS drag forces for different Reynolds number for the different solid fractions (a) φ =0.1(b) φ =0.2 (c) φ =0.3 (d) φ =0.4

- The simulations used in this study consider particles of density ratio=2, and there are a total of 20 different experiments that form the dataset.
- An experiment is characterized by its solid fraction and Reynolds number, there 4 different solid fractions in this study, and for each of the 4 solid fractions there are 5 different mean Reynolds numbers.
- Drag force statistics show that along with an increase in the drag force with an increase in Reynolds number, there is also an increase in standard deviation. The same can be said about solid fractions.

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TD0 Frequency ? Tafti, Danesh, 2024-08-12T12:59:35.642



TD0 will have to explain to me - does not mean anything to me. Tafti, Danesh, 2024-08-12T13:05:58.796 VIRGINIA TECH.

— Methods: Stationary

Stationary model : Data splitting and Training





 $F_{D,pred} = f_{\theta}(Re_{local}, \vec{r}_{i,t=1})$

 $F_{D,pred} = f_{\theta}(Re_{local}, \vec{r}_{i,t=2})$

• Here f_{θ} is the trainable GCN model, Re and φ are the global parameters $\vec{r}_{i,t=1}$ and $\vec{r}_{i,t=2}$ are the position vectors of the *n*(here *n*=15) nearest neighbors at *t* = 1 and *t* = 2 respectively.



- A single particle and its 15 nearest neighbors at a given time frame forms a single datapoint.
- For a particular experiment 80% of the time frames form the training dataset and remaining 20% form the testing dataset.

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TD0	i though RE was local							
	Tafti, Danesh, 2024-08-12T13:09:03.256							

n0 0 corrected

neilashwinraj, 2024-08-12T14:30:37.782



\pmb{arphi} /Reynolds number	10	50	100	200	300	
φ =0.10	0.965	0.816	0.684	0.614	0.514	
φ =0.20	0.810	0.571	0.532	0.417	0.484	
φ =0.30	0.645	0.398	0.384	0.391	0.433	
φ =0.40	0.632	0.274	0.249	0.203	0.245	

- The performance deteriorates with an increase in Reynolds number and solid fraction.
- For all the experiments the GCN model performs better than the mean PRS drag force, and accuracy difference between the GCN and the mean drag reduces with an increase in Reynolds number and solid fraction.

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Stationary model : Predictions





Dynamic model: Graph Attention

Graph convolution layer

$$\boldsymbol{x}_{i}^{(l)} = \sum_{j \in N(i) \cup \{i\}} \frac{1}{\sqrt{\deg(i)} \cdot \sqrt{\deg(j)}} \cdot \left(\boldsymbol{W}^{T} \cdot \boldsymbol{x}_{j}^{k-1}\right) + \boldsymbol{b}$$



 $\alpha_{i,j} = \frac{exp(\text{LeakyReLU}(\boldsymbol{a}^T[\boldsymbol{W}\boldsymbol{x}_i||\boldsymbol{W}\boldsymbol{x}_j]))}{\sum_{k \in N(i)} exp(\text{LeakyReLU}(\boldsymbol{a}^T[\boldsymbol{W}\boldsymbol{x}_i||\boldsymbol{W}\boldsymbol{x}_k]))}$



P. Veličković, A. Casanova, P. Liò, G. Cucurull, A. Romero, Y. Bengio, Graph attention networks, in: 6th Int. Conf. Learn. Represent. ICLR 2018 - Conf. Track Proc., International Conference on Learning Representations, ICLR, 2018. https://doi.org/10.1007/978-3-031-01587-8_7.

- The concept of the "attention mechanism" in deep learning refers to weighing the different embeddings or latent space representations within a deep learning architecture.
- For the problem of drag predictions using the nearest neighbors, this would mean that the GNN can now in the course of training can assign higher importance to the nearby nodes as they will influence the drag forces more than the far away nodes, something which is not explicitly performed by a conventional GCN layer.



Methods: Dynamic

Dynamic model: Combining Graph Attention with Transformers



TD0 explain what transformer is in simple language when presenting Tafti, Danesh, 2024-08-12T13:20:13.733



Dynamic model: Predictions

	Stationary				Dynamic					
<i>φ</i> /Reynolds number	10	50	100	200	300	10	50	100	200	300
φ =0.10	0.965	0.816	0.684	0.614	0.514	0.931	0.82	0.705	0.680	0.675
<i>φ</i> =0.20	0.810	0.5706	0.532	0.417	0.484	0.857	0.579	0.659	0.561	0.604
φ =0.30	0.645	0.398	0.384	0.391	0.433	0.764	0.573	0.553	0.514	0.493
φ =0.40	0.632	0.274	0.249	0.203	0.245	0.697	0.475	0.477	0.486	0.415

- The dynamic model outperforms the stationary model across all the experiments.
- The model sees the same trend pf performance deterioration with increasing Reynolds numbers and solid fraction.
- The improvement in performance is more prominent at higher Reynolds numbers and solid fractions, essentially meaning that a lower Reynolds and solid fraction the flow field the difference between the dynamic and static flow fields is not significantly different.







— Methods: Dynamic

Dynamic model: Predictions on Single Particles



Conclusions and Further Work

- Graph neural networks-based models were assessed in their ability to model drag forces in dense suspensions
 of spherical particles across different solid fractions and Reynolds numbers.
- The dynamic model outperformed the stationary model across all dataset, thus including trajectory history is crucial in developing accurate drag models.
- The sequence-to-sequence based training outperforms the many to one mapping model.

Future Work:

- Introducing hierarchical learning framework by using hypergraph convolutions
- Incorporating physical constraints on the training datasets, such as rotational equivariance and invariance.

- 1. Shirzadi, M., Fukasawa, T., Fukui, K. and Ishigami, T., 2023. Application of deep learning neural networks for the analysis of fluid-particle dynamics in fibrous filters. *Chemical Engineering Journal*, 455, p.140775.
- 2. Ma, H., Xu, L. and Zhao, Y., 2017. CFD-DEM simulation of fluidization of rod-like particles in a fluidized bed. Powder technology, 314, pp.355-366.
- 3. Santos, J.E., Xu, D., Jo, H., Landry, C.J., Prodanović, M. and Pyrcz, M.J., 2020. PoreFlow-Net: A 3D convolutional neural network to predict fluid flow through porous media. Advances in Water Resources, 138, p.103539.
- 4. He, L. and Tafti, D., 2018. Variation of drag, lift and torque in a suspension of ellipsoidal particles. Powder Technology, 335, pp.409-426.

Thank You

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15